



RULE MODEL OF FEATURE INSPECTION AND RESOURCE SELECTION FOR DIMENSIONAL MEASUREMENT PLANNING

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Gaithersburg, MD

April 4, 2018



Outline

- Background
- Quality Information Framework
- Activity Model
- Rule Model
- Sample Instances
- Conclusion



Background

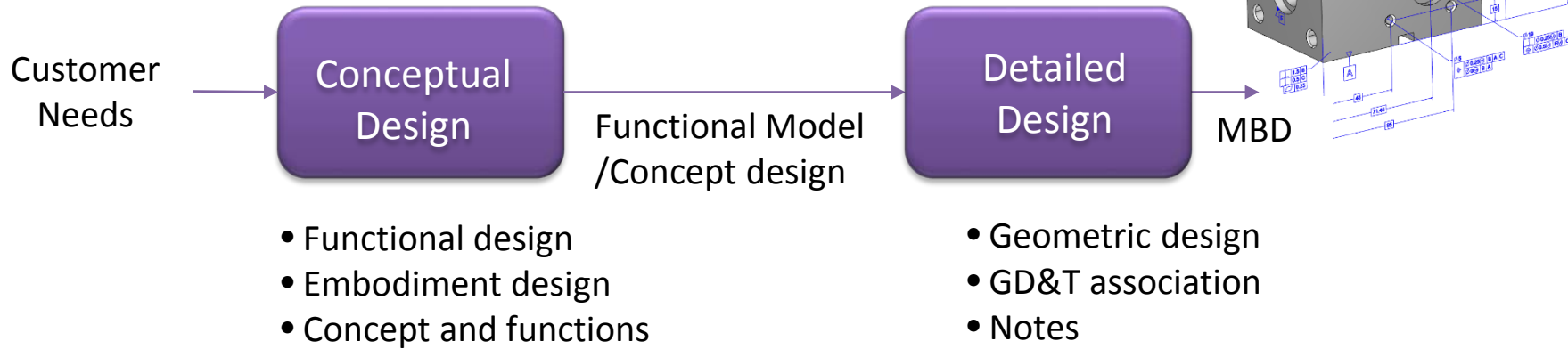
Dimensional inspection planning is “one of outstanding activities in manufacturing process automation.”

- Design features are sophisticated and geometries are complicated.
- Surface roughness and reflectivity affect measurements.

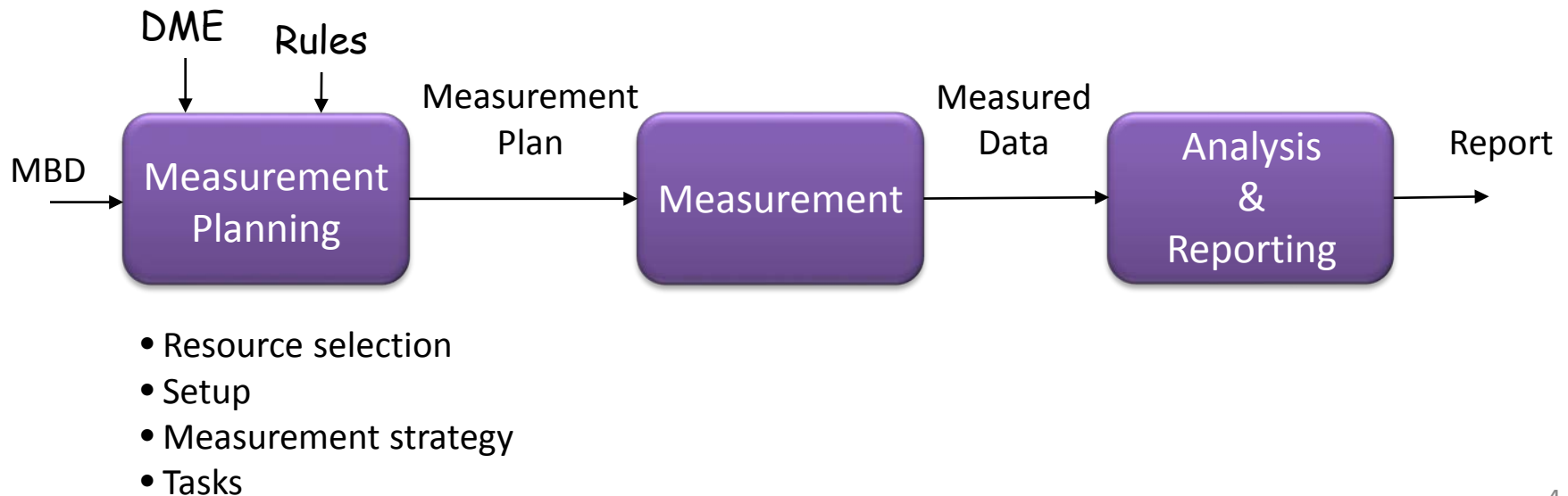
AND

- Measurement requirements are high.
 - Low measurement uncertainty.
 - Sensor-accessible to diverse features.
 - Short measurement and lead times.
 - Stringent requirements on working environment.

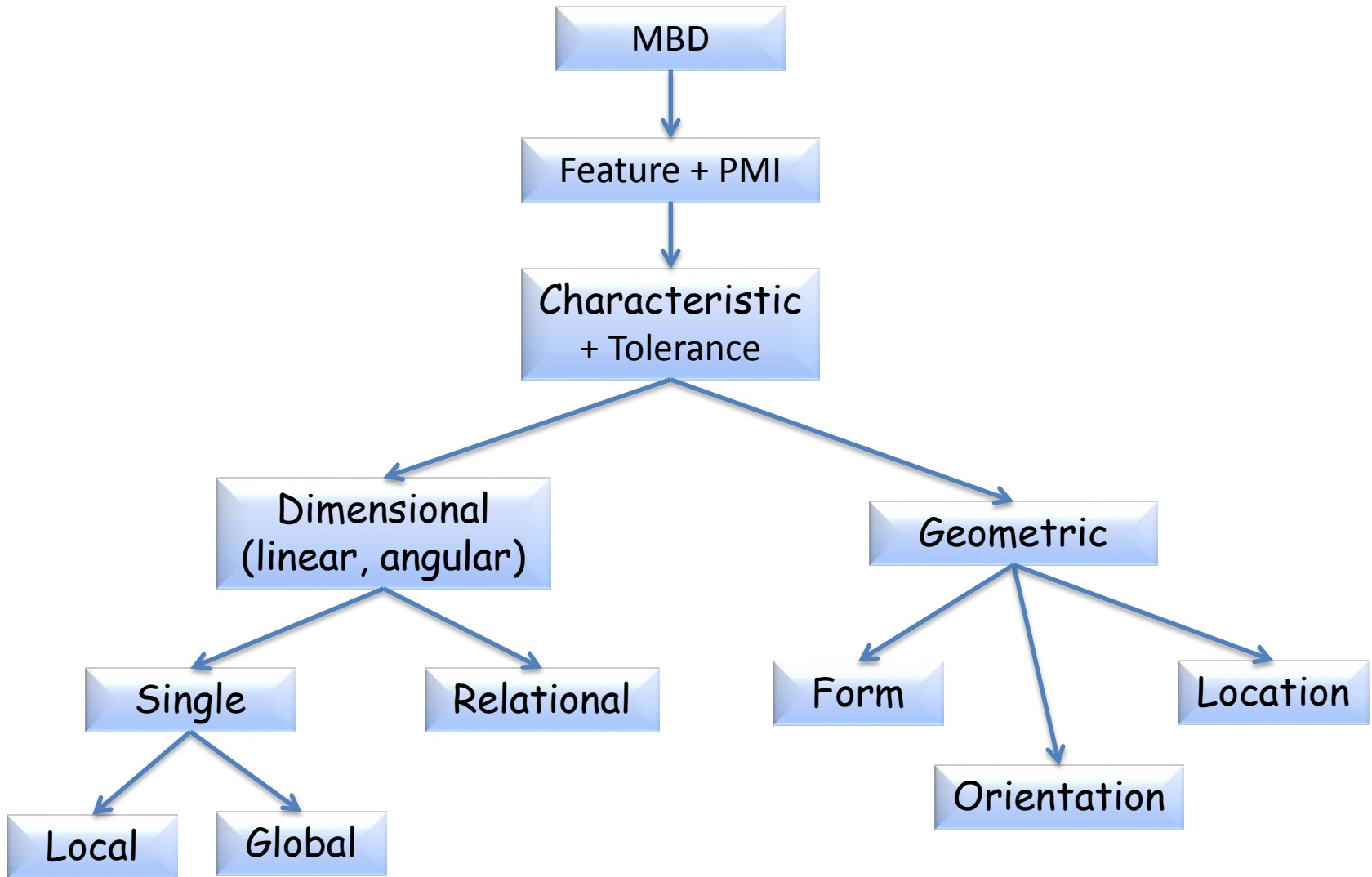
Design



Measurement

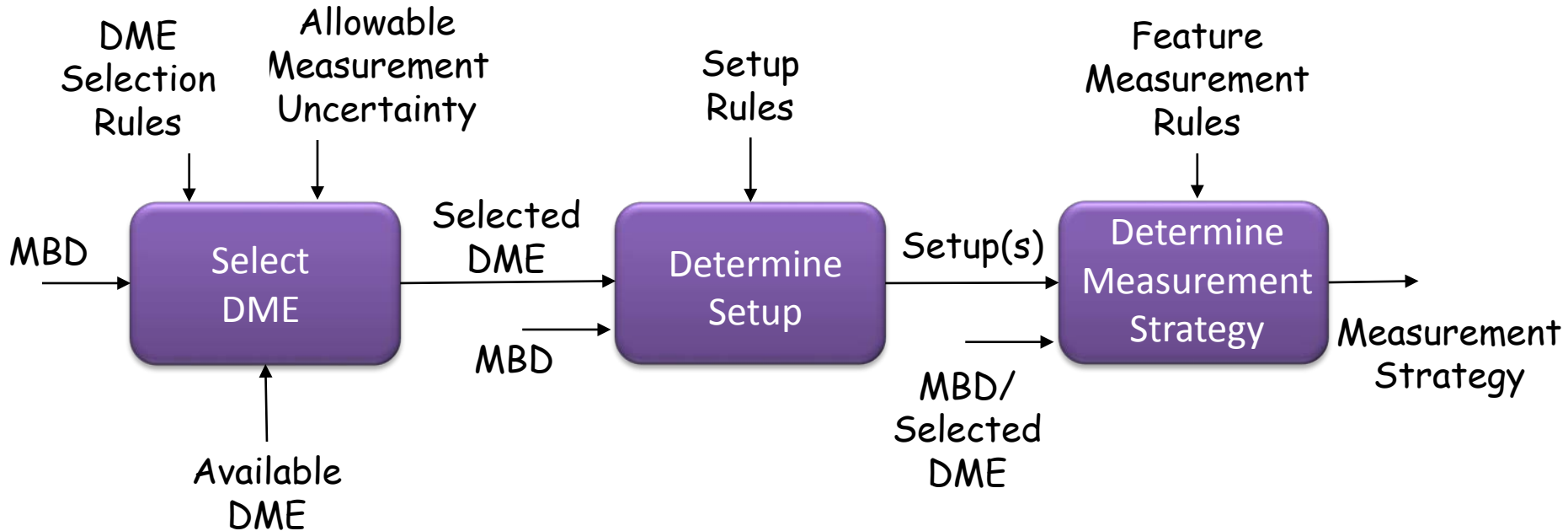


Design Characteristic



Reference: ISO 17450-1 Geometrical product specifications (GPS) - General concepts - Part 1: Model for geometrical specification and verification

Measurement Planning

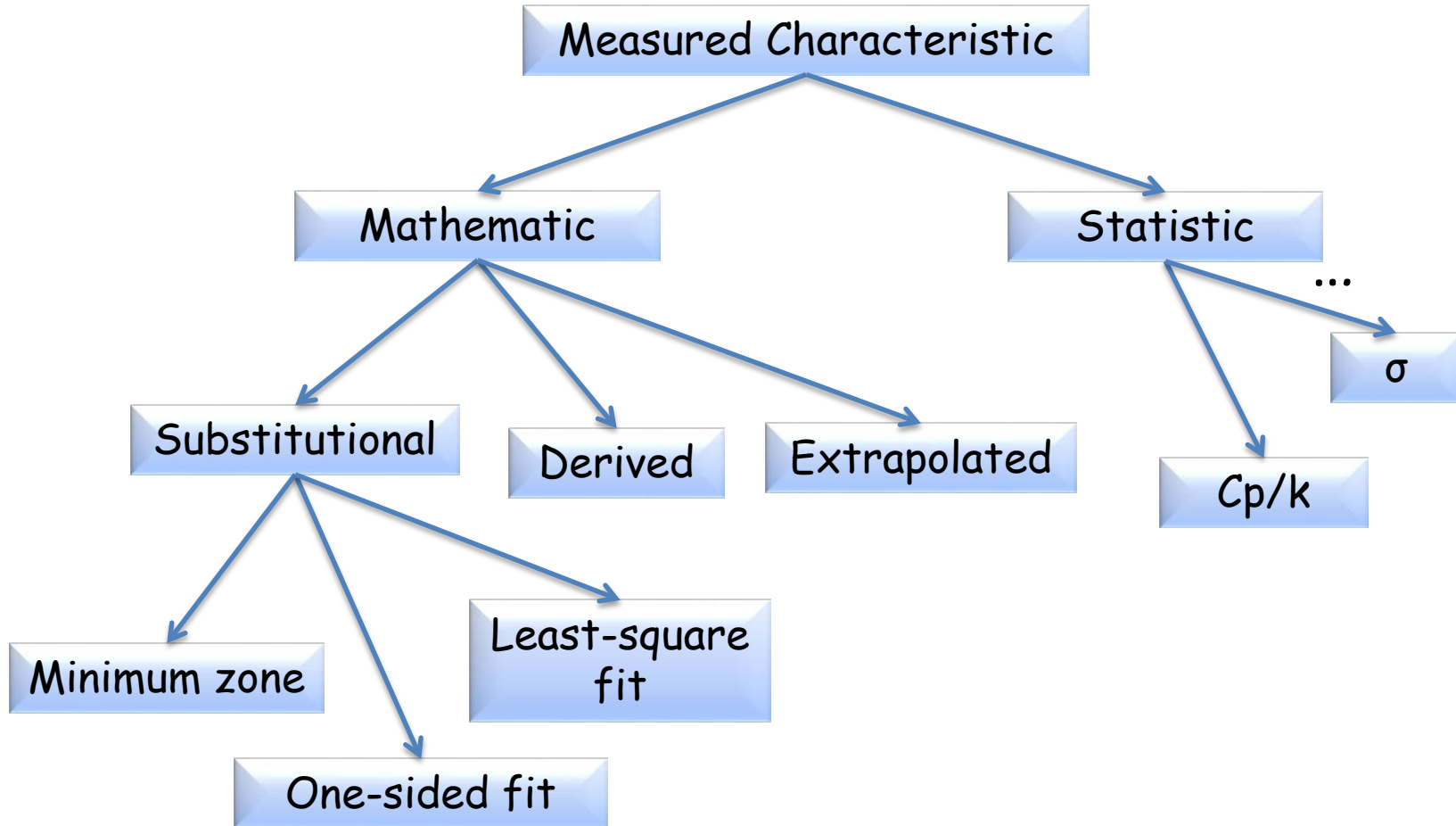


DME: Dimensional Measurement Equipment

References:

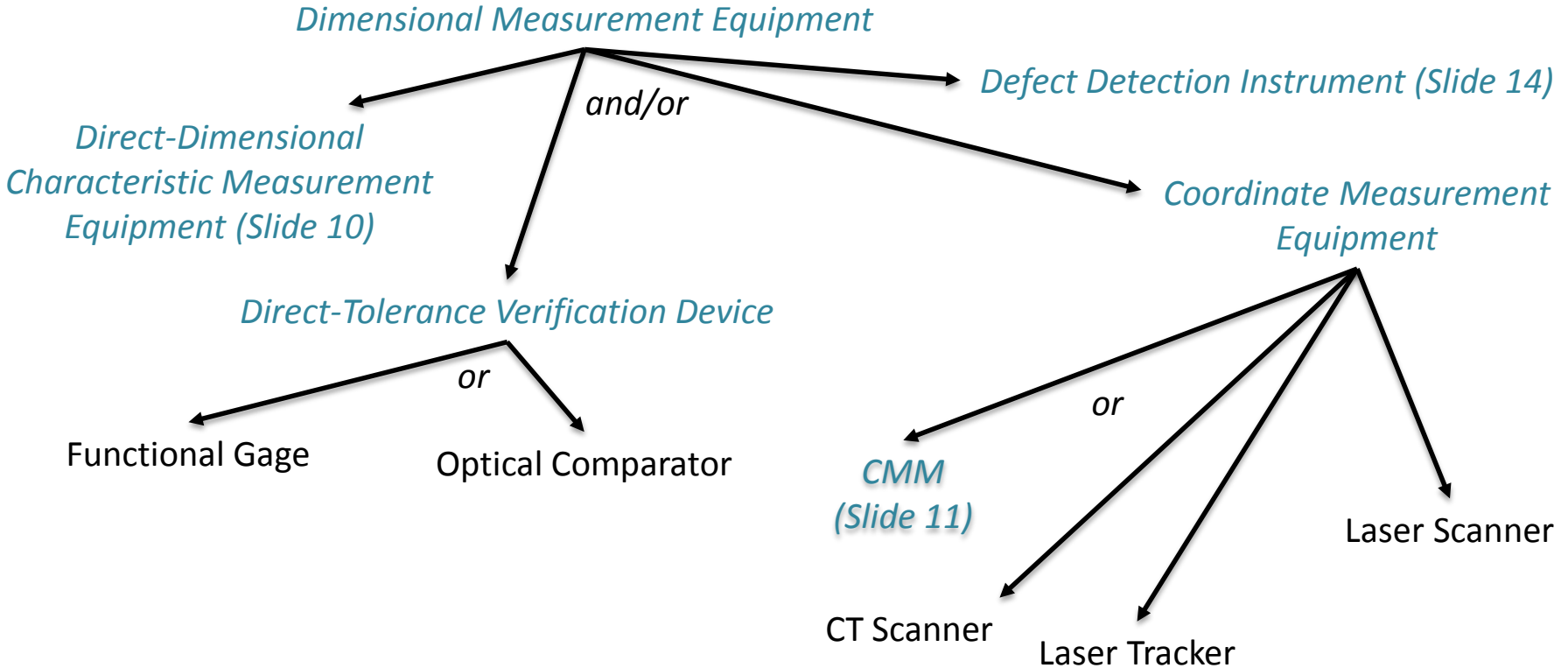
- ISO 15530-3 Geometrical product specifications (GPS) -Coordinate measuring machines (CMM): Technique for determining the uncertainty of measurement - Part 3: Use of calibrated workpieces or measurement standards
- ISO 13385-1 Geometrical product specifications (GPS) -Dimensional measuring equipment - Part 1: Calipers; Design and metrological characteristics
- ISO 14660-1 Geometrical Product Specifications (GPS) —Geometrical features —Part 1: General terms and definitions
- ISO 25378 Geometrical product specifications (GPS) - Characteristics and conditions - Definitions

Measured Characteristic

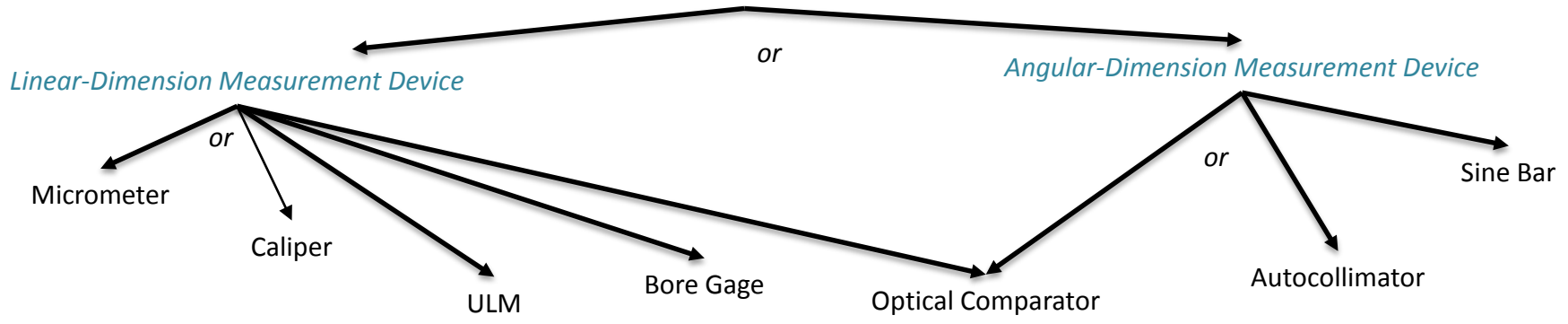


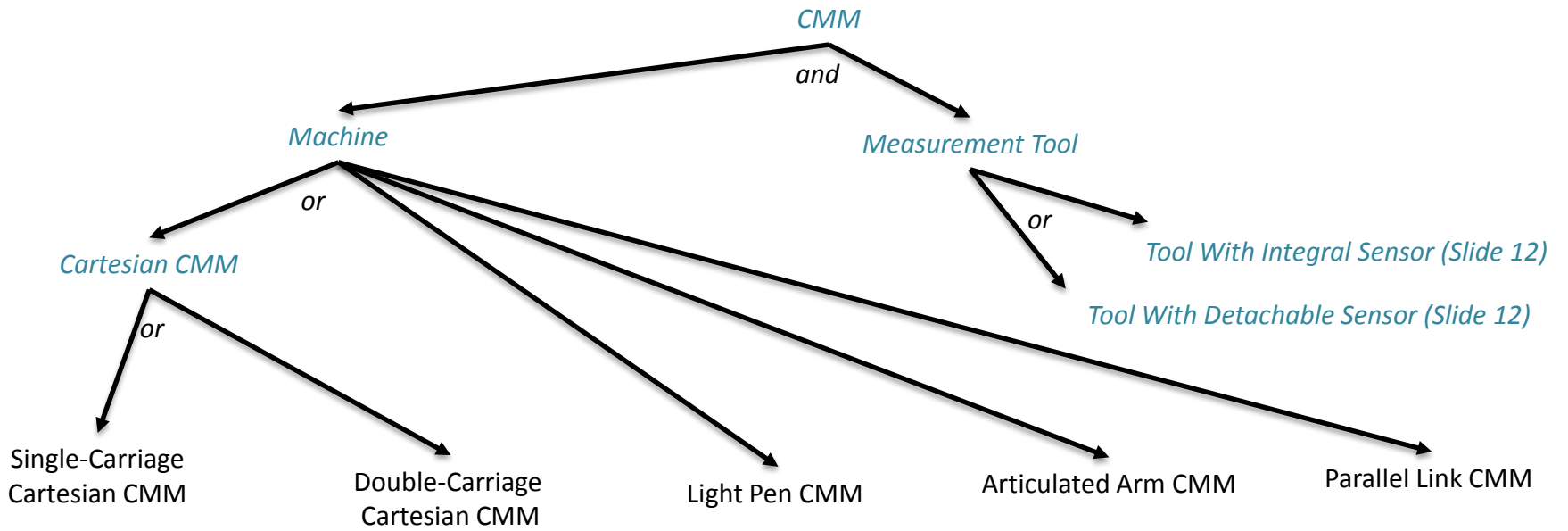


Furthermore, **Dimensional measurement equipment** has become very sophisticated and versatile.



*Direct-Dimensional Characteristic
Measurement Equipment*





Tool With Detachable Sensor

(Similar structure for Tool With Integral Sensor)

or

*Tactile Probe
(Slide 13)*

Nontactile Sensor

Magneto Inductive Sensor

or

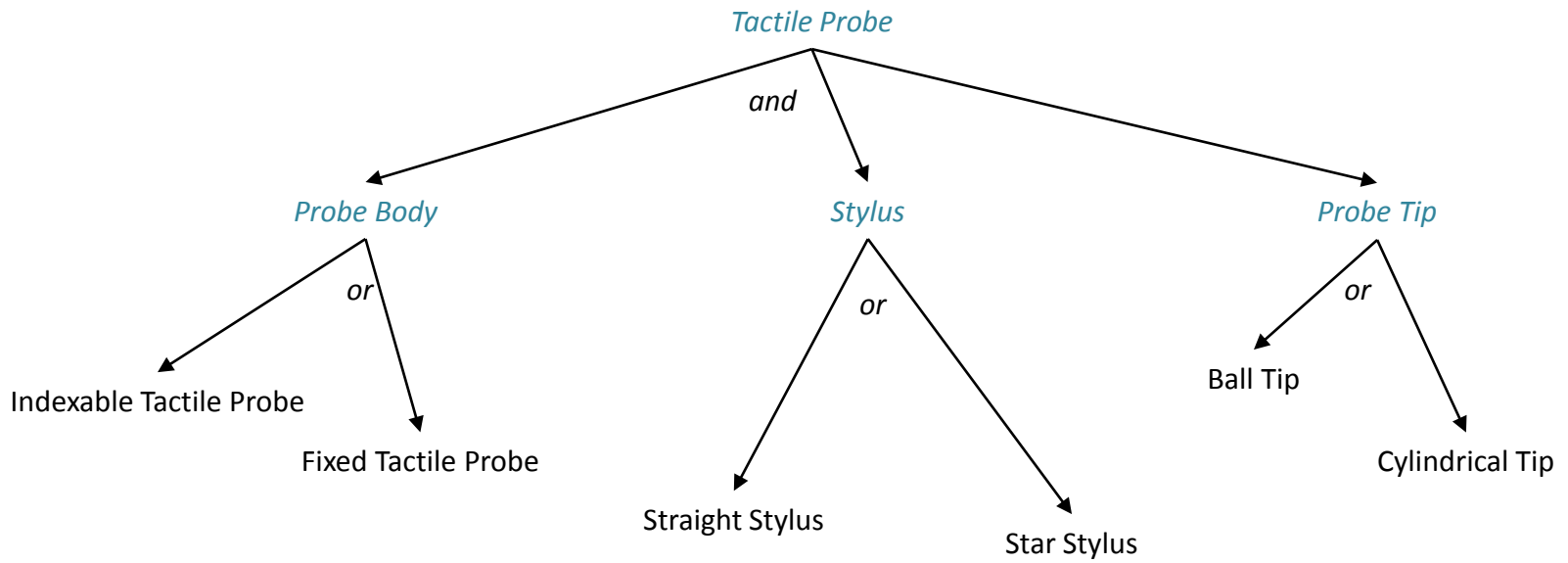
Laser Triangulation Probe

CCD Camera

Structured Light Sensor

Capacitive Sensor

Confocal Chromatic Sensor

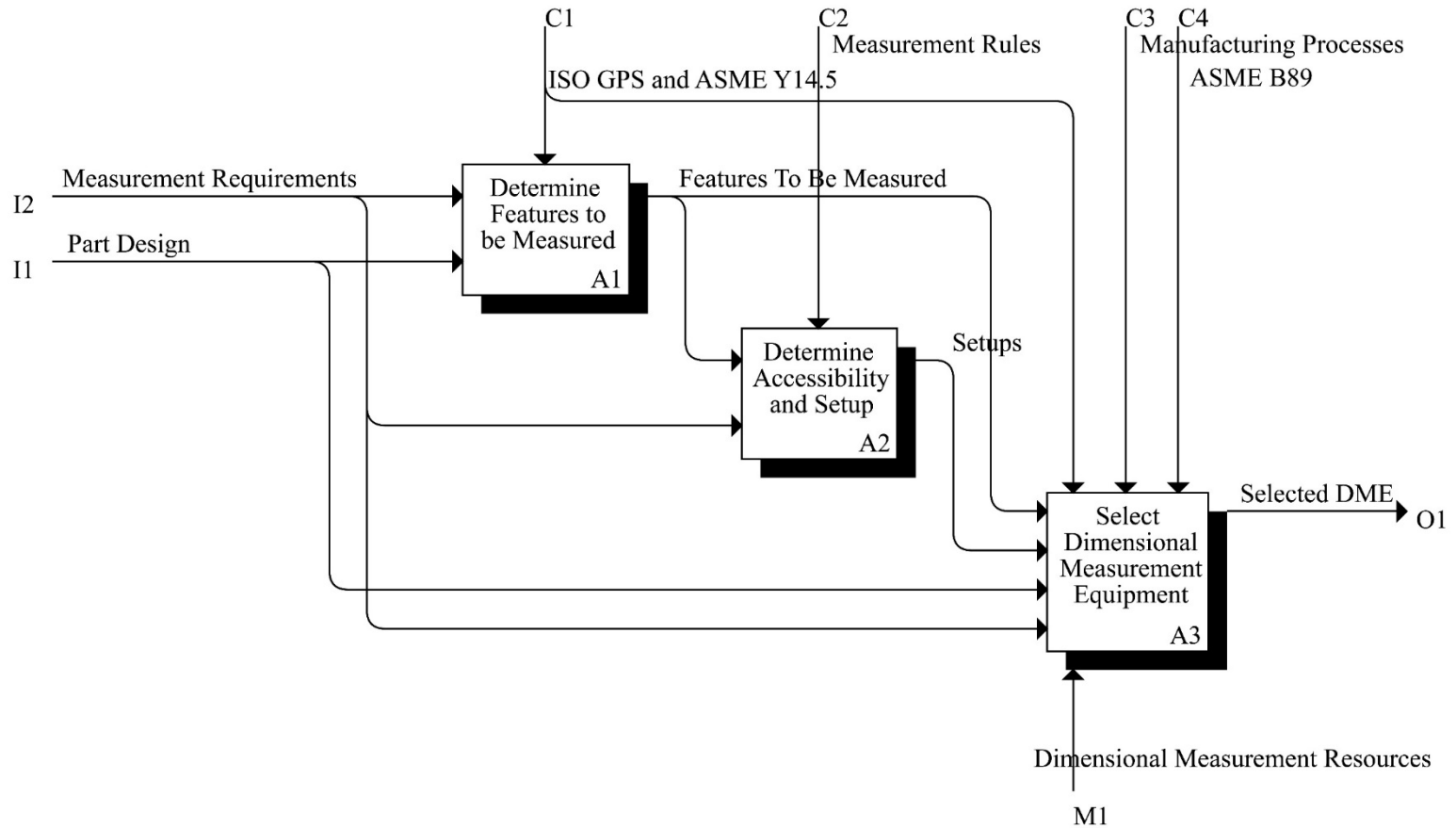




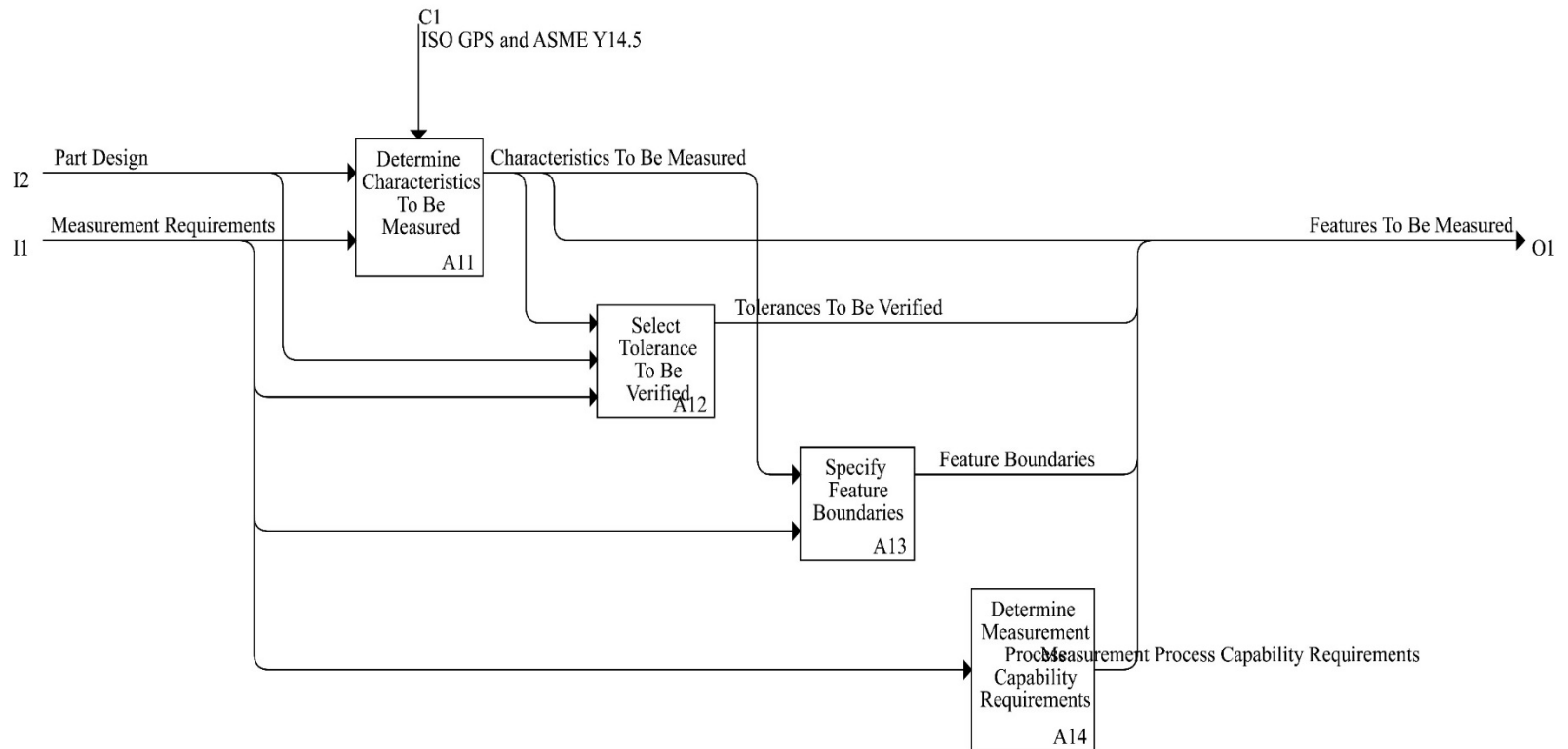
Industry Needs

Rule models for writing metrological rules to establish the relationship between (1) dimensional and geometric characteristics, tolerances, and measurement requirements with (2) choices of dimensional measurement equipment.

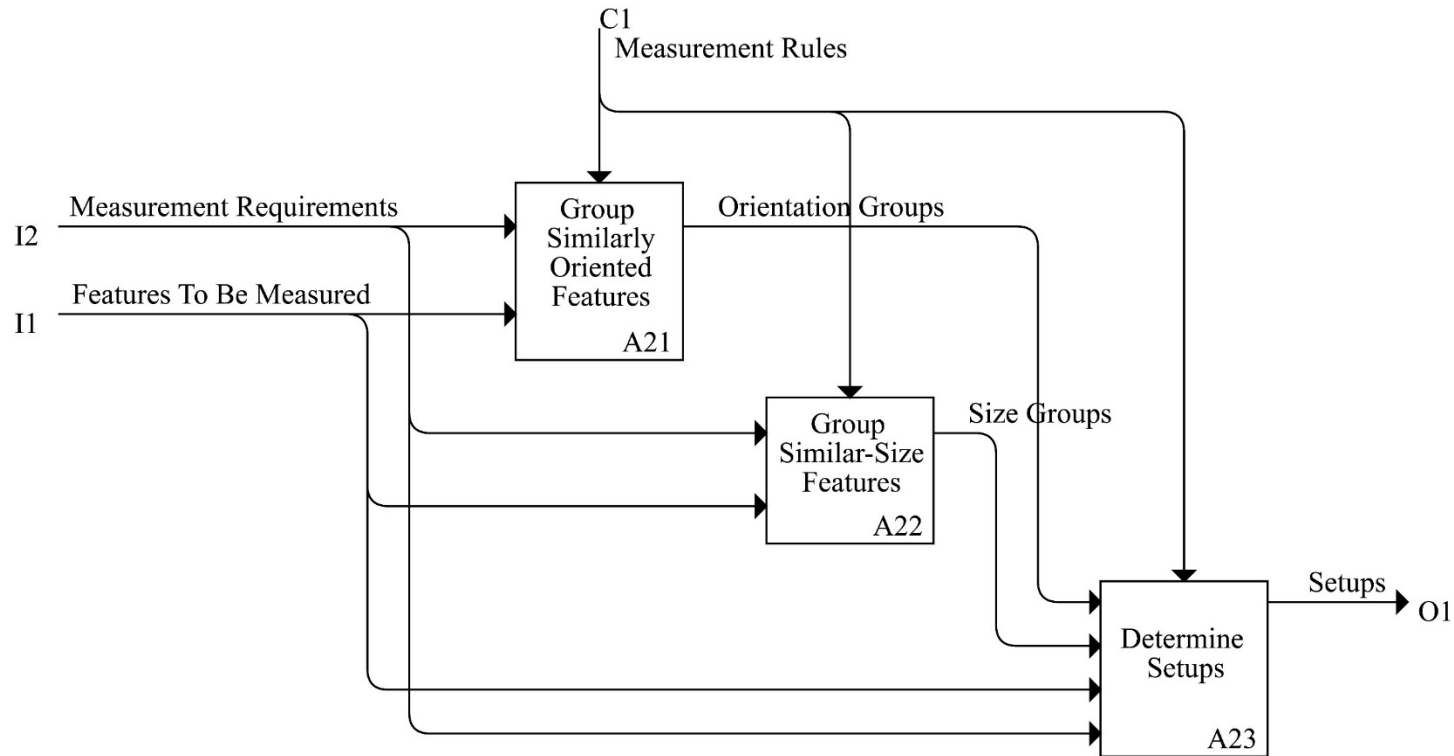
Dimensional Measurement Equipment Selection Process



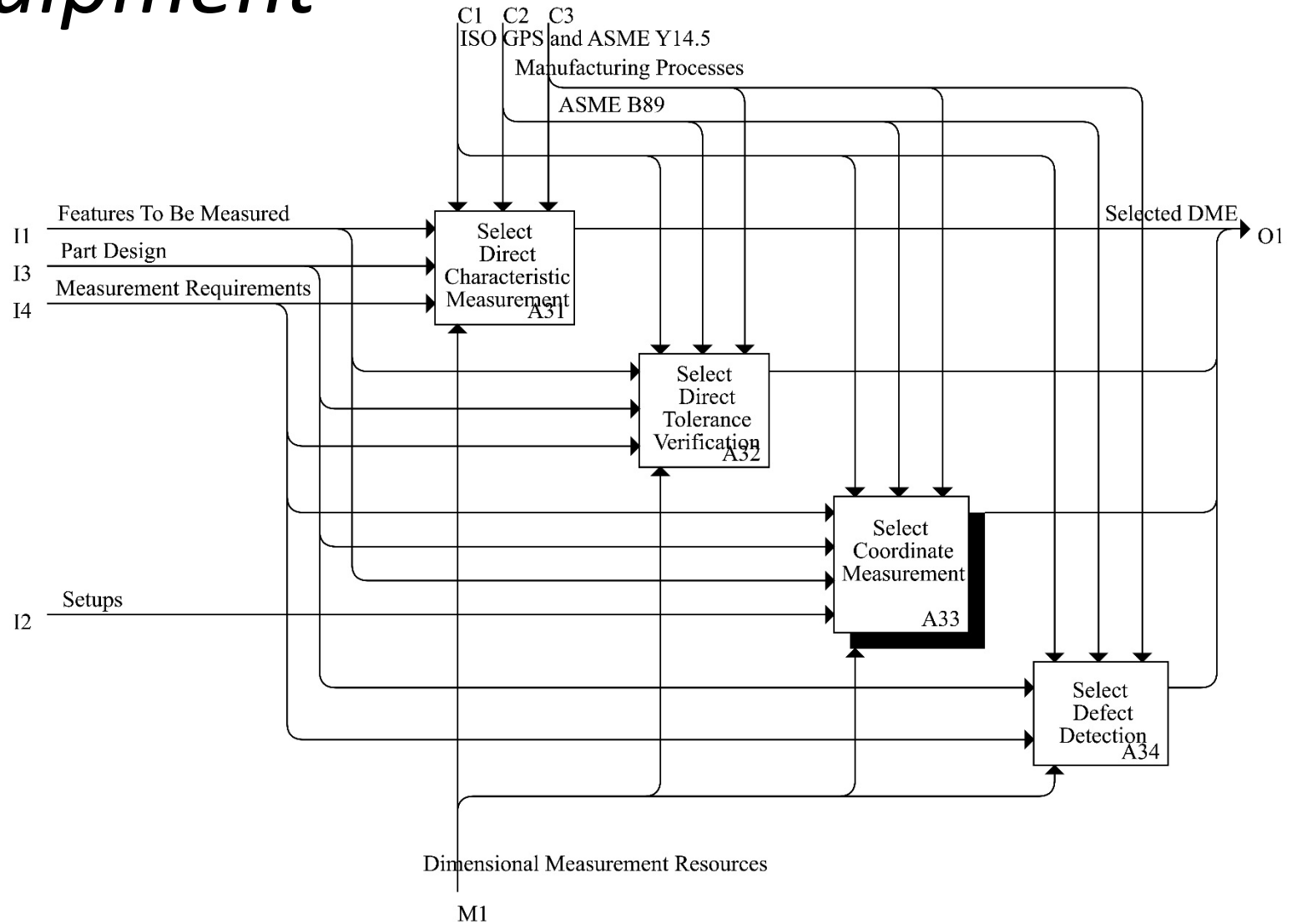
Determine Features to Measure



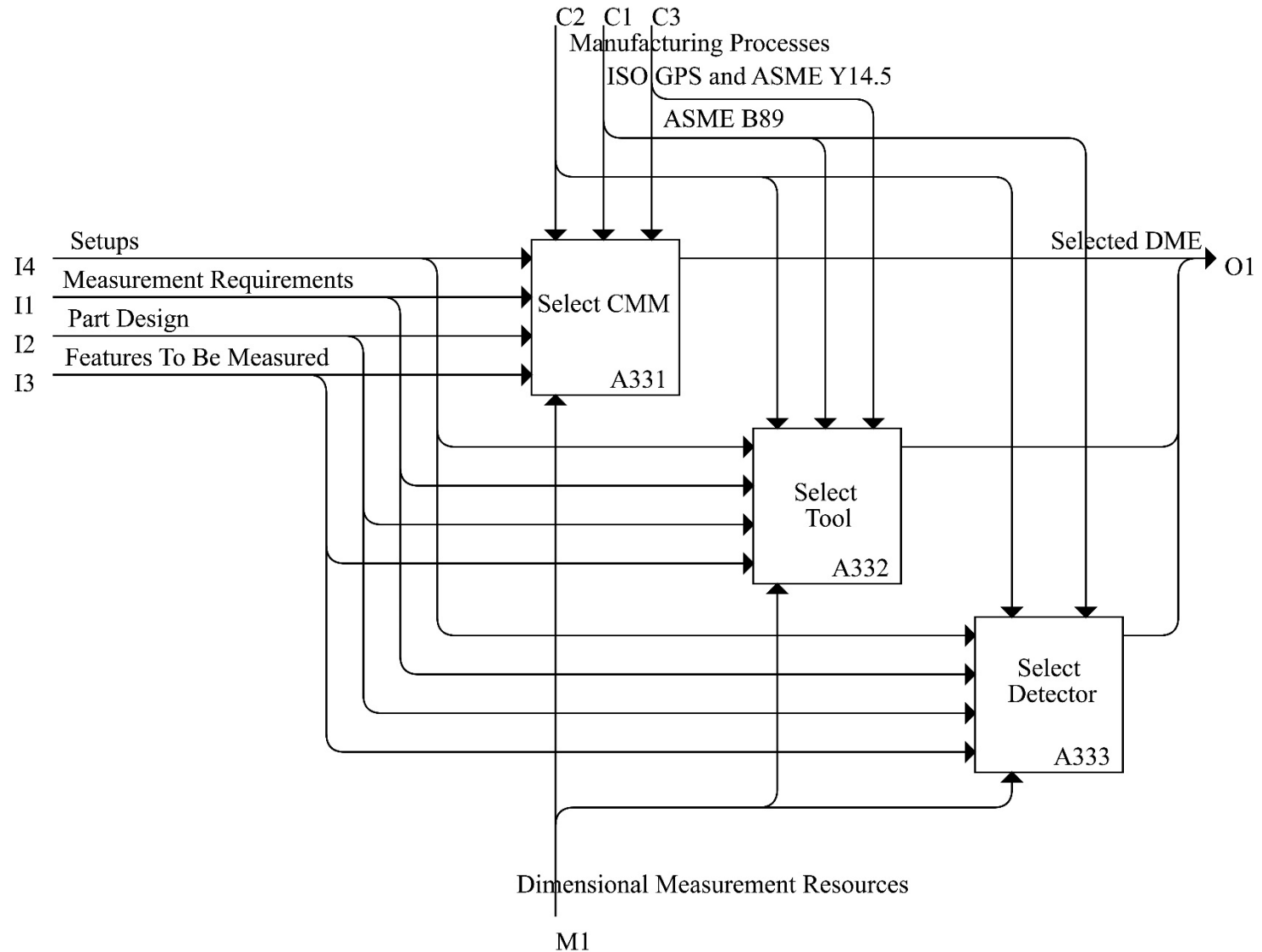
Determine Accessibility and Setups



Select Dimensional Measurement Equipment



Select Coordinate Measuring Machine



Example Rule Types – General Rules

| | |
|--------------------------|--|
| Equipment capability (C) | $C = \text{Tightest Tolerance} / \text{MPE (Max Permissible Error)}$ |
| Examples | $C \geq 10$ (Recommended) $C \geq 4$ (OK) |

| | |
|------------------------------|--|
| Work Volume Requirement (WR) | $WR_x = \text{Equipment Work Volume in X} / \text{Workpiece Space in X}$ $WR_y = \text{Equipment Work Volume in Y} / \text{Workpiece Space in Y}$ $WR_z = \text{Equipment Work Volume in Z} / \text{Workpiece Space in Z}$ |
| Examples | $WR_x \geq 1.5$ AND $WR_y \geq 1.5$ AND $WR_z \geq 1.5$ |

| | |
|--------------------------------|--|
| Probe Tip Accessibility (PT) | $PT = \text{Smallest Internal Feature Size} / \text{Probe Tip Size}$ e.g., $PT = \text{SmallestHoleDiameter} / \text{TipEndDiameter} \geq 2$ |
| Stylus Accessibility (SA) | $SA = \text{Stylus Length} / \text{Length of the Deepest Internal Feature}$ e.g., $SA = \text{Stylus Length} / \text{Length of the Deepest Hole} \geq 1.5$ |
| Orientation Accessibility (OA) | $OA \text{ in the XY plane} = \text{Probe Reachable Orientation in XY} >$ $\text{Most Slant Feature Orientation in XY}$ Similarly, OA in the YZ plane and in the ZX plane e.g., $OA \text{ in XY} = \text{Probe Reachable Orientation (45 deg)} >$ $\text{Most Slant Hole (20 deg)}$ |

Example Rule Types – General Rules

| | |
|--------------------------------------|--|
| Working Environment Temperature (TR) | TR should be kept in a range e.g., TR = 22 deg C +/- 0.5 deg C |
| Working Environment Humidity (HR) | HR should be kept in a range e.g., HR = 1 g/cubic meter +/- 0.1 g/cubic meter |

| | |
|------------------------|---|
| Surface Roughness (SR) | SR <= UserDefinedSR e.g., SR <= 100 micro meter (Sa) |
|------------------------|---|

| | |
|---------------------------|--|
| Surface Reflectivity (RF) | RF <= UserDefineMaximumSurfaceReflectivity RF >= UserDefineMinimumSurfaceReflectivity |
|---------------------------|--|

Example Rule Types – Specific Rules

Tactile probe selection

| | |
|-----------------|--|
| IF (Conditions) | PT >= UserDefinedPT AND SA >= UserDefinedSA AND OA >= UserDefinedOrientation |
| THEN (Actions) | Select ((FixedTactileProbe or IndexableTactileProbe) AND (StraightStylus or StarStylus) AND (BallTip or CylindricalTip or ConicalTip)) |

Nontactile probe selection

| | |
|-----------------|--|
| IF (Conditions) | RF >= UserDefinedMinimumRF AND RF <= UserDefinedMaximumRF |
| THEN (Actions) | Select (LaserTriangulationProbe OR CCDCamera OR StructuredLightSensor OR ConfocalChromaticSensor OR CapacitiveSensor) |

Example Rule Types – Specific Rules

CMM selection

| | |
|-----------------|---|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC AND PT >= UserDefinedPT AND SA >= UserDefinedSA AND OA > UserDefinedOA AND TR >= UserDefinedTR AND HR >= UserDefinedHR AND LT < UserDefinedLT AND MT < UserDefinedMT AND A == UserDefinedA AND SR <= UserDefinedSR AND RF >= UserDefinedMinimumRF AND RF <= UserDefinedMaxumumRF |
| THEN (Actions) | Select TypeofCMM AND (ToolwithDetachableSensor or ToolwithIntegralSensor) AND (TactileProbe or NontactileSensor) |

Example Rule Types – Specific Rules

Gage selection for Direct Linear Measurement

| | |
|-----------------|---|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC |
| THEN (Actions) | Select (ULM OR Micrometer OR BoreGage or OpticalComparator) |

Optical Gage selection for Direct Angular Measurement

| | |
|-----------------|---|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC |
| THEN (Actions) | Select (Autocollimator OR SineBar or OpticalComparator) |

Example Rule Types – Specific Rules

Direct-tolerance verification device selection

| | |
|-----------------|---|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC |
| THEN (Actions) | Select (Go/No-GoGage or OpticalComparator) |

Example Rule Types – Specific Rules

Surface defect inspection instrument selection

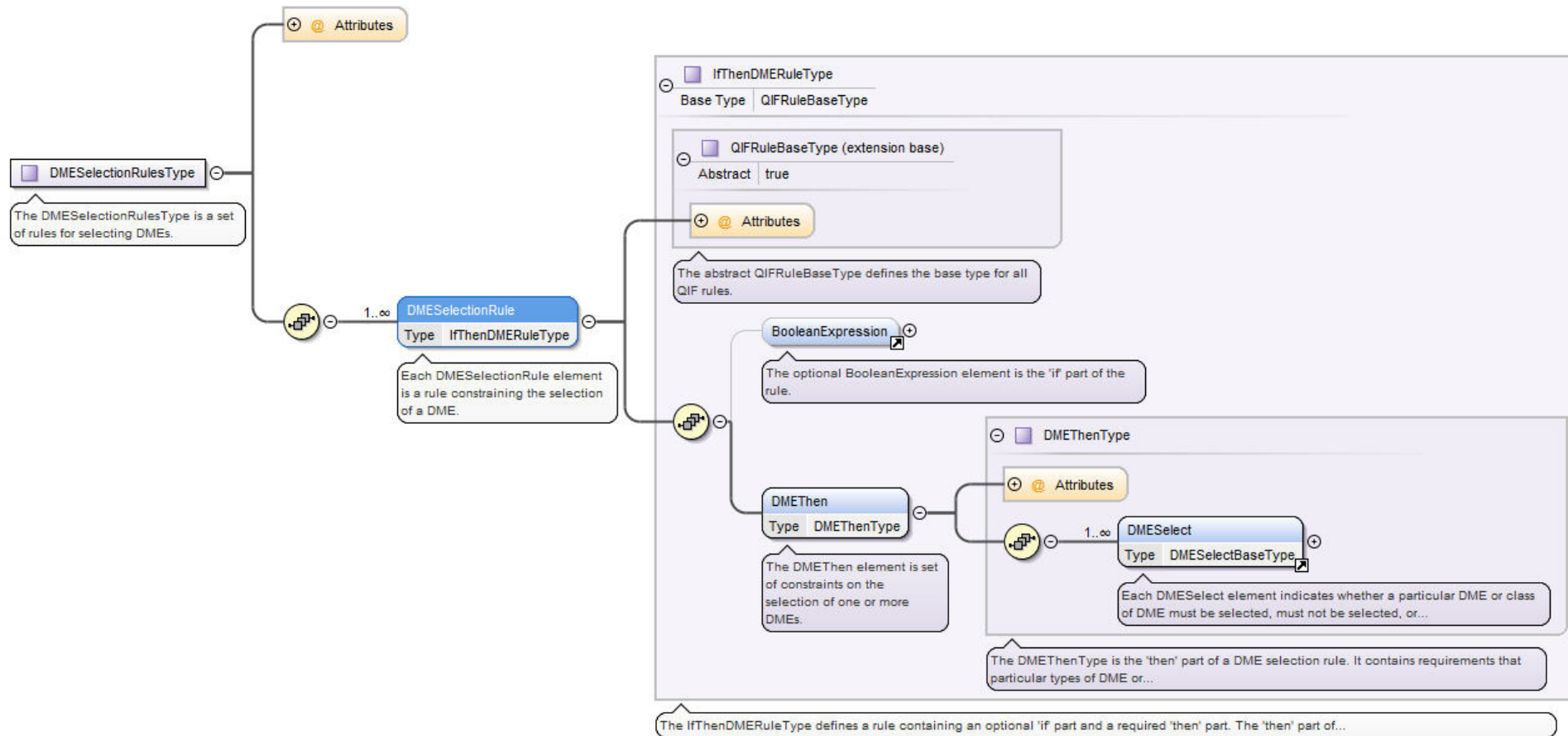
| | |
|-----------------|--|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC AND LT < UserDefinedLT AND MT < UserDefinedMT AND A == UserDefinedA |
| THEN (Actions) | Select (SpecificSurfaceDefectDetectionInstrument) |

Beneath surface defect inspection instrument selection

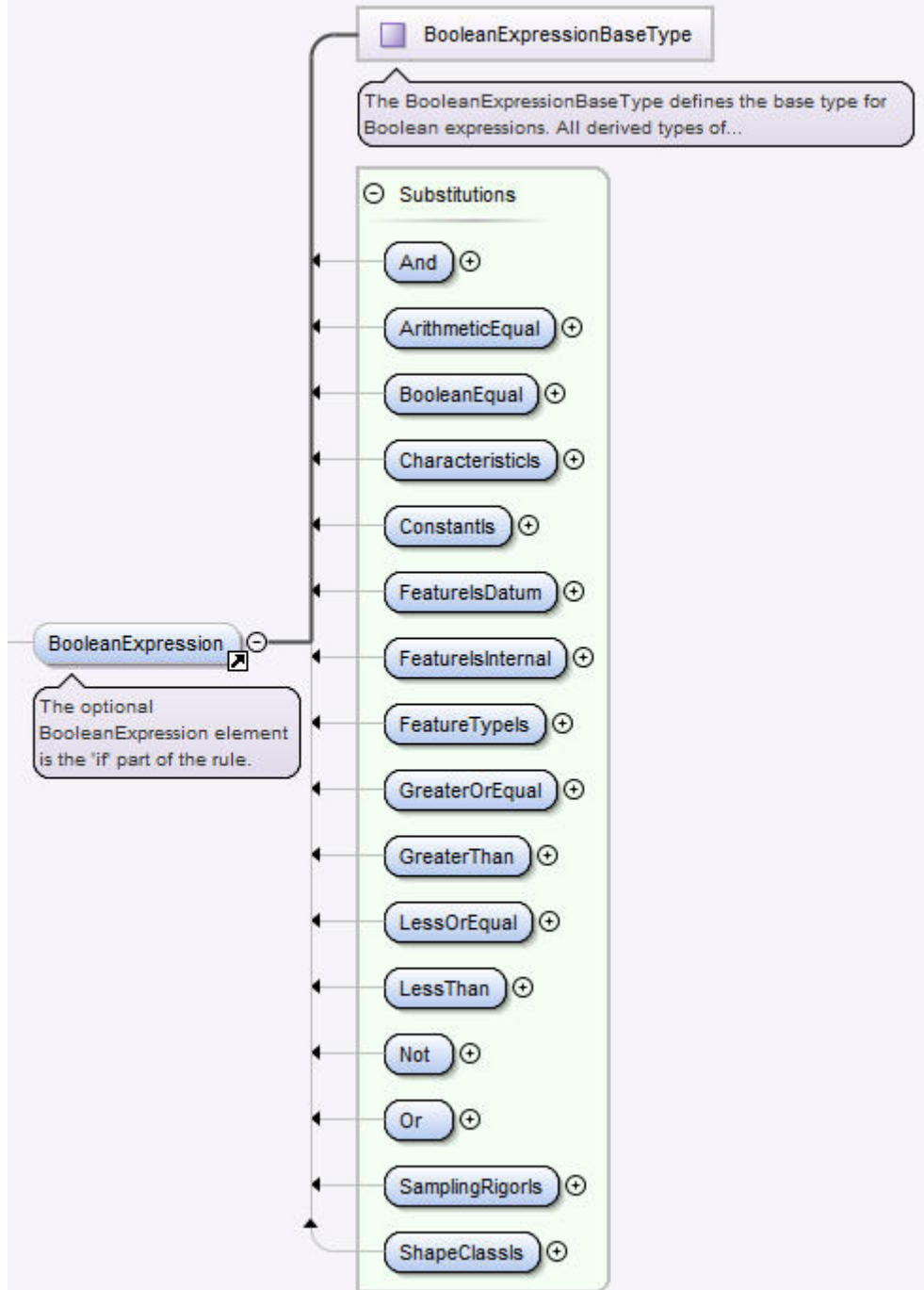
| | |
|-----------------|--|
| IF (Conditions) | C >= UserDefinedC AND WR >= UserDefinedWR AND IC == UserDefinedIC AND LT < UserDefinedLT AND MT < UserDefinedMT AND A == UserDefinedA |
| THEN (Actions) | Select (SpecificBeneathSurfaceDefectDetectionInstrument) |

Implemented QIF Rules XML Schema

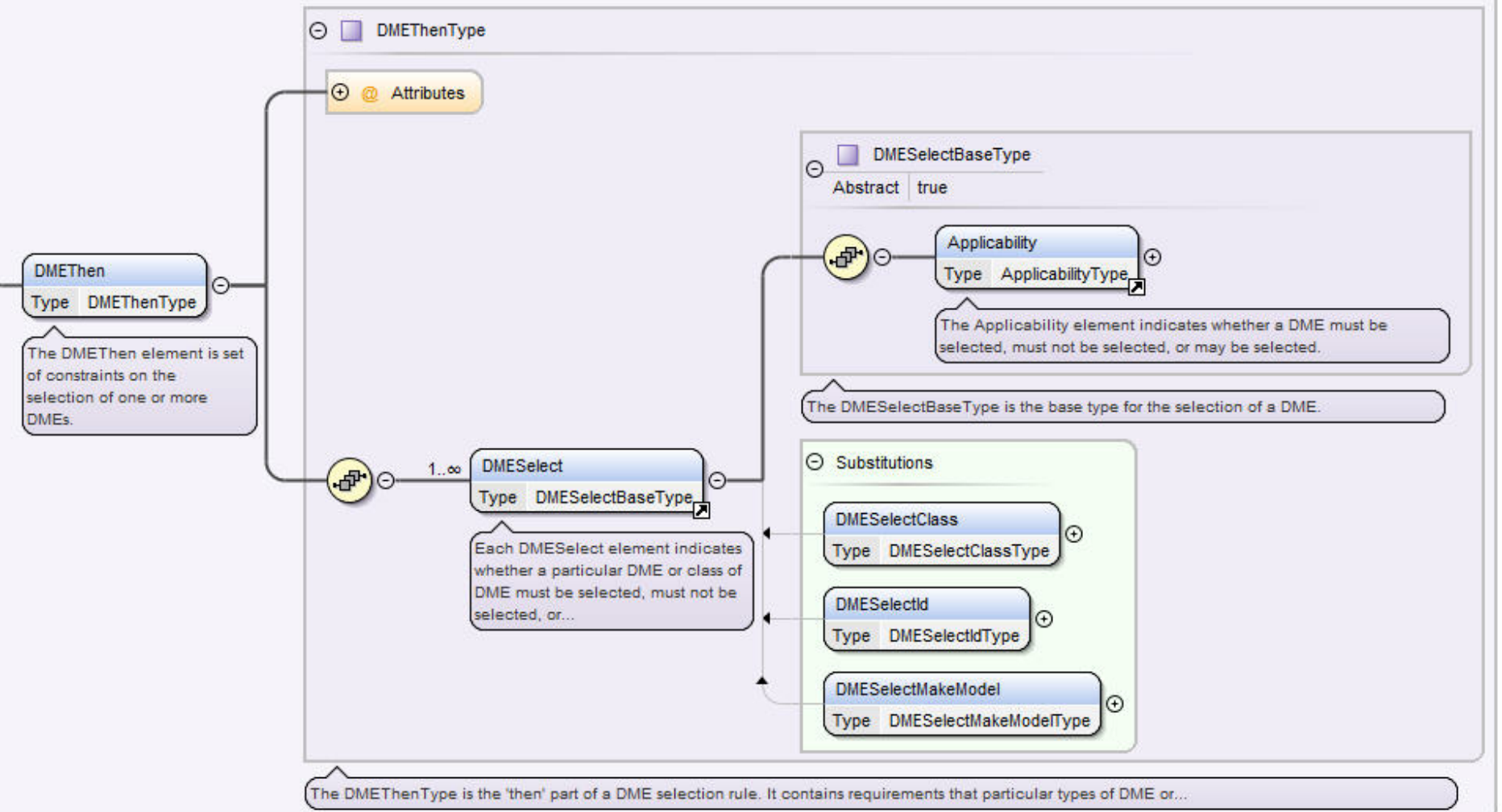
DMESelectionRulesType



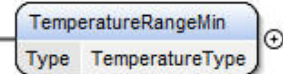
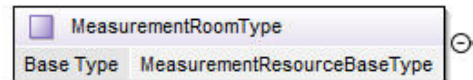
DMEBoolean



DMEThen



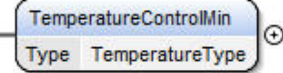
Measurement Room



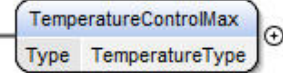
The TemperatureRangeMin element gives the minimum temperature that the room can maintain while staying within the...



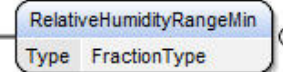
The TemperatureRangeMax element gives the maximum temperature that the room can maintain while staying within the...



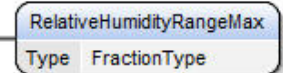
This is an amount below any in-range temperature that the room is guaranteed not exceed. This must be a positive value.



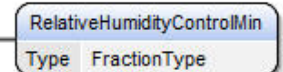
This is an amount above any in-range temperature that the room is guaranteed not exceed.



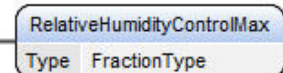
The RelativeHumidityRangeMin element gives the minimum relative humidity that the room can maintain while staying...



The RelativeHumidityRangeMax element gives the maximum relative humidity that the room can maintain while staying...

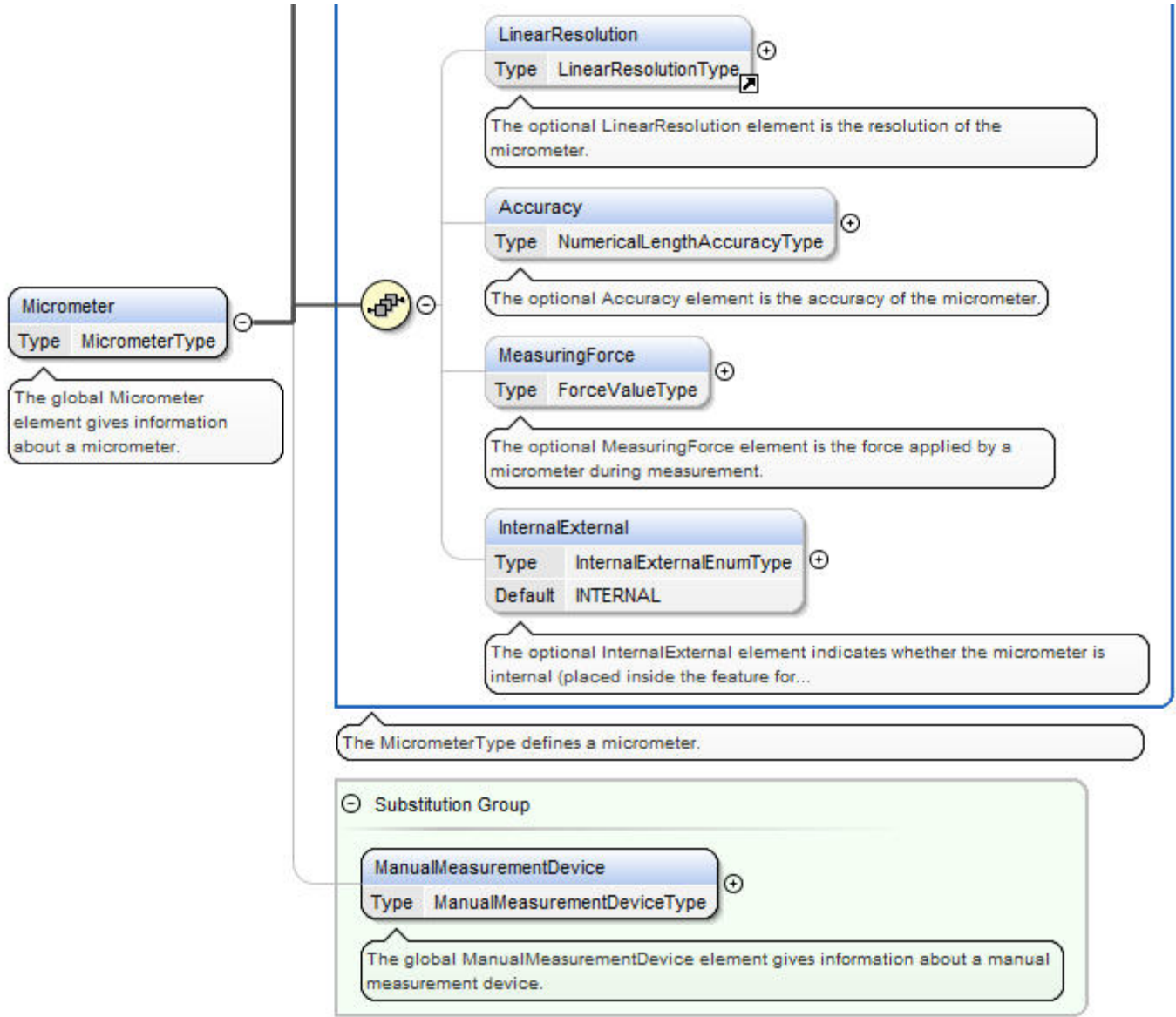


This is an amount below any in-range relative humidity that the room is guaranteed not exceed. This must be a positive...

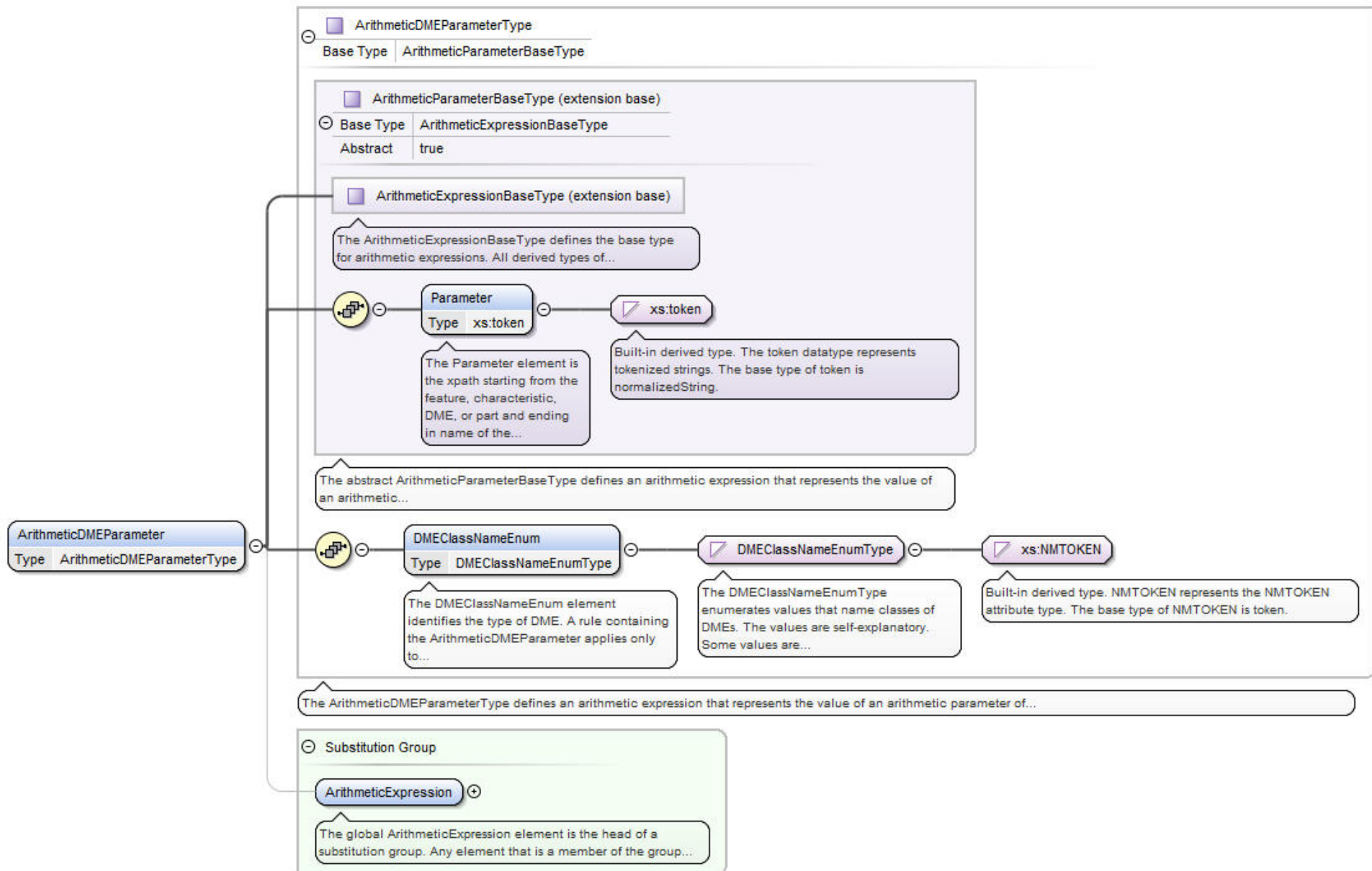


This is an amount above any in-range relative humidity that the room is guaranteed not exceed.

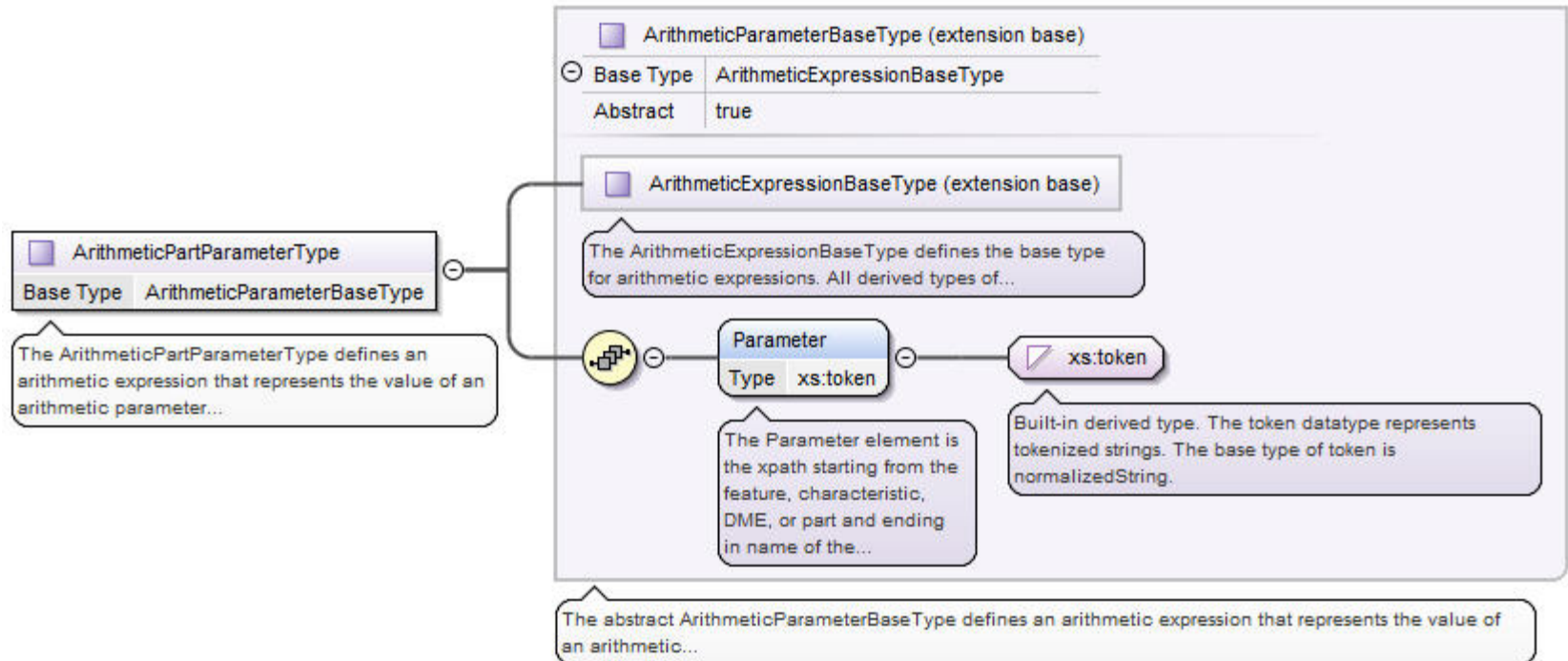
Micrometer



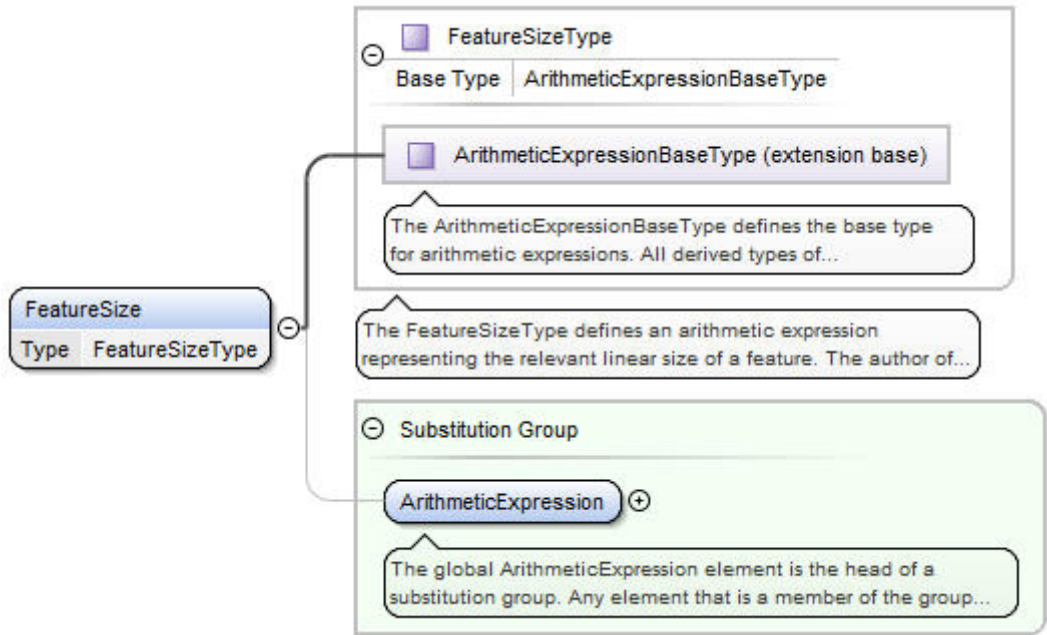
ArithmeticDMEParameter



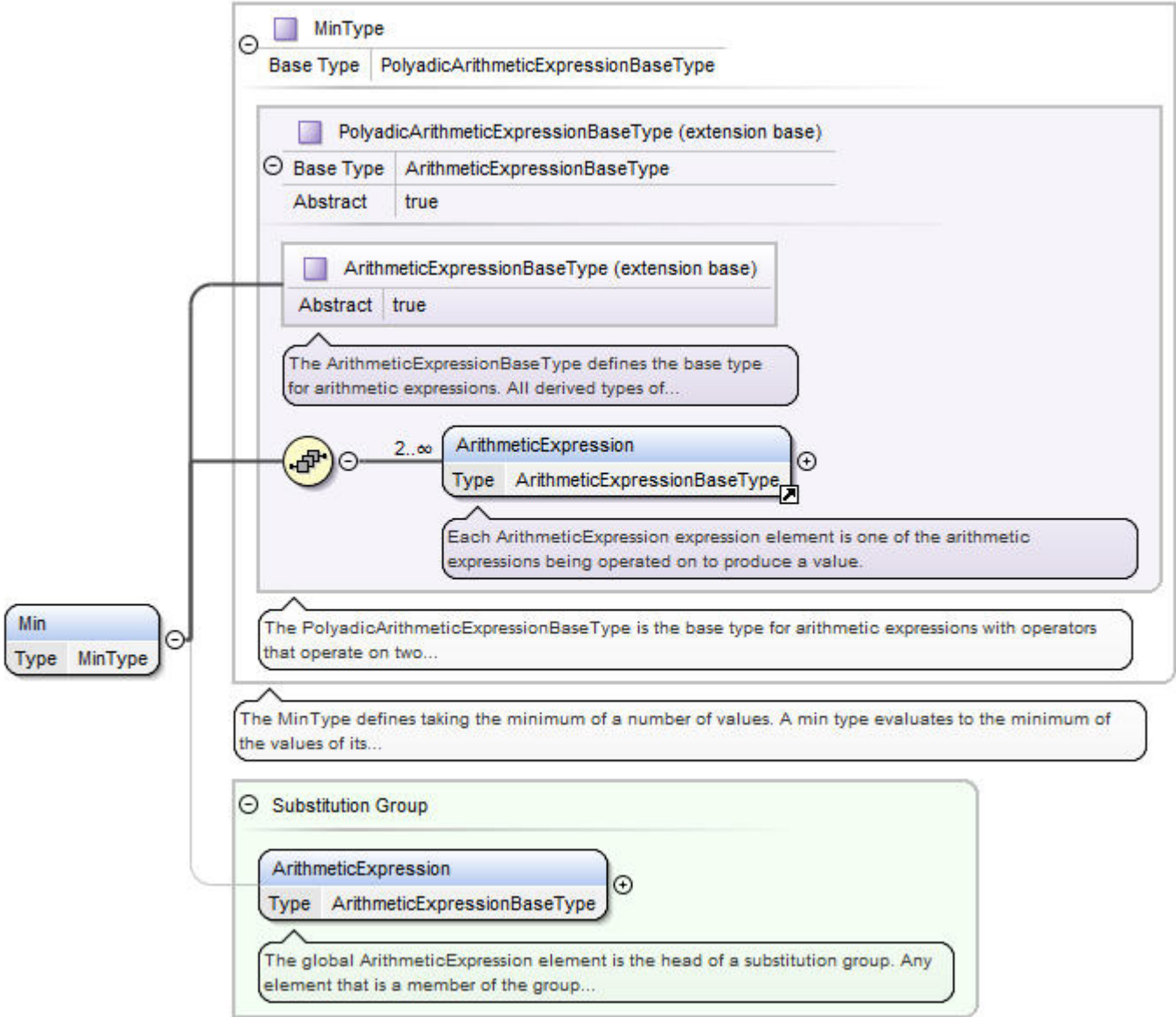
ArithmeticPartParameter



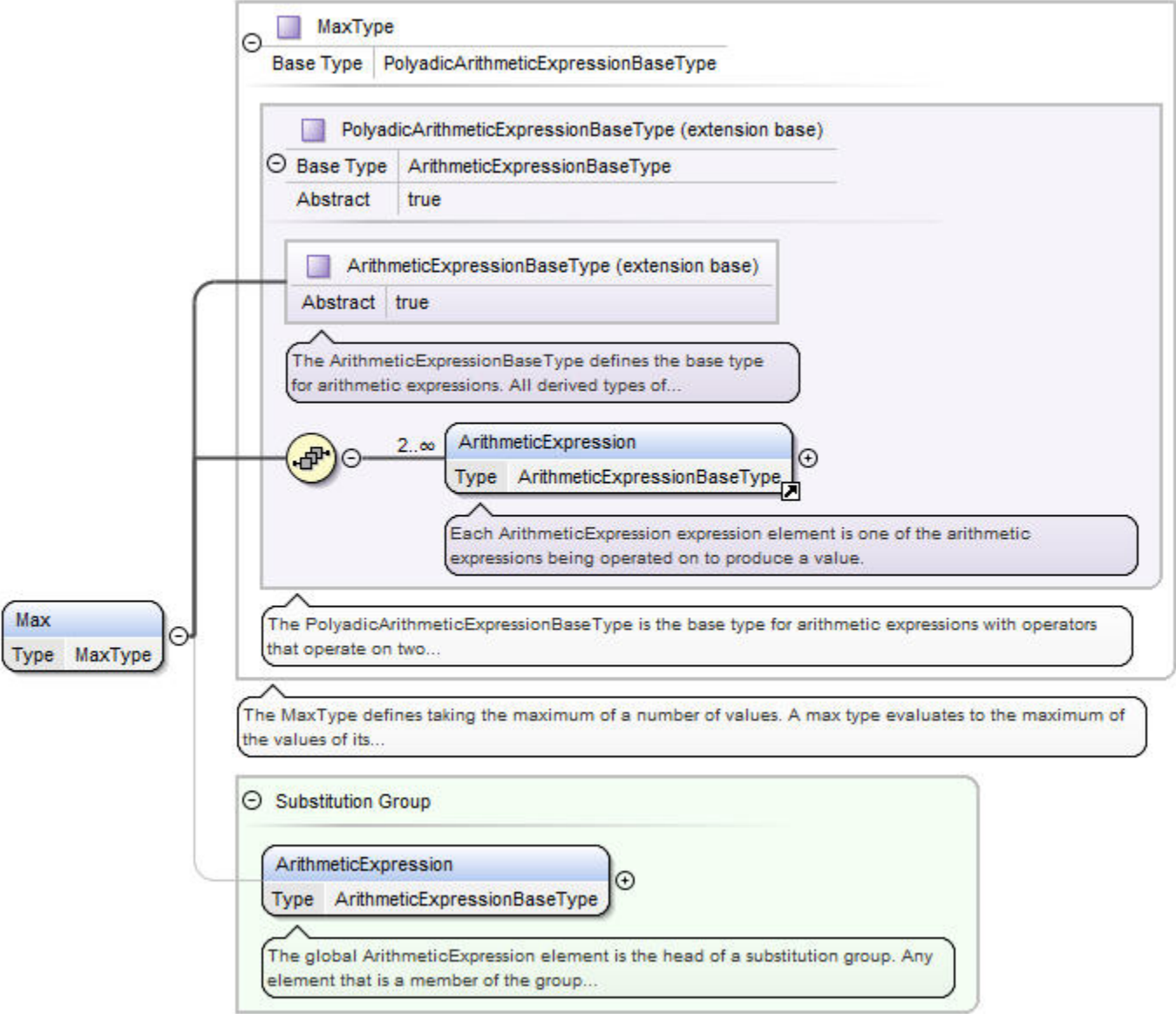
Feature Size



Min



Max



Instance

Example 1

<!--
DME resolution must be less than or equal to tolerance times 0.1.
(Rolls-Royce Guide, page 6, section 2.2.3, text)

This rule has no IF part

```
-->  
  <DMESelectionRule>  
<DMEMThen n="1">  
  <DMESelectClass>  
    <Must/>  
    <DMEClassName>ALLDMES</DMEClassName>  
    <ParameterConstraints n="1">  
      <DMEParameterConstraint>  
<ParameterName>Resolution</ParameterName>  
<Comparison>LESSOREQUAL</Comparison>  
<Times>  
  <ArithmeticConstant val="0.1"/>  
  <ArithmeticCharacteristicParameter>  
    <Parameter>Tolerance</Parameter>  
  </ArithmeticCharacteristicParameter>  
</Times>  
</DMEParameterConstraint>  
</ParameterConstraints>  
</DMESelectClass>  
</DMEMThen>  
</DMESelectionRule>
```

Instance Example 2

```
<!--
```

```
If the characteristic is thickness, then a micrometer may be used.  
(Rolls-Royce Guide, page 7, Equipment Selection table)
```

```
-->
```

```
<DMESelectionRule>
```

```
<Characteristics val="THICKNESS"/>
```

```
<DMEMThen n="1">
```

```
<DMESelectClass>
```

```
<May desirability="1"/>
```

```
<DMEClassName>MICROMETER</DMEClassName>
```

```
</DMESelectClass>
```

```
</DMEMThen>
```

```
</DMESelectionRule>
```

Instance Example

3

```
<!-- If Equipment Effective Working Volume >= Part Bounding Box Volume * 1.5 Then a Universal Device may be
selected.-->
<DMSElectionRule>
<GreaterOrEqual>
  <Times>
    <ArithmeticDMEParameter>
      <Parameter>CartesianWorkingVolume/XAxisLength</Parameter>
      <DMEClassNameEnum>UNIVERSAL_DEVICE</DMEClassNameEnum>
    </ArithmeticDMEParameter>
    <ArithmeticDMEParameter>
      <Parameter>CartesianWorkingVolume/YAxisLength</Parameter>
      <DMEClassNameEnum>UNIVERSAL_DEVICE</DMEClassNameEnum>
    </ArithmeticDMEParameter>
    <ArithmeticDMEParameter>
      <Parameter>CartesianWorkingVolume/ZAxisLength</Parameter>
      <DMEClassNameEnum>UNIVERSAL_DEVICE</DMEClassNameEnum>
    </ArithmeticDMEParameter>
  </Times> <Times>
    <ArithmeticConstant val="1.5"/>
    <ArithmeticPartParameter>
      <Parameter>PartFamily/MinimumBoundingBox/Length</Parameter>
    </ArithmeticPartParameter>
    <ArithmeticPartParameter>
      <Parameter>PartFamily/MinimumBoundingBoxWidth</Parameter>
    </ArithmeticPartParameter>
    <ArithmeticPartParameter>
      <Parameter>PartFamily/MinimumBoundingBoxHeight</Parameter>
    </ArithmeticPartParameter>
  </Times>
</GreaterOrEqual>
<DMEMThen n="1">
  <DMESelectClass> <May/> <DMEClassName>UNIVERSAL_DEVICE</DMEClassName>
</DMESelectClass>
</DMEMThen>
</DMSElectionRule>
```

Conclusions & Future Work

- Activity modeling is an effective way for identifying activities, inputs, controls, mechanism, and outputs for determining characteristics/features to be measured.
- The new DME Selection Rule Types should meet the needs of users to share DME selection rules among heterogenous systems.
- Pilot implementations of the model are undergoing. Feedback will be provided to the QIF Rules Working group.



QIF Rules Information Model and Schema v3.0 (draft)

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