



**DRS**

*TECHNOLOGIES*

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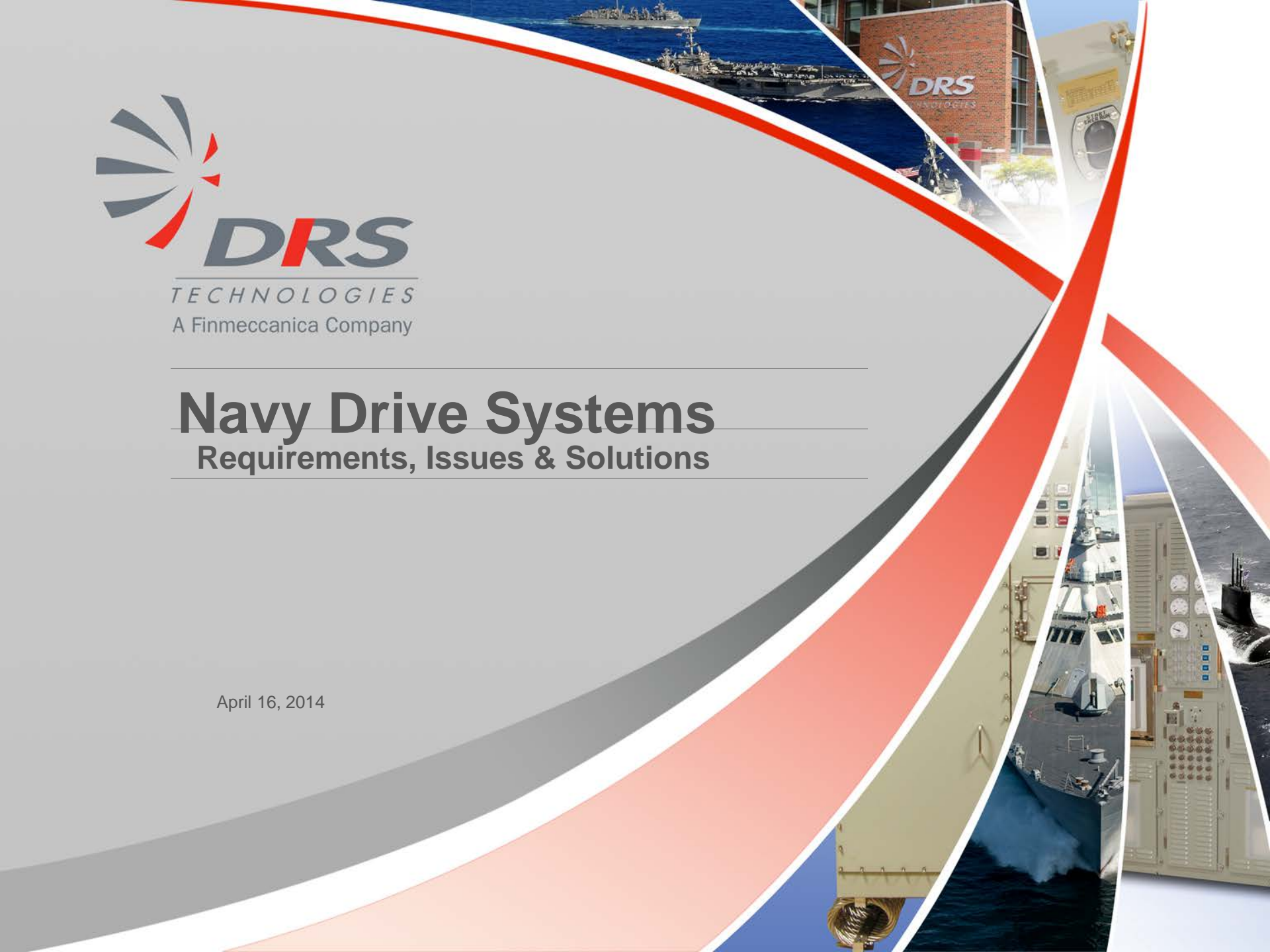
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# Navy Drive Systems

## Requirements, Issues & Solutions

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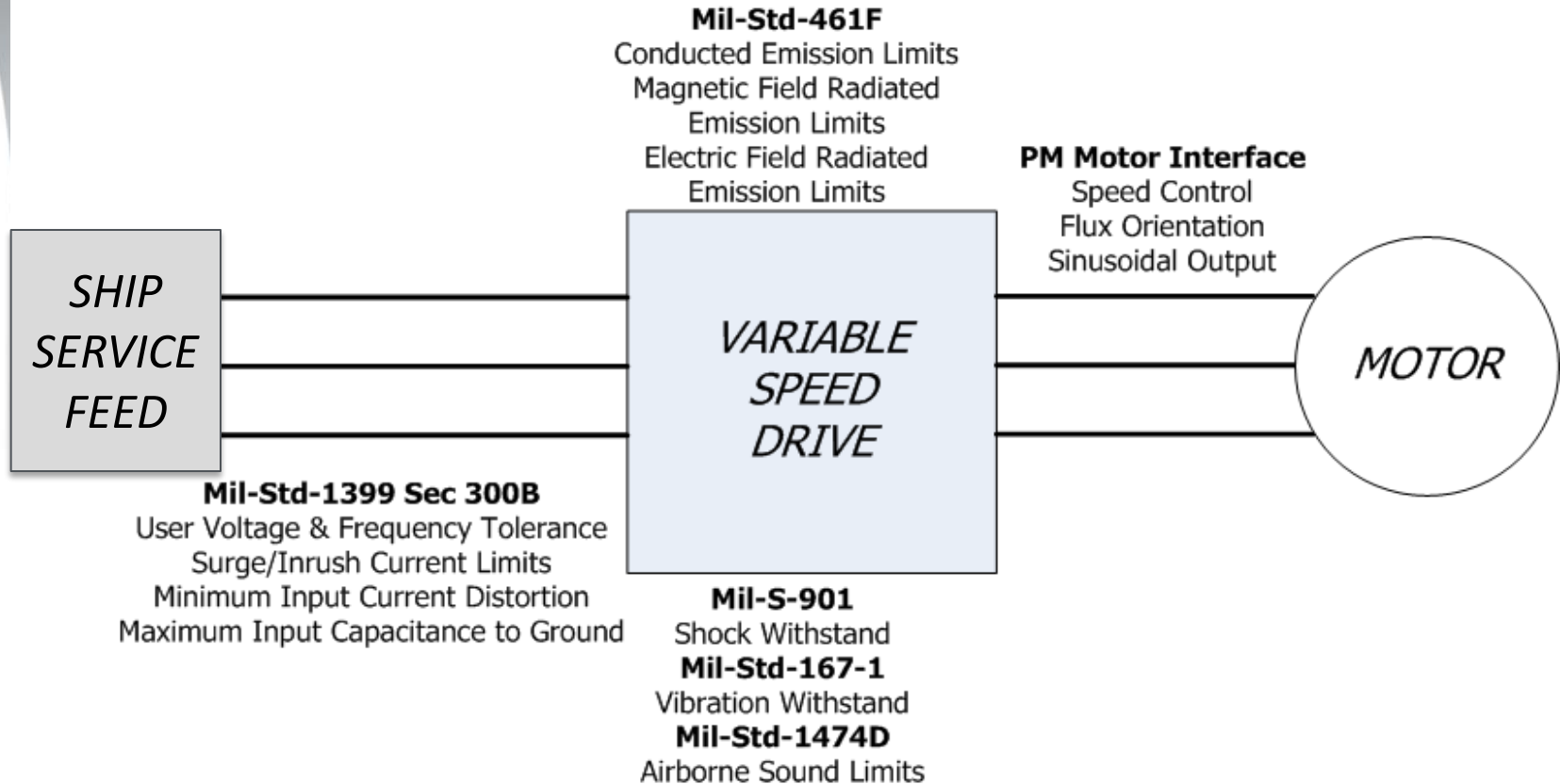
April 16, 2014



## *OVERVIEW*

- ✦ **Shipboard Variable Speed Drive (VSD) System Requirements**
  
- ✦ **High HP VSD Solution Drivers:**
  - **Gaps and Dilemmas**
  
- ✦ **Previous and Future VSD Solutions**

# SHIPBOARD INTERFACE REQUIREMENTS



## ***HIGH HP VSD SOLUTION DRIVERS***

### **✦ Power Density**

- For retro-fit solutions, must fit into the existing space
- For new platforms space is limited

### **✦ Motor Load**

- Permanent Magnet Motor is more power dense
- Low leakage inductance
  - Good from a power density perspective
  - Bad from the perspective that it drives high power quality requirements into the motor
- Voltage level
  - High voltage drives significant risk and qualification costs
  - Insulation system needs to be over-designed for the rating
  - Lower voltage through >3 phase or multi-level VSD strategies puts cost and reliability burden on the VSD

## ***HIGH HP VSD SOLUTION DRIVERS (CONT.)***

### **✦ Ship Service Power Interface**

- **Must meet high input power quality (IHD<3%)**
- **Must withstand large input voltage fluctuations without impacting down-stream processes**
- **Multi-Pulse Transformer-Rectifier solution impacts power density**
- **Active front-end solution adds significantly to VSD cost and increases the conducted and radiated EMI (which must be mitigated)**

### **✦ Environment**

- **Shock/Vibration mitigation requires mil-hardened design or “cocooning” of commercial solutions**
- **Temperature usually drives the VSD design more than the motor design**
- **Availability of Water cooling**
  - **Drives need for “cocooning” to provide self-contained controllable environment**
  - **A water-cooled motor is a costly, custom design**
  - **Imposes requirement on shipboard auxiliaries that impacts every aspect of shipboard system design and CONOPS**

## ***HIGH HP VSD SOLUTION DRIVERS (CONT.)***

### **☼ Serviceability**

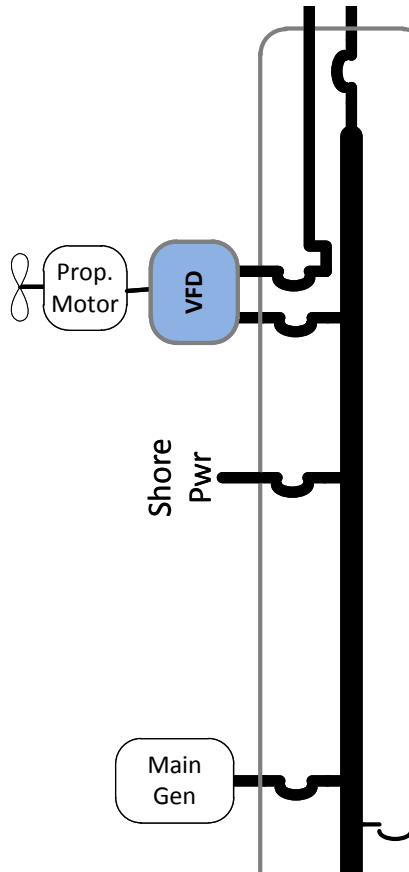
- **Obsolescence of replacement parts**
- **Identification of the Lowest Replaceable Unit (LRU)**
- **Modular multi-phase VSD designs are desirable but impose significant cost and reduce power density**
- **Fault tolerant VSD and motor combination a plus**
- **VSD MTBF becomes an unexpected cost**
  - **Often missed in the proposal stage**
  - **Must be verifiable in terms of existing norms**
  - **The Navy should adopt new paradigms that allow for technology advancements in how reliability is managed**

### **☼ Cost**

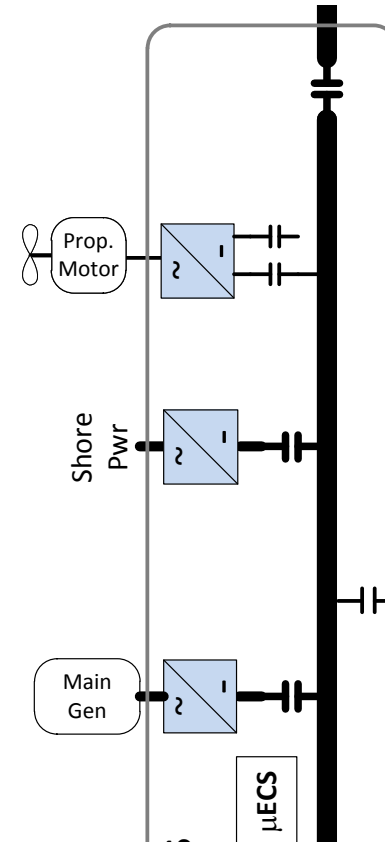
- **External pressures to reduce spending favor COTS solutions and overshadows compliance during procurement phase**
- **COTS solutions generally fall short in meeting shipboard requirements**
- **VSDs often “get a black eye” because of high integration costs:**
  - **Lack of system integration experience by the VSD supplier**
  - **Lack of Navy shipboard experience with power conversion**
  - **Unexpected and missed requirements**

# VSD VS. NEXT GENERATION INTEGRATED POWER SYSTEMS

## MVAC Fed Architecture



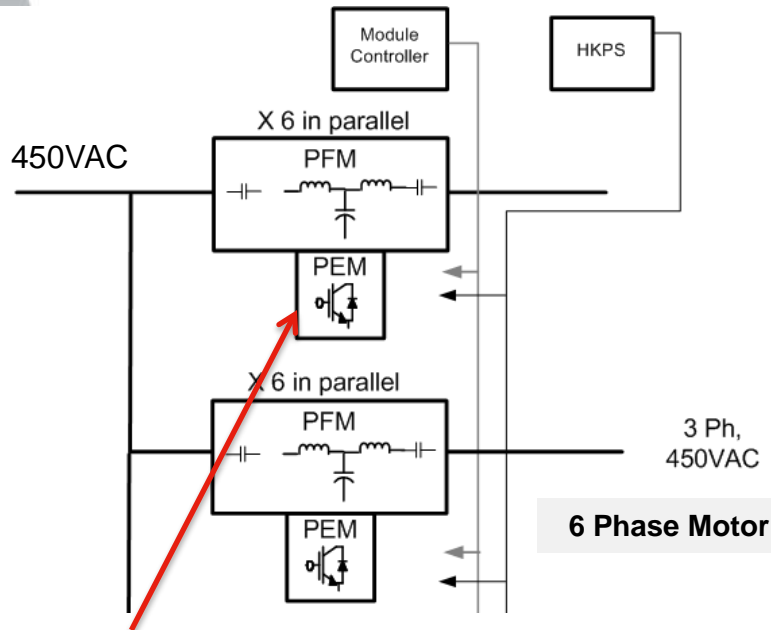
## MVDC Fed Architecture



# PRIOR HIGH POWER VSD SOLUTIONS

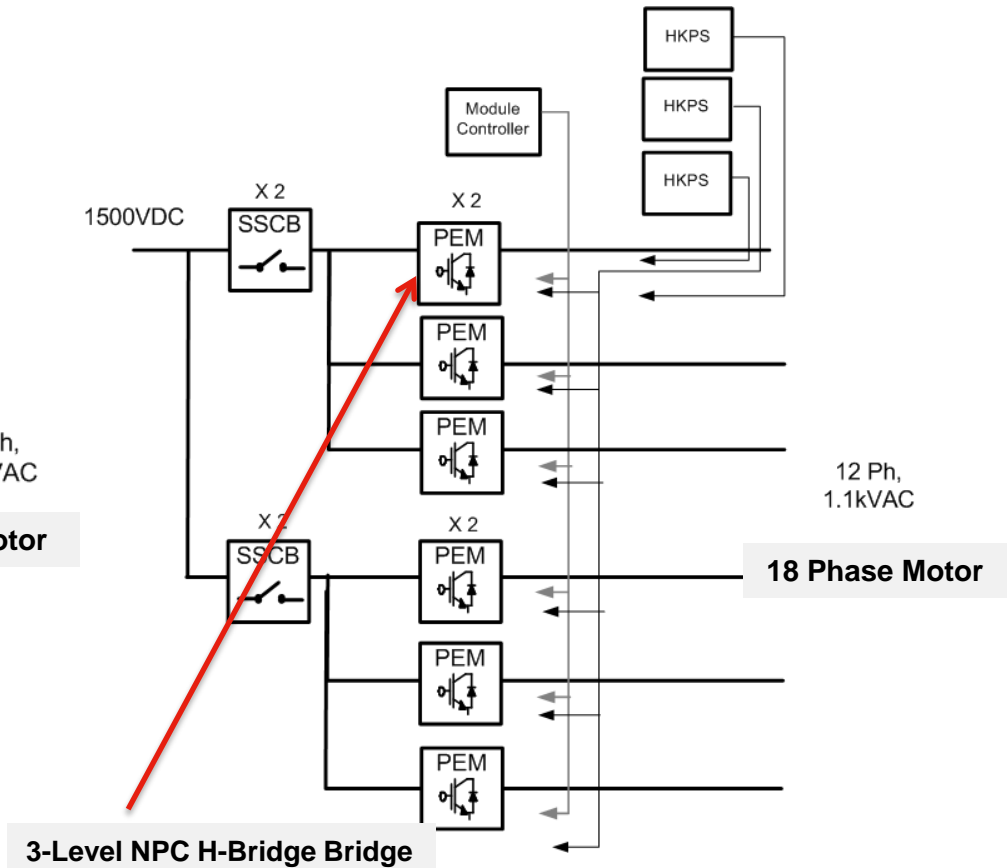
## PM MOTOR VSD SYSTEMS

### Non-Isolated AC-Fed



3-Level 3-Phase NPC Bridge

### DC-Fed

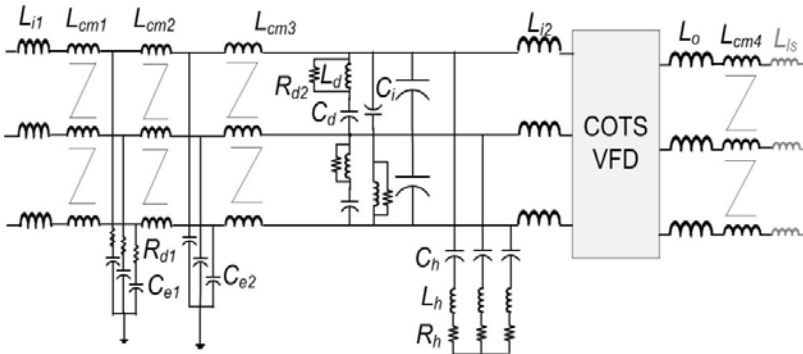




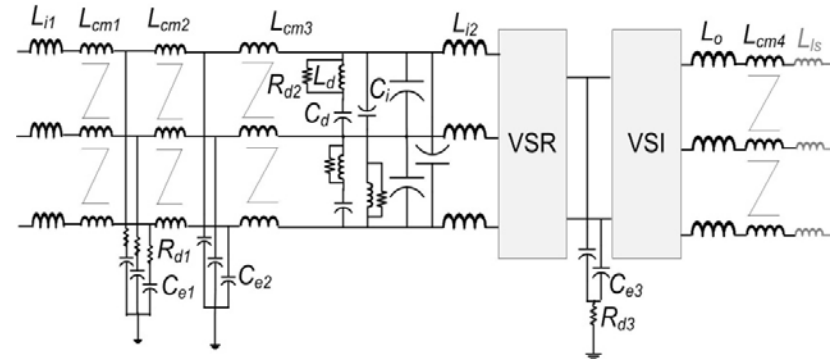
## ***SHIPBOARD DRIVES DEVELOPMENT GOALS***

- ✦ Development of MIL compliance, platform based drives family to provide solutions which are cost effective and address the obsolescence issues for the Navy and DRS-PCT.
  - Utilizing the latest power electronics/control technologies
  - Utilizing next generation power semiconductor modules
  - Extend the technology to SiC
  
- ✦ Develop a technology platform in hardware and software for a high level of modularity and use common parts for cost reduction.

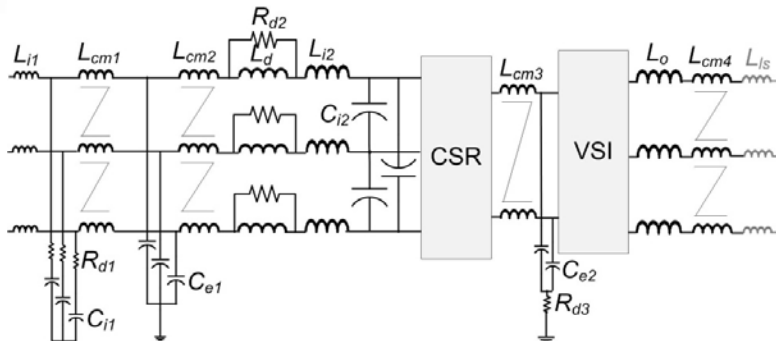
# NEXT GENERATION VSD SOLUTIONS: WHICH TOPOLOGY YIELDS LOWEST SIZE/WEIGHT/COST?



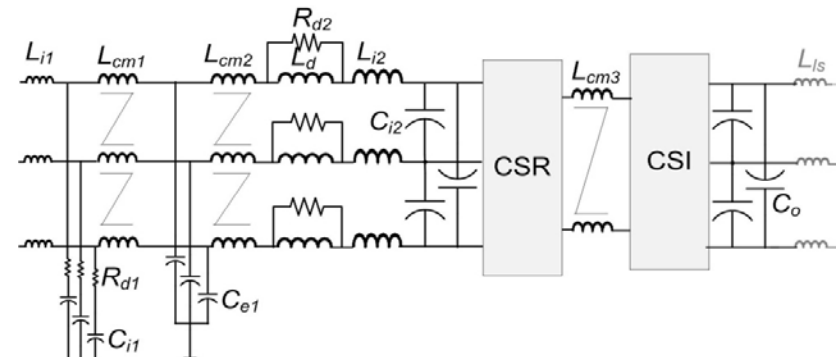
**“Cocooned” COTS VFD (Buck)**



**VSR-VSI (Boost-Buck)**



**CSR-VSI (Buck-Buck)**



**CSR-CSI (Buck-Boost)**

## ***NEXT GENERATION SHIPBOARD IPS CHALLENGES***

### ✦ MVDC (10-20kVDC) Platform:

- High voltage motor vs. cost of Solid State Transformer to reduce motor voltage
- Multi-Level VSD topologies
- Maximize device voltage rating vs. allowable switching frequency (>5kHz is desirable)

### ✦ MVAC (13.8kVAC) Platform:

- Focus technology on transformer-rectifier front end design
- With appropriate focus on AC interfaces, risks in VSD topology can be reduced

### ✦ Legacy (450VAC, 4160VAC) Platforms:

- Ship service feed compatibility
- Cost vs. compliance vs. performance