



University of  
Nottingham

Centre for Aerospace Manufacturing

# Common Shared System Model for Evolvable Assembly Systems

David Sanderson,  
Jack C Chaplin, Svetan Ratchev

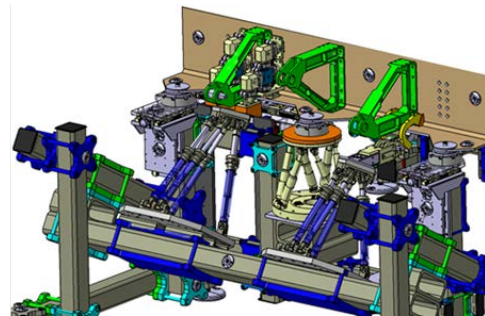
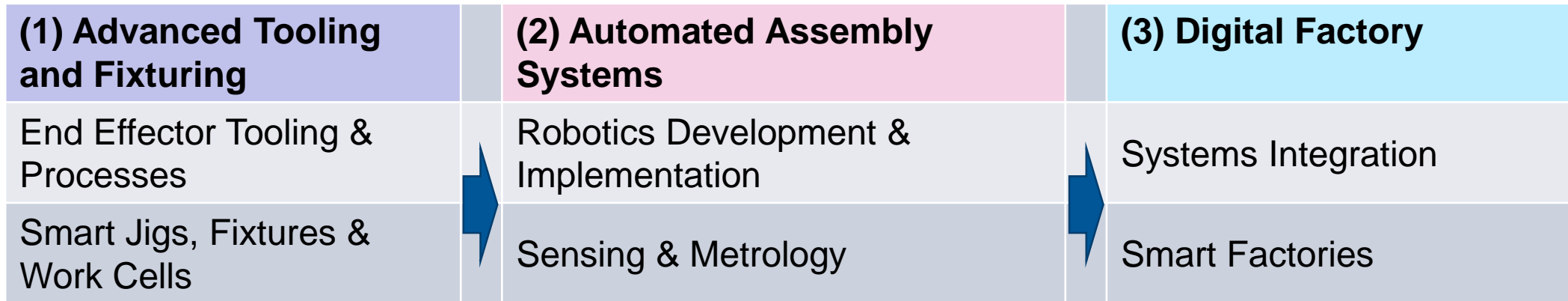


- Advanced Manufacturing Global Priority Research Theme
- Bringing together critical mass from a range of science, business and engineering disciplines
  - 422 members of staff and PGR students
- Current Manufacturing Research Portfolio
  - £49M including £32M EPSRC, £4M InnovateUK, £7M EU, £6M Industry
- Research excellence measured by quality outputs, delivering impact via strategic corporate partnerships
  - Centre for Aerospace Manufacturing established in 2010, now current portfolio in excess of £10M
- Investment in world-class research and teaching infrastructure
  - £7M – research facilities (2006-2014)
  - £24M – new state of the art IfAM building

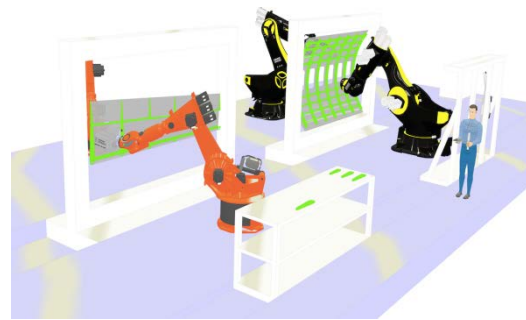




## Research Strategy - Automated Assembly Systems, Tooling and Fixturing



Gripping, Handling & Joining of Components



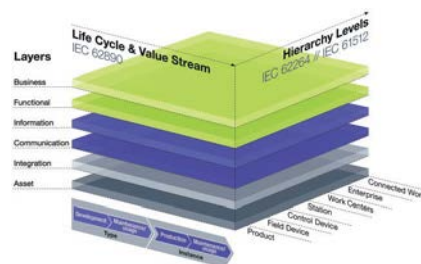
Identification, Location, Handling and Assembly of Component Structures



Final Assembly of Products



- Business drivers:
  - Improve global competitiveness
  - Dramatic reduction in production cost
  - Improve productivity
  - Upskilling of labour
  - Retaining capability to manufacture complete products in the UK
  - Improved quality and in-service support



- Product focus:
  - High value, high complexity products
  - Variable volumes
  - Trend towards product customisation
- Evolution:
  - Product
  - Process
  - System



## **EP/K018205/1 Evolvable Assembly Systems: *Towards Open, Adaptable and Context-Aware Equipment and Systems***

Part of EPSRC Flexible and Reconfigurable Manufacturing Systems Panel

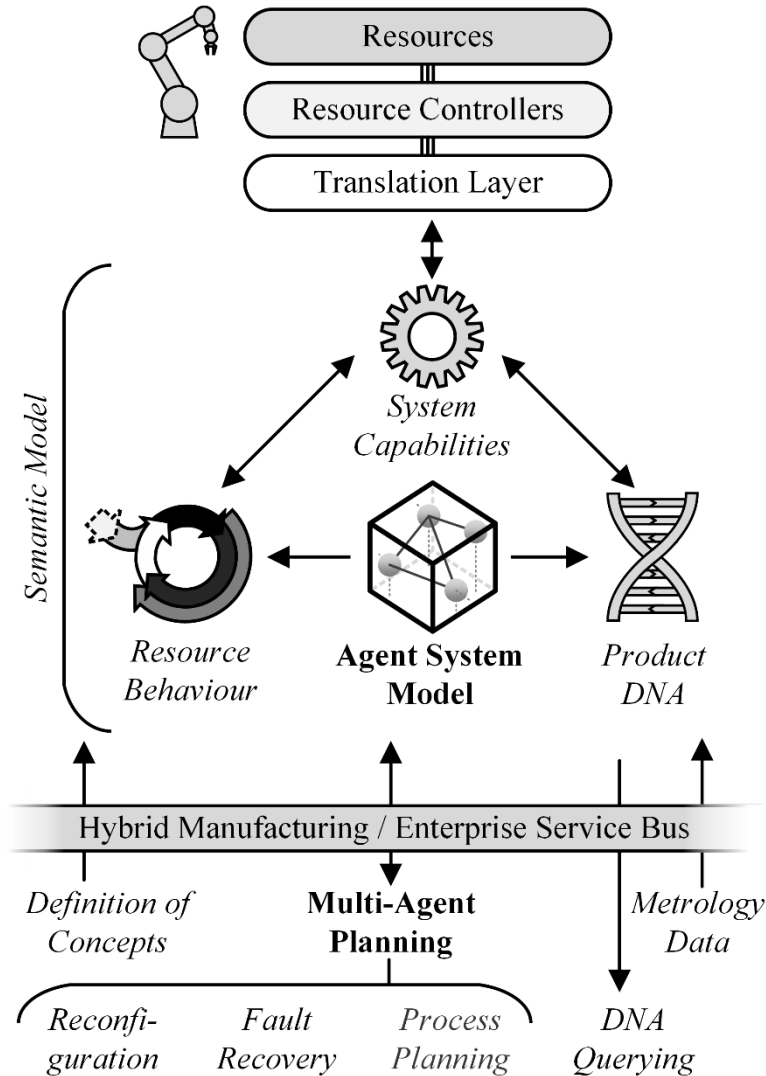
**5 Year Project: 1<sup>st</sup> Feb 2013 – 31<sup>st</sup> Jan 2019**

**Total Budget: £2.66 million**



GE  
Measurement & Control





## ■ Behaviour

- How will the system react to disruption?
- How do we guide system behaviour to achieve goals?

## ■ Capabilities

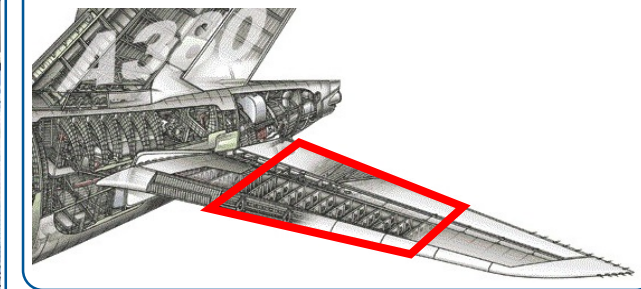
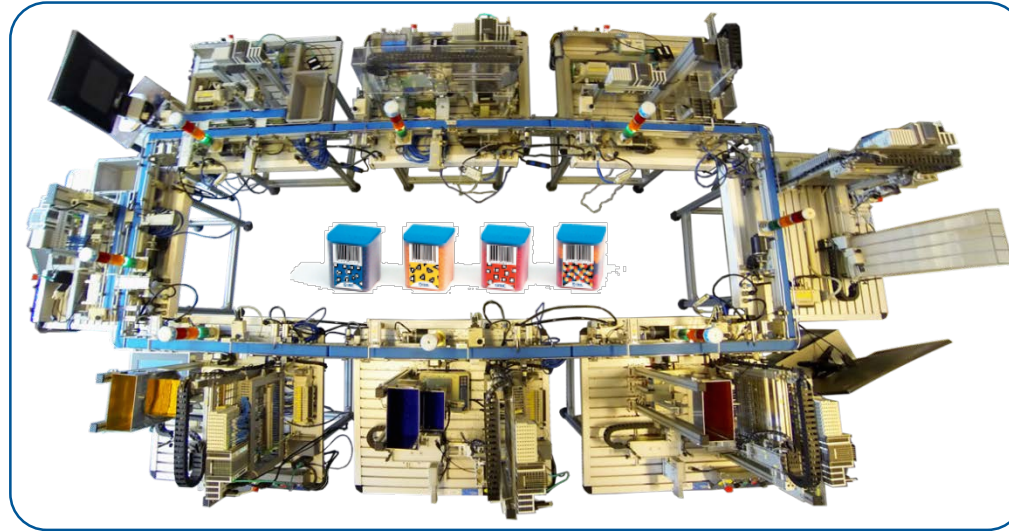
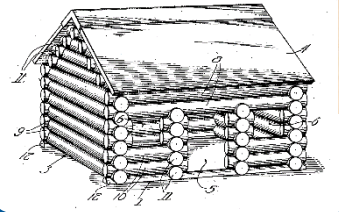
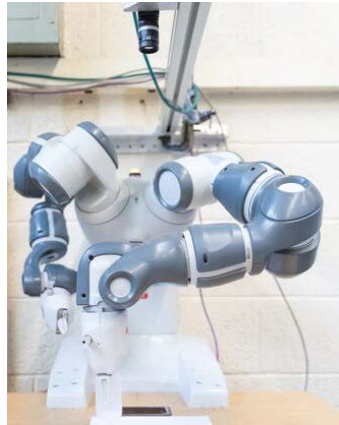
- What is the system topology?
- What can the whole system do?

## ■ Products / Parts

- What happened to *<PartY>*?

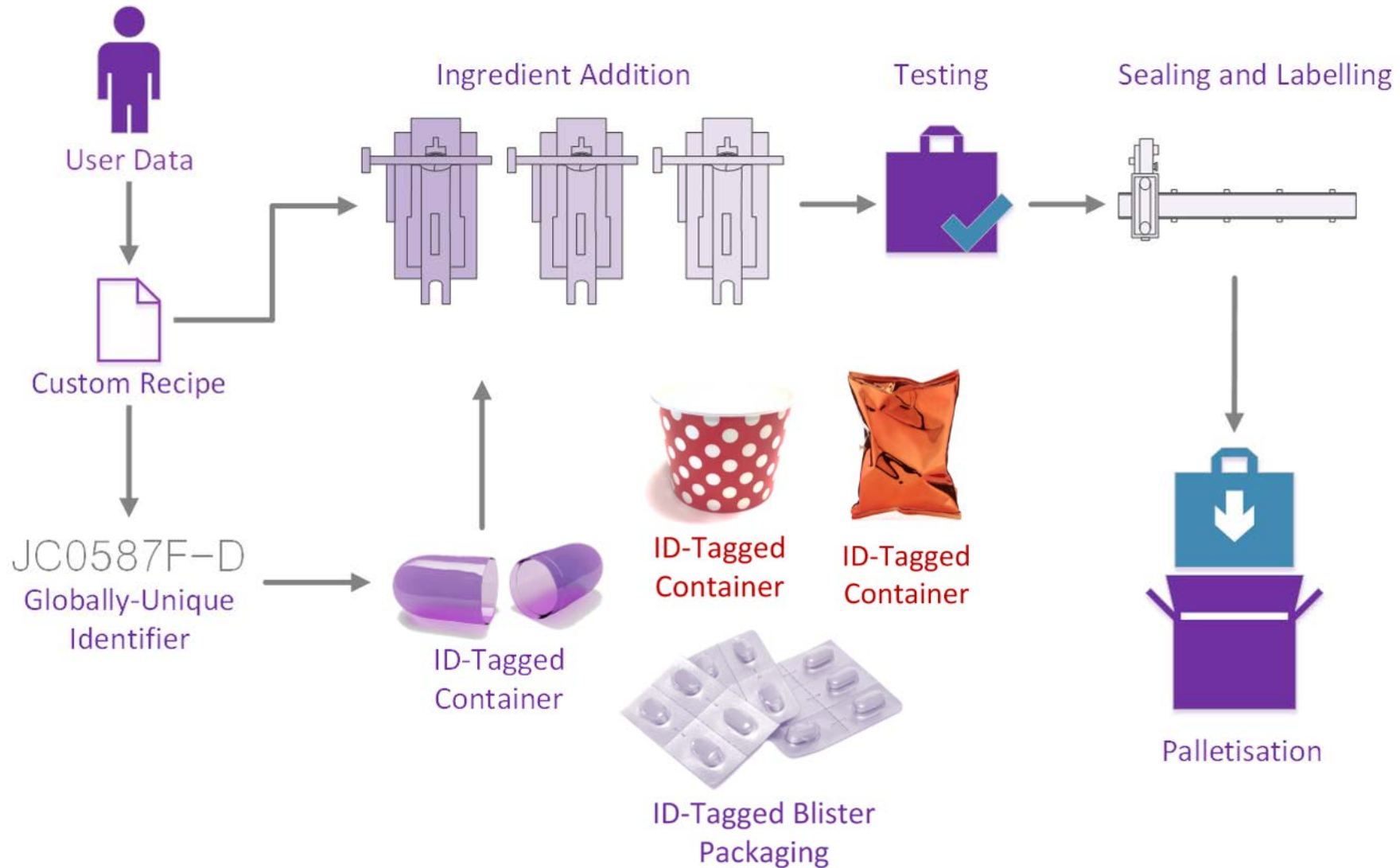


# Example Scenarios – Batch Size of One





# Batch Size of One Scenario – Customisable Pharma/Food





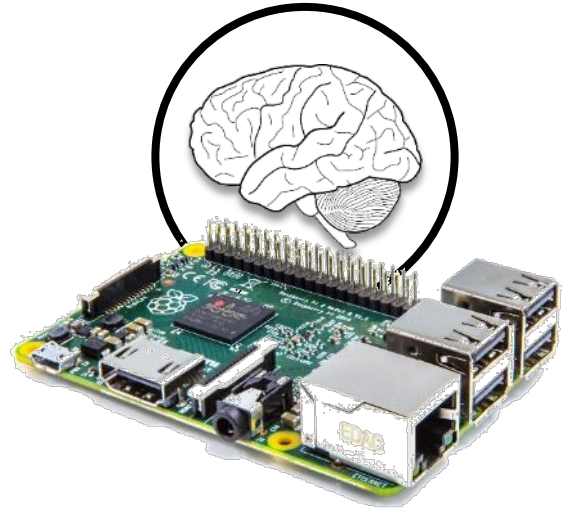


# SMART Demonstrator





# EAS Intelligent Agent Control



**High-Level  
Commands**

**Low-Level  
Control**

**Capability  
Instantiation**

**High-Level  
Decisions**

**Processed  
Data**

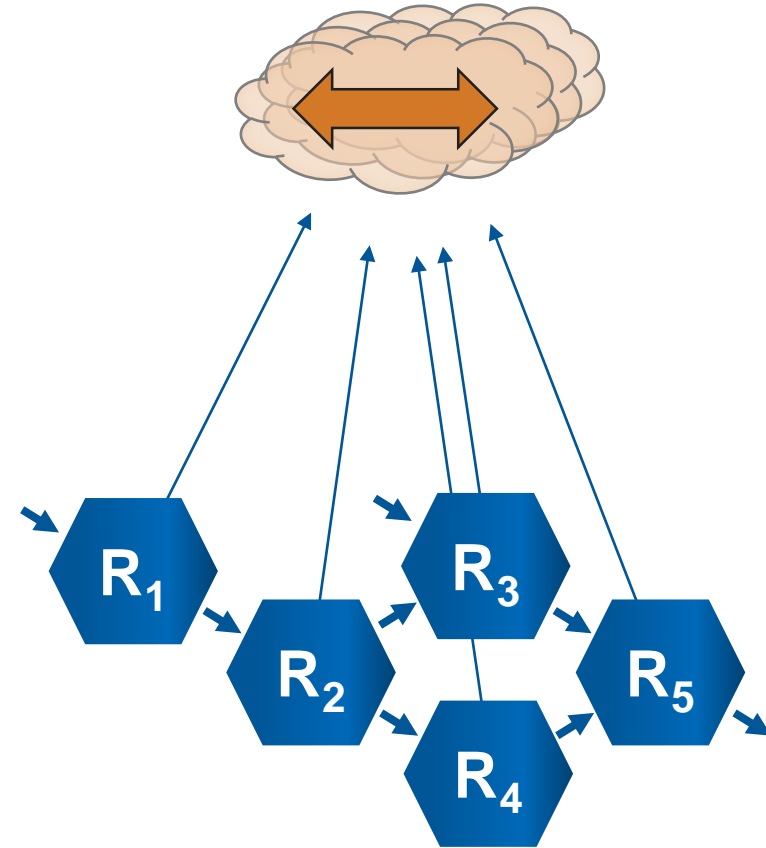
**Raw  
Data**





- Data Distribution Services promote a **decoupled, data-driven** communication strategy
- Nodes **publish** and **subscribe** to topics without concern for the origin/consumer node
- The topics and nodes form a **Shared System Context** – a single canonical view of all data
- Resources need only take from this Context what they require to make **intelligent decisions**

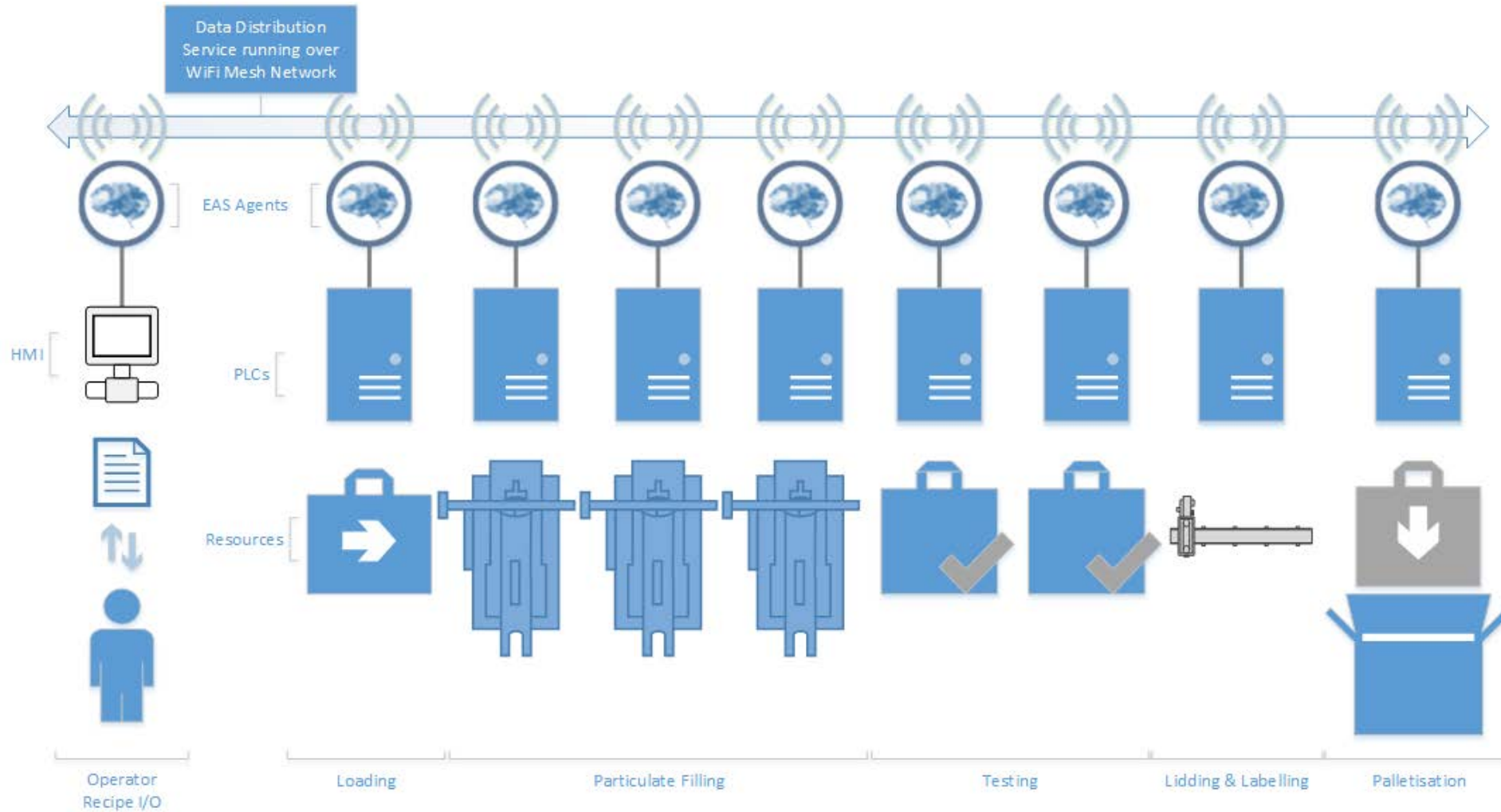
## Shared System Context



**Production Line**



# SMART Network

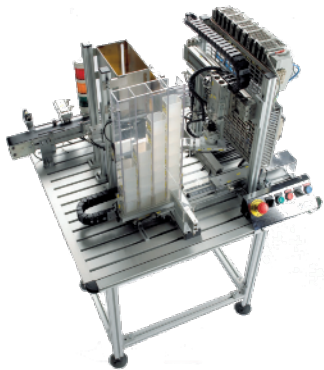




# Recipe Tracking

## *To-Do List*

Recipe ID	Identifier	Action ID	Action	Arguments	Pre-requisites
0001	0000 0001	3	Fill Yellow	1	1,2



Fill Yellow

## *Referenced Recipes*

Recipe ID	Action ID	Action	Status
0001	1	Load	Complete
	2	Fill Blue	Complete
	3	Fill Yellow	Claimed
	4	Test	Claimed
	5	Lid/Label	Claimed
	6	Palletise	Claimed



Institute for  
**Advanced Manufacturing**

 **The University of  
Nottingham**  
UNITED KINGDOM · CHINA · MALAYSIA

## **EPSRC Evolvable Assembly Systems**

TOWARDS OPEN, ADAPTABLE AND CONTEXT AWARE EQUIPMENT AND SYSTEMS  
EP/K018205/1

### **SMART Demonstrator**

(Smart Manufacturing and Reconfigurable Technologies)

  
**EPSRC**  
Engineering and Physical Sciences  
Research Council

  
**Evolvable**  
Assembly Systems

[YouTube Link](#)

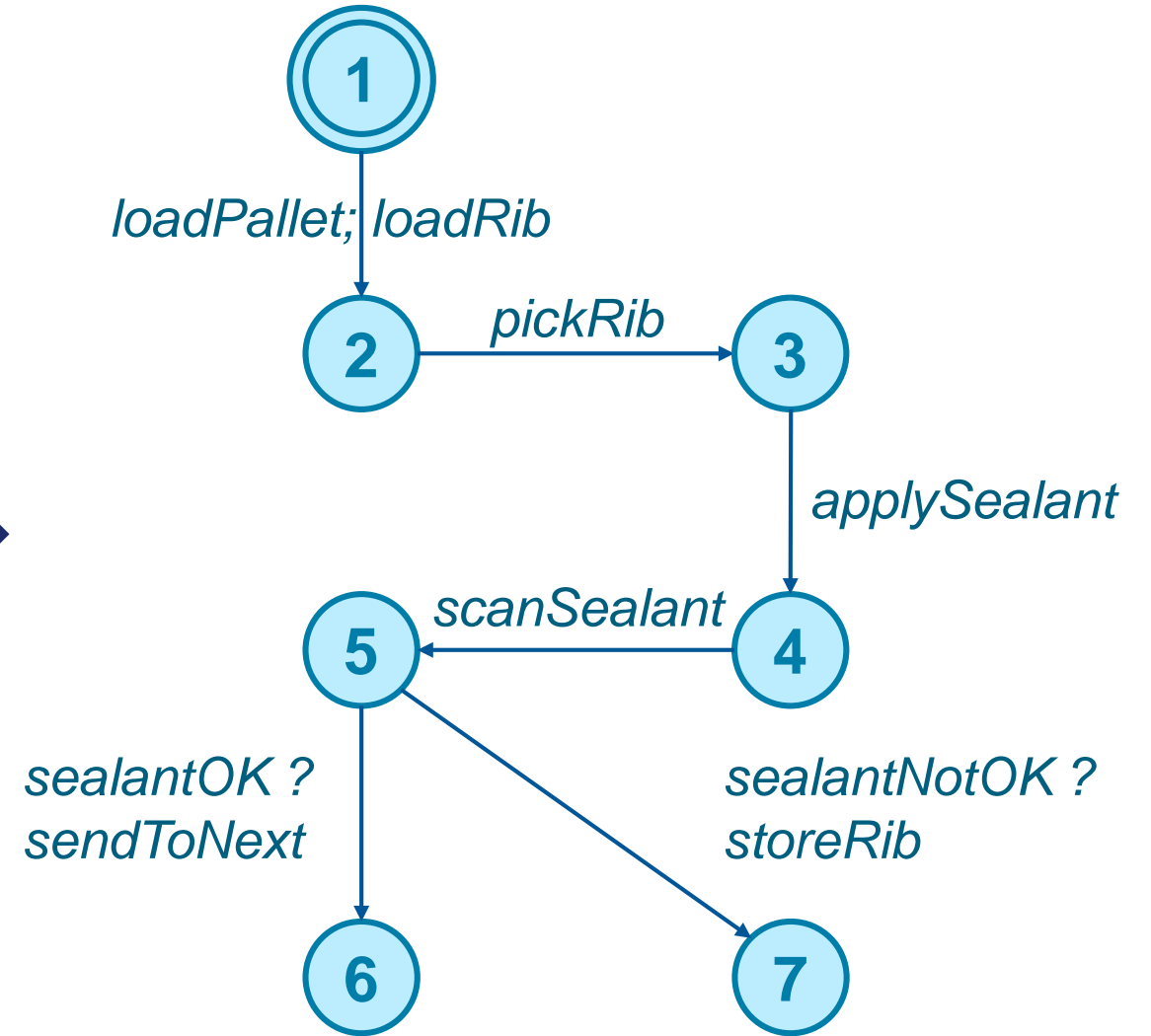


- Automatically apply and verify sealant application to multiple unique rib components
  - Each rib unique – but not immediately obvious to operator
  - Recipe-driven automation
- Rib components to be assembled as part of larger structure
  - Requires information about quality of sealant to achieve tight tolerances
- Automated cell, but decisions must be scrutinised if necessary
  - Requires complete data logging





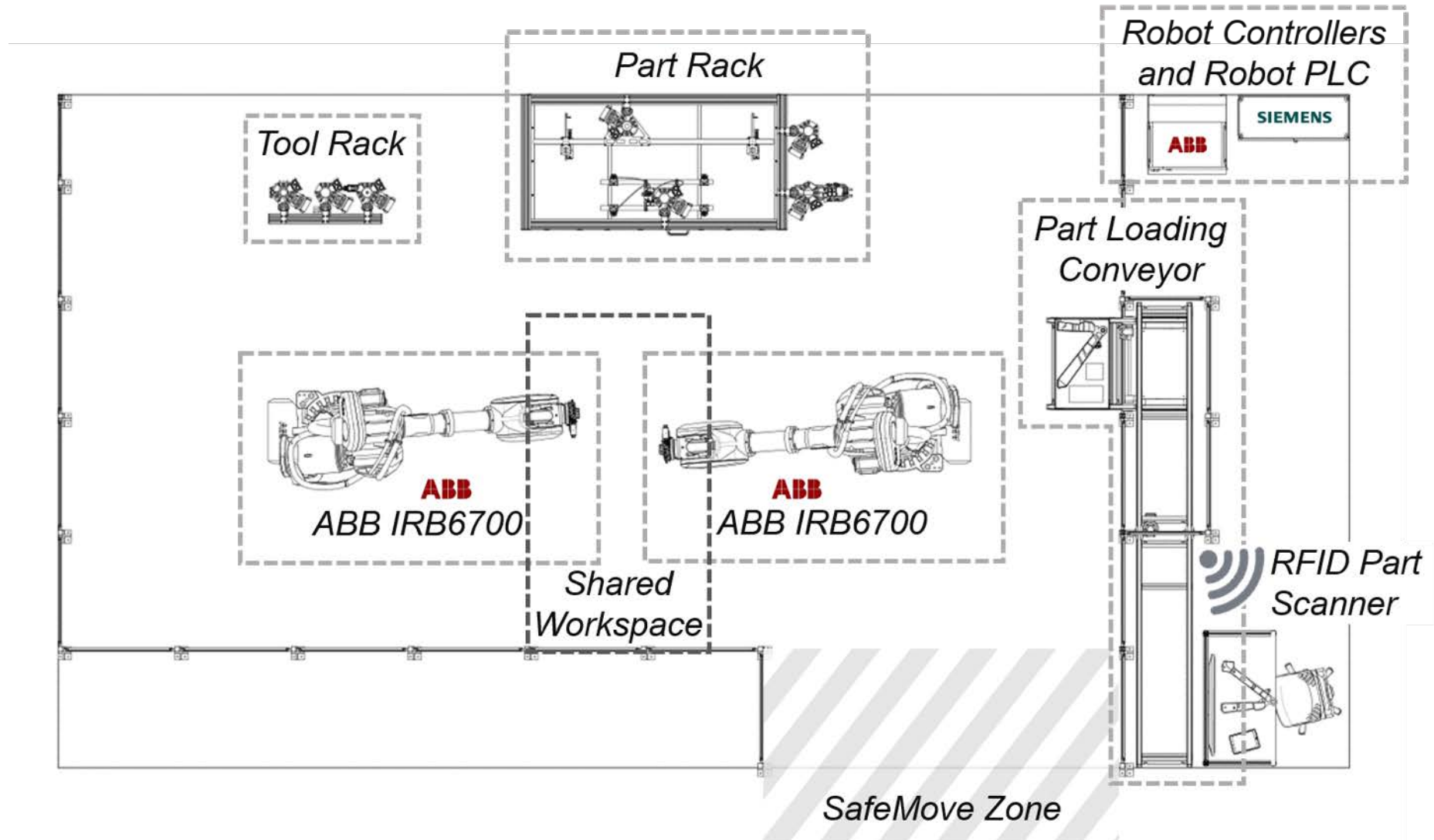
# Example Recipe





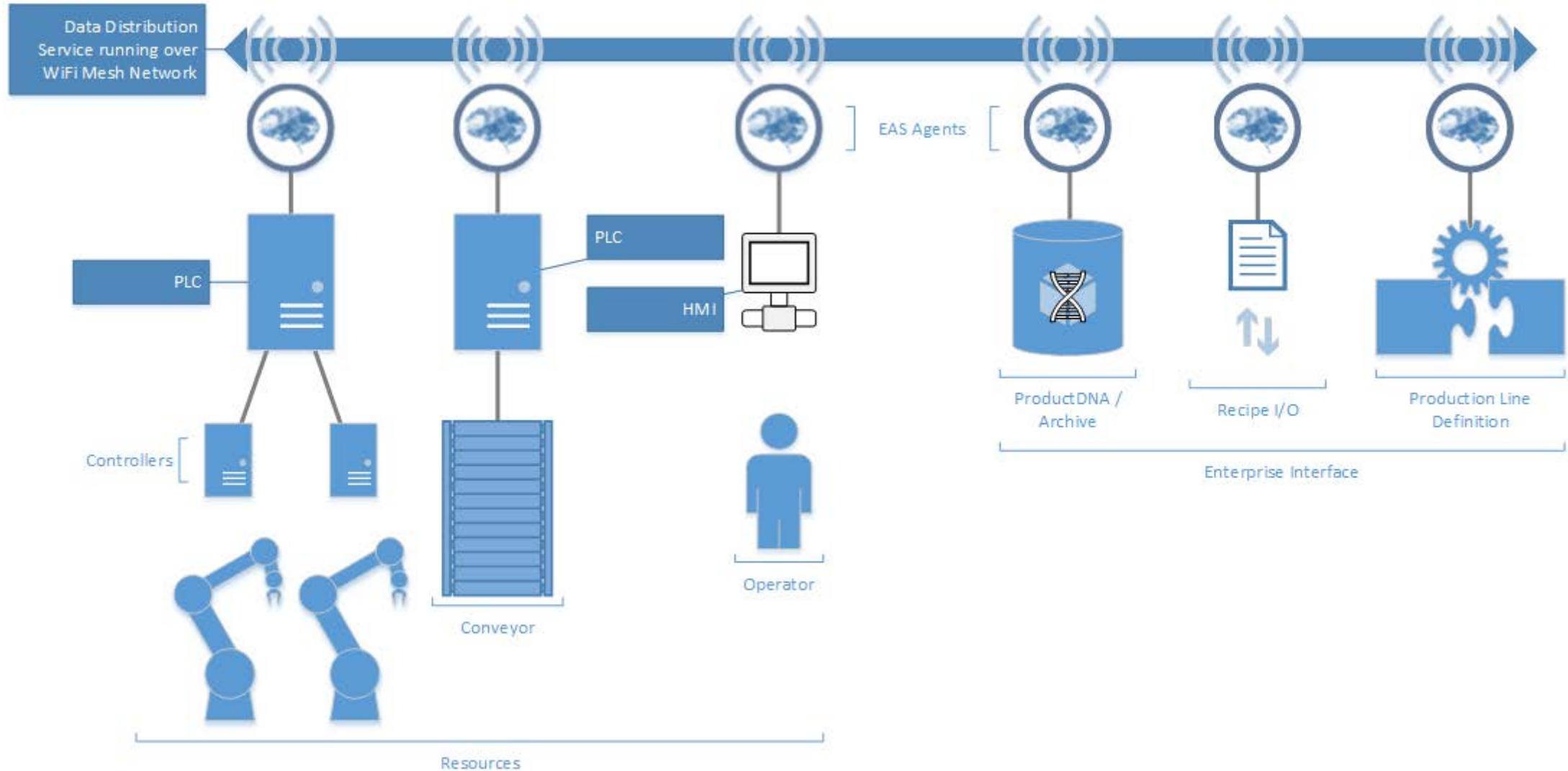


# Cell Resources





# ABB Cell Network





# Batch Size of One Demonstration

The screenshot displays the 'RecipeSubmissionAgent' window. On the left, there are controls for selecting a recipe type ('Apply Sealant, Scan Rib, and Store'), target rib ('Rib/Pallet 1'), and production line ('ABB Cell'). A 'Submit Recipe' button is at the bottom. The main area shows a state transition diagram with five states (state0 to state4) and transitions labeled with actions like 'getPalletLoc1()(P1)', 'loadRib(P1)(R1)', 'scanAndSealant(R1)(R1Sealed)', and 'storeLoc1(R1Sealed)(R1Sealed)'. A 'Recipe Completed' dialog box is overlaid, displaying the message: 'Recipe 'sealantScan1.wop2017/11/06/10:19:49' was completed on production line 'ABB Cell'.' with an 'OK' button. At the bottom of the window, there are various view controls like zoom and spacing options.

- Recipes can be submitted to the system via user interface
- Agents collaborate to determine if recipe is possible, and what the execution plan is
- Shared system model allows per-recipe topics for agents to track multiple recipe progress



# Recipe Tracking

Domain: Recipe 0001

Topic: pickRib

**Task Status:**  
Complete

**Location:**  
104.6X 205.4Y 67.1Z  
56A 78B 104C

**Time Completed:**  
2018/01/01  
14:56:12

**RFID Part ID:**  
6D0000000000001

What data is important for others to know?

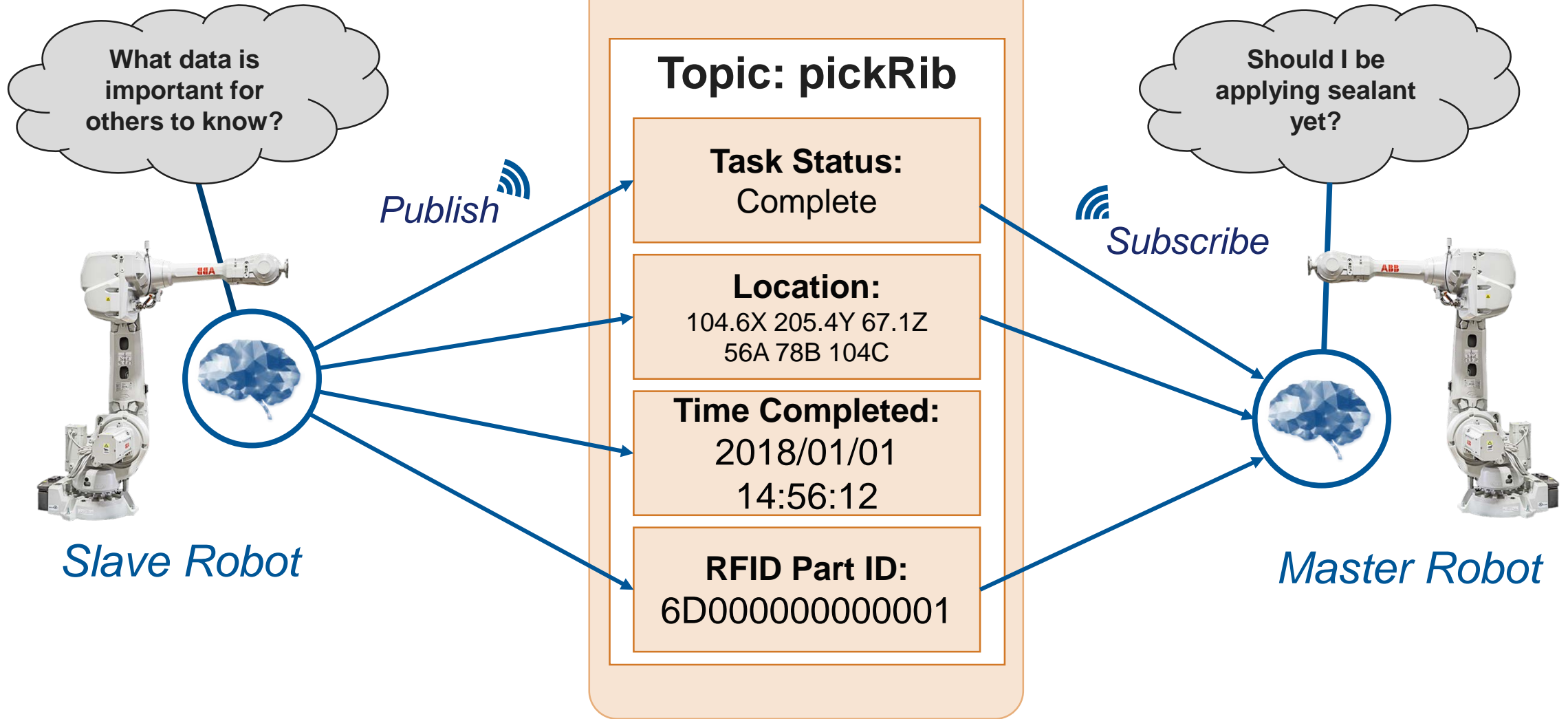
*Publish*

Should I be applying sealant yet?

*Subscribe*








*Slave Robot*

*Master Robot*





# Industrialisation of Fundamental Research

Partners	Key Projects	Funding	Research Theme
	<ul style="list-style-type: none"> <li>Next Generation Composite Wing (NGCW)</li> <li>Factory of Aircraft Future (FoAF)</li> <li>Wing Lean Innovative Future Technologies (WingLIFT)</li> </ul>	Direct Funding and Aerospace Technology Institute (ATI)	<ul style="list-style-type: none"> <li>Future Factory</li> <li>Future Assembly Tooling</li> <li>Current Production Tooling &amp; Business Case</li> </ul>
 	<ul style="list-style-type: none"> <li>Advanced Wing Structure for Rotorcraft Additional Lift (ASTRAL)</li> </ul>	Clean Sky 2, EU	<ul style="list-style-type: none"> <li>Design and Structural Optimisation</li> <li>Cost Modelling for Composite Manufacturing and Assembly</li> <li>Automated Assembly of 3m Demonstrator Wing <i>(UoN Core Partner &amp; Coordinator)</i></li> </ul>
	<ul style="list-style-type: none"> <li>Digital Factory</li> <li>Assembly Philosophies</li> <li>Assembly Demonstrator</li> </ul>	Direct Funding and Aerospace Technology Institute (ATI)	<ul style="list-style-type: none"> <li>Future Assembly Tooling</li> <li>Automated Assembly Processes</li> <li>Future Factory Enablers <i>(Awarded 3 Chairman's Bronze Awards)</i></li> </ul>
 	<ul style="list-style-type: none"> <li>Validation and Integration of Manufacturing Enablers for Future Wing Structures (VIEWS)</li> </ul>	Aerospace Technology Institute (ATI)	<ul style="list-style-type: none"> <li>Flexible Component Assembly Cell</li> <li>Automated Sealant Application</li> <li>Human Robot Collaboration</li> </ul>
	<ul style="list-style-type: none"> <li>Variance Aware Determinate Assembly Integrated System (VADIS)</li> </ul>	Clean Sky 2, EU	<ul style="list-style-type: none"> <li>Scanning of Aircraft Wing Skins (~10m) for Rib Holes and Interfaces <i>(UoN Coordinator)</i></li> </ul>



University of  
Nottingham

Centre for Aerospace Manufacturing

A photograph of a large industrial facility, likely an aircraft manufacturing plant, with several large orange KUKA robotic arms positioned around a central assembly area. The scene is dimly lit with a blue tint.

# Thank You

Supported by UK EPSRC “Evolvable Assembly Systems” (Grant EP/K018205/1)