



Wearable Robotics/Exoskeleton/Augmentation Definitions and Taxonomy

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Varied Applications

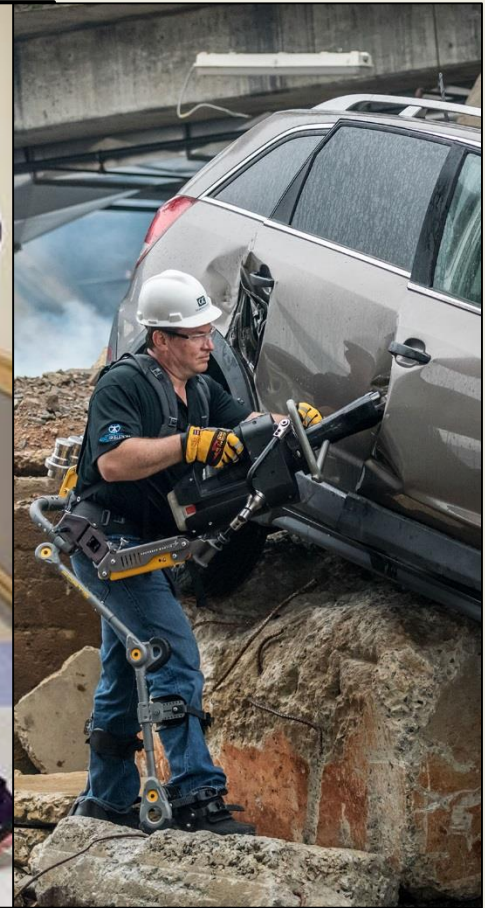


Military

Industry

Medical

First Responders





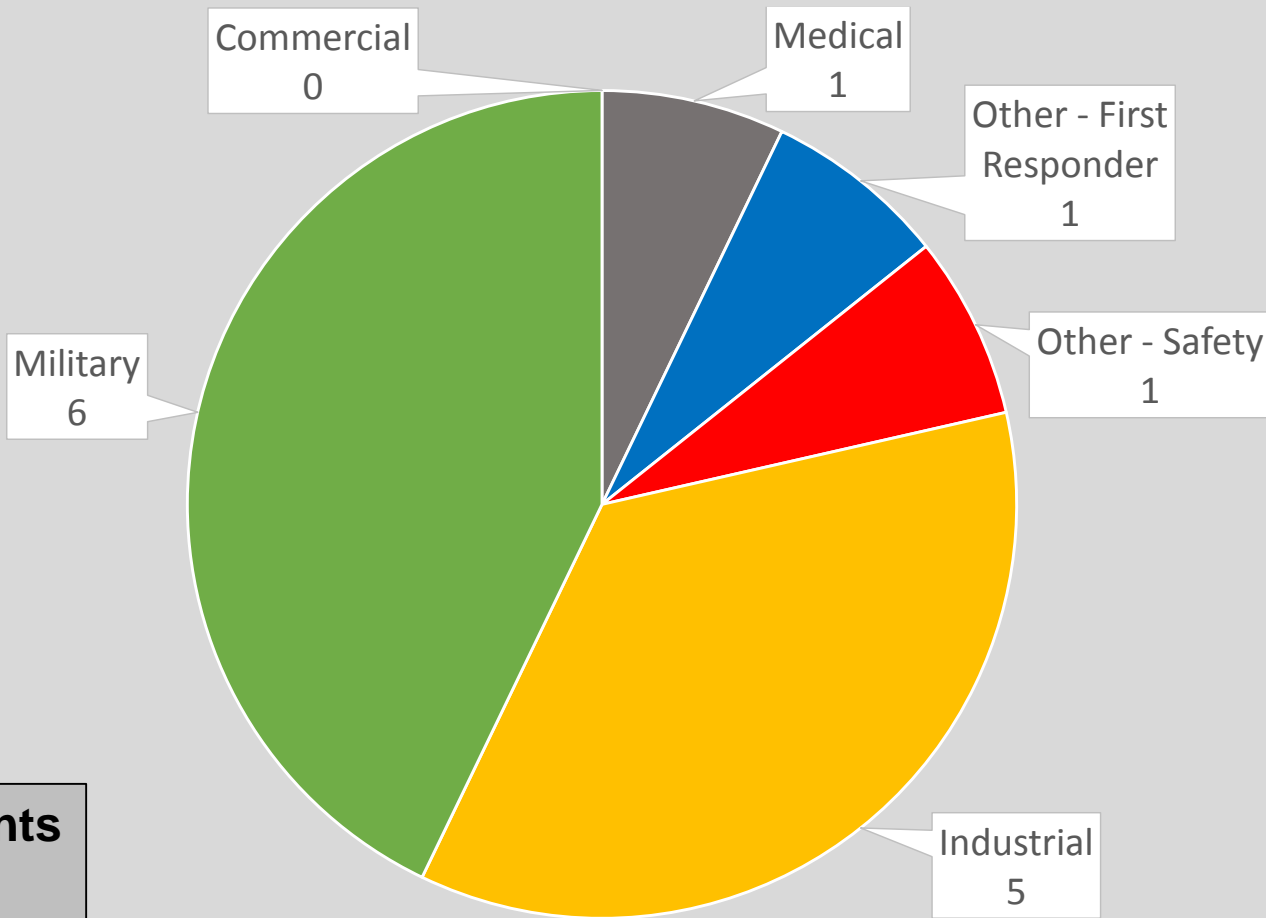
1. I would categorize myself as being interested in Standards and Testing for wearable robotics from the (circle one) medical / military / industrial / commercial point of view.
2. I am primarily involved in the (circle one) development / assessment / consumer aspect of wearable robotics.
3. I would define 'Wearable Robotics' as....
4. I would define 'Augmentation System' as....
5. What is not included in Wearable Robotics?
6. What is not included in an Augmentation System?

Survey completed at 23 August 2016

Human Worn Robotics / Wearable Performance Augmentation Standards and Test Methods Meeting



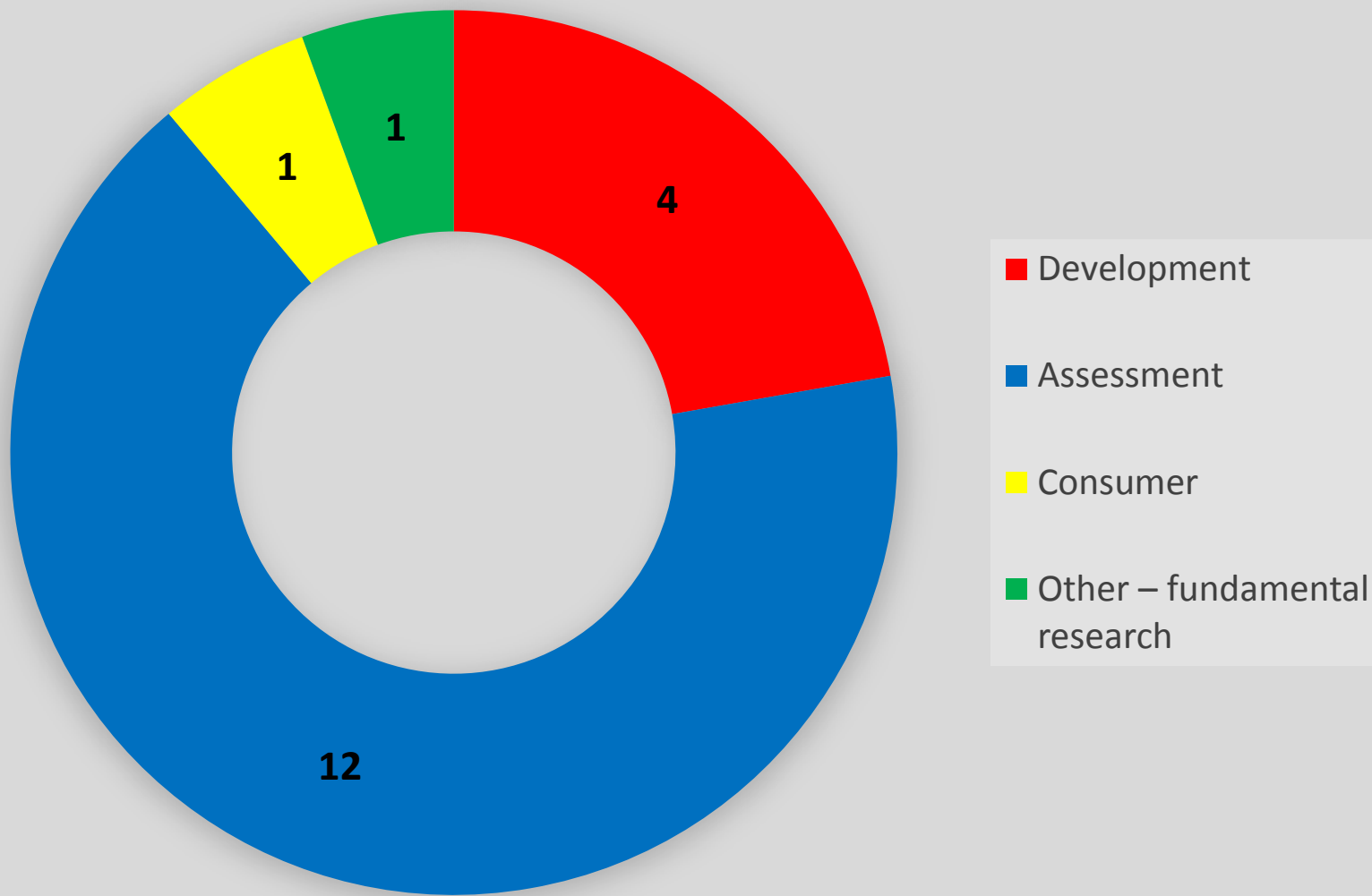
1. I would categorize myself as being interested in Standards and Testing for wearable robotics from the (circle one) medical / military / industrial / commercial / other point of view.



~15 respondents total



2. I am primarily involved in the (circle one) development / assessment / consumer aspect of wearable robotics.





3. I would define 'Wearable Robotics' as....

Example responses:

- “A body worn device that is powered and provides support and power/torque to a body part (arm, leg, lower extremities) to assist movement or aid in the user’s ability to perform a given task.”
- “Any system that augments the human capability.”
- “Any human worn technology that is powered and/or transfers loads/forces to the ground. May be powered with electrical, pneumatic, hydraulic, spring, stored energy source, and with or without feedback control.”
- “Mechanical systems worn on the body for the purpose of improving/maintaining the individual’s ability to perform required task (thought: does ‘robotic’ imply an active system requiring some sort of computation/power?)”
- “Technology worn on the body that restores or enhances the biomechanical aspects of the person.”



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3. I would define 'Wearable Robotics' as....

Frequency of Use

8	7	6	5	4	3	2	
human	powered system worn	perform tasks robot body	wearable user ISO	robotic	capabilities augmentation considered mechanical definition physical provides robotics without ability device person task	situational assistance mechanical physically electrical assistant cognitive awareness required autonomy movement intended consider systems programmable	control provide devices assist robots animal one arm may normal



4. I would define 'Augmentation System' as....

- “Assistance or enhancement in the performance or a given task. Ability to perform a task better, longer, or complete a task you could previously not do but can now do.”
- “Helps the user exceed ‘normal’ capabilities”
- “Taking a current capability and adding technology that gives the individual an increase to that capability”
- “Any system that enhances (augments) human performance (Physical strength, endurance, sensory, cognitive)”
- “Supplementing or improving functionality or capability.”
- “Powered and unpowered devices that can assist in performance of normal activities”
- “The addition of technology or devices to the human body with the goal of biomechanical improvement”
- “Enhancement of someone’s inherent capability or return them to normal performance from a degraded state.”



4. I would define 'Augmentation' as....

Frequency of Use			
5	4	3	2
performance capability task	technology human	normal	supplementing capabilities augmentation enhancement previously devices system making



5. What is not included in Wearable Robotics?

- Completely autonomous systems
- Purely passive devices, no power required and no 'smart' features
- Basically nothing
- Artificial intelligence, learning systems that take feedback
- UAVs, UGVs, robots or robotics independent of the body (non-attached), technology to enhance solely vision and hearing
- Implantables
- Devices only worn on body for transportation and/or do not interact with the host. e.g. man-portable UAVs are NOT "wearable robotics".
- Passive system without programmable, controlled, powered assistance input to the musculoskeletal system, would not be wearable "robotics".
- Anything worn by a person, not powered to enhance performance
- Mech systems that are more akin to a human in a robot vs. a wearable system
- Collaborative robots (e.g., robots working with humans but not fixture to humans)
- Systems that rely primarily on wheels for transport
- Technology that enhances performance but doesn't intimately interact with person



5. What is not included in Wearable Robotics?

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Common Ideas

- Unpowered
- Unattached to a person
- Transportation



6. What is not included in an Augmentation System?

- Pharmaceuticals (augmentation systems are externally applied mechanical/electrical assist devices)
- Anything that does not improve some aspect of a person's, system's, or component's performance
- Something that does not improve capabilities.
- Nothing
- External systems/devices that perform functions not under direct human control
- Soft vs hard robotics technology. Pneumatic system
- Handheld tools
- Pharmaceuticals
- Devices which do not provide additional capability to an existing feature set.
- Def of augmentation system should exclude technologies that are not self-contained with respect to the user. "Wearable" may be synonymous with "self-contained"



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- Pharmaceuticals (augmentation systems are external mechanical/electrical assist devices)
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Common Ideas

- Pharmaceuticals
- Should improve a capability/performance



Based on the survey responses, several more terms emerged that likely need to be defined:

Passive

Medical exoskeleton

Active

Augmentation

Pseudo passive

Performance

Pseudo active

Resiliency

Exoskeleton

Performance

Robot

enhancement

Wearable robot

Collaborative robots

Others?



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Variety of Systems



SARCOS, XOS-2, USA



Human Universal Load Carrier, USA



Google, USA



20 Knots Plus, USA



Powered Exos, China



AirLegs Exoskeleton, USA



Mawashi, Canada



Harvard/Wyss, USA



Revision, Canada



Otherlabs, USA

Slide credit: Angela Boynton, ARL