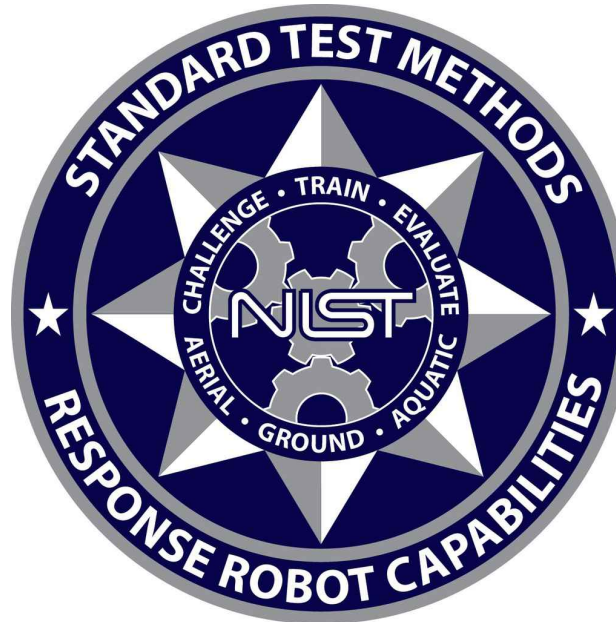


Sensor Tests

Ground Robots

Version 2020C



Test Director:

Adam Jacoff

Intelligent Systems Division
National Institute of Standards and Technology
U.S. Department of Commerce

Sponsor:

Science and Technology Directorate
U.S. Department of Homeland Security

Internet
RobotTestMethods.nist.gov



Email
RobotTestMethods@nist.gov

Sensing: Visual Acuity Test

ASTM E2566-2017

MORE CONTINUOUS TARGETS

DIFFERENT LEVELS OF ACUITY

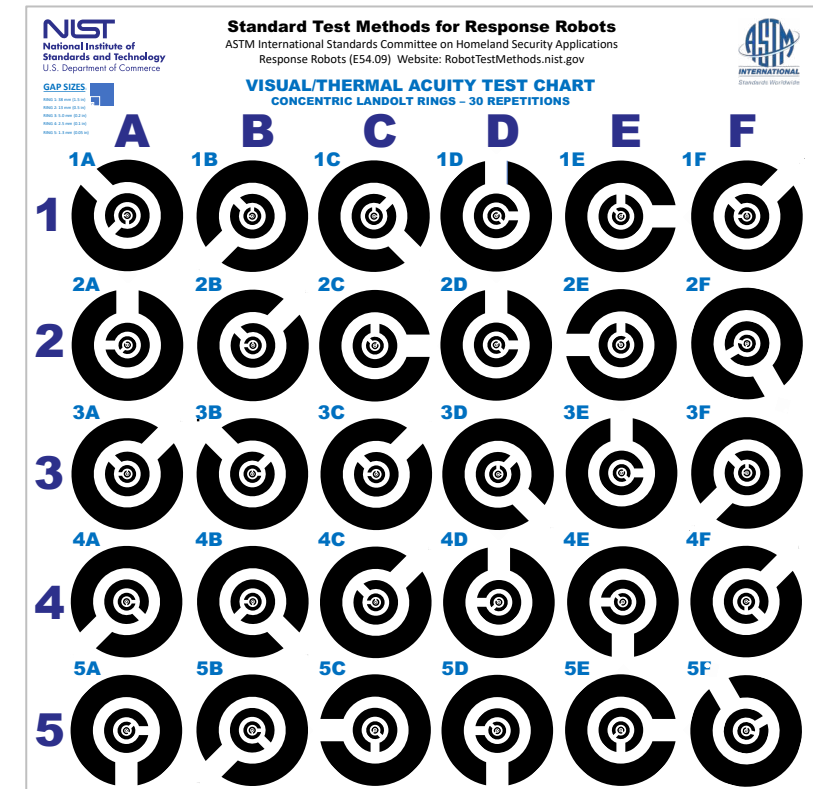
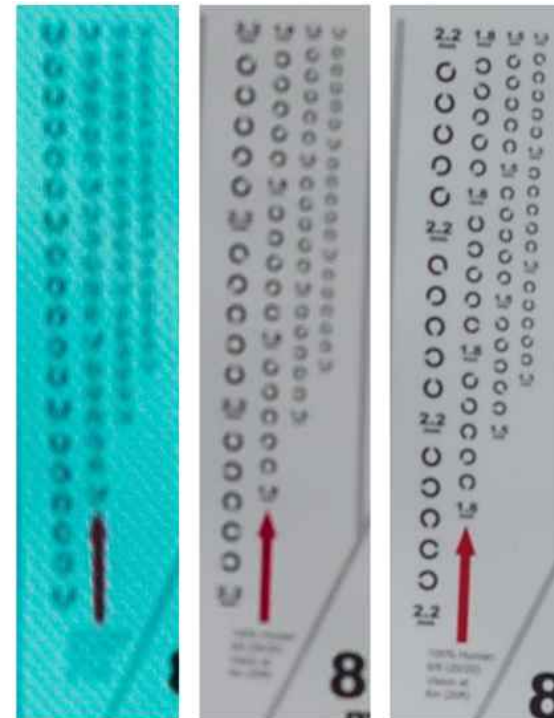
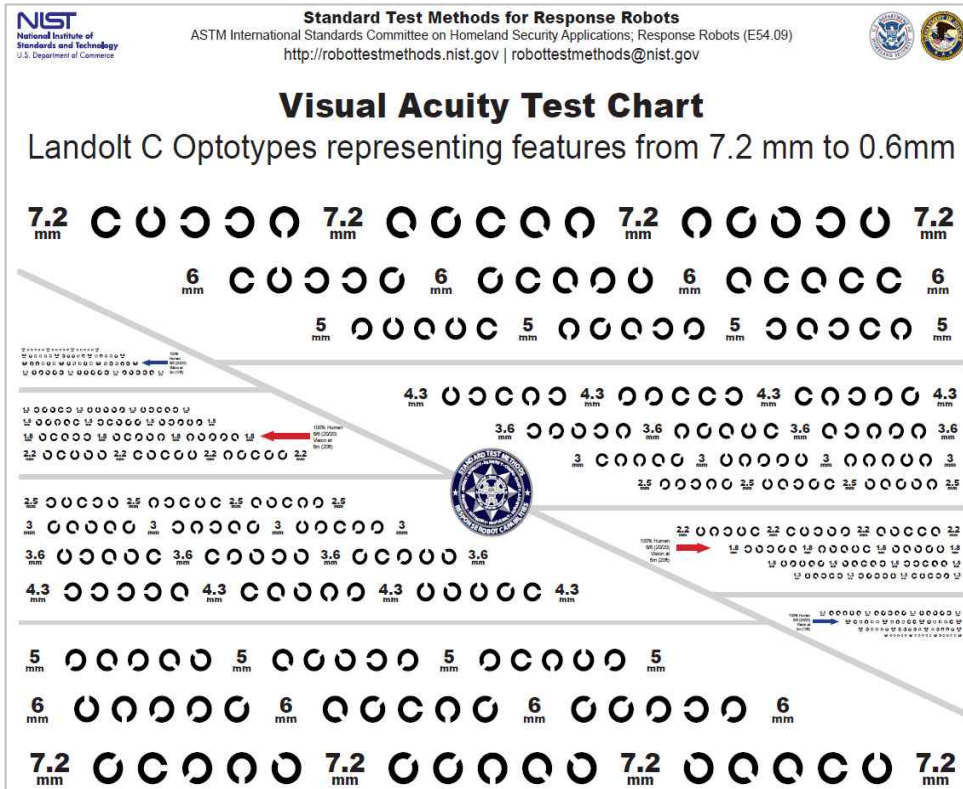
5 DEEP CONCENTRIC C TARGETS

Interface Streamed Recovered

LIVE

BETTER

BEST



Sensing: Color Acuity Test

ASTM WK54755

COLOR DOTS

ROTATING HAZMAT LABELS

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Standard Test Methods for Response Robots
ASTM International Standards Committee on Homeland Security Applications
Response Robots (E54.09) | <http://RobotTestMethods.nist.gov>

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Standards Worldwide

COLOR ACUITY TEST CHART
6 RANDOM HAZMAT LABEL COLORS - 30 REPETITIONS
Colors as specified in 49 CFR (Code of Federal Regulations) 172.407(d)

A

	A	B	C	D	E	F
1	1A	1B	1C	1D	1E	1F
2	2A	2B	2C	2D	2E	2F
3	3A	3B	3C	3D	3E	3F
4	4A	4B	4C	4D	4E	4F
5	5A	5B	5C	5D	5E	5F

Colors:
Red (hex: #E41A1C)
Orange (hex: #FF9933)
Yellow (hex: #FFFF00)
Green (hex: #33A02C)
Blue (hex: #3366CC)
Black

NIST
National Institute of
Standards and Technology
U.S. Department of Commerce

Standard Test Methods for Response Robots
ASTM International Standards Committee on Homeland Security Applications
Response Robots (E54.09) | <http://RobotTestMethods.nist.gov>

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HAZARDOUS MATERIAL LABEL TEST CHART
30 RANDOM, RANDOMLY ORIENTED 100 MM (4 IN) LABELS

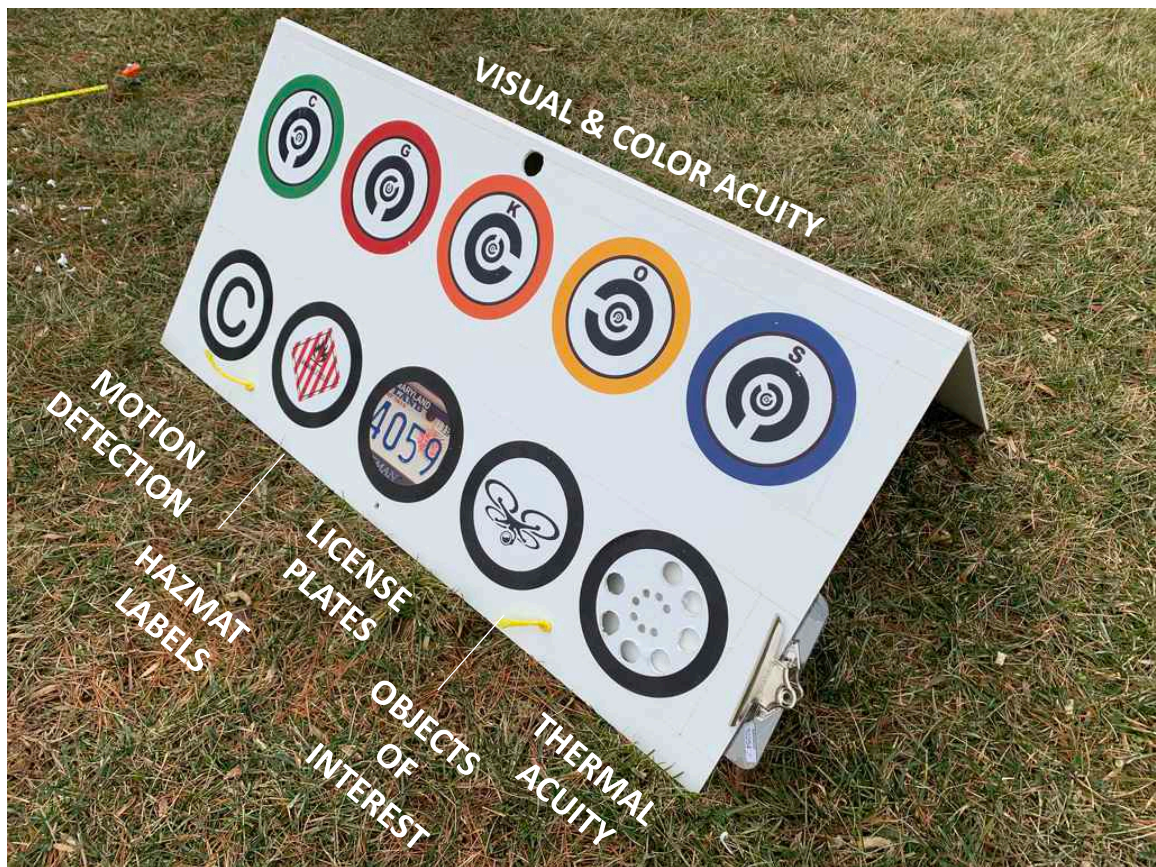
A

	A	B	C	D	E	F
1	1A	1B	1C	1D	1E	1F
2	2A	2B	2C	2D	2E	2F
3	3A	3B	3C	3D	3E	3F
4	4A	4B	4C	4D	4E	4F
5	5A	5B	5C	5D	5E	5F

Sensing: Point and Zoom Camera Test

ASTM WK33261

Visual, Color, Motion, Thermal, and Operationally Significant Objects



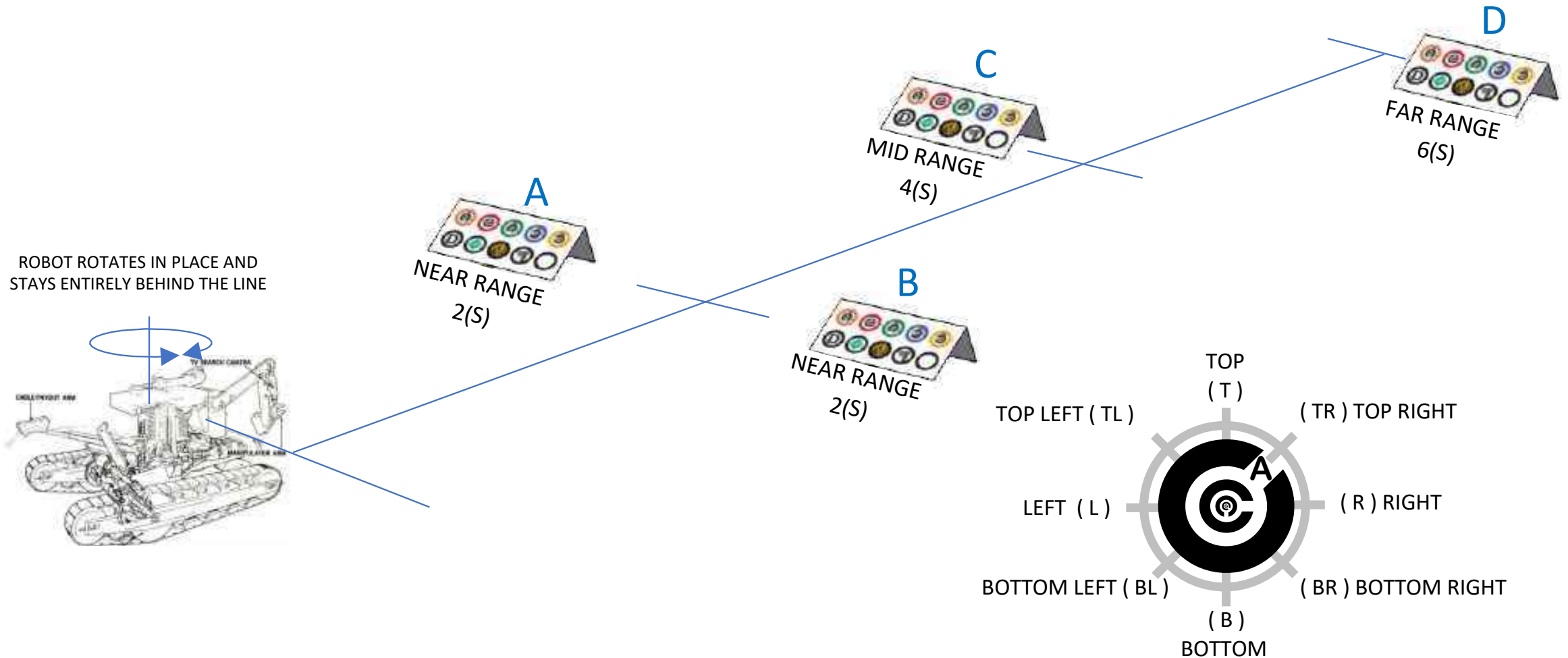
LICENSE
PLATES

OBJECTS OF
INTEREST

THERMAL
HAND WARMER

Sensing: Point and Zoom Camera Test

ASTM WK33261



Sensing: Point and Zoom Camera Test

ASTM WK33261

[WATCH MOVIE OF ASSEMBLY PROCESS HERE](#)



Thermal acuity circular hole patterns. The large holes are 1 inch diameter and small holes are 1/2 inch diameter. One of the 8 directions is missing, like the gap on the visual acuity targets. There is a sticker template to drill through in the Disk Insert file.

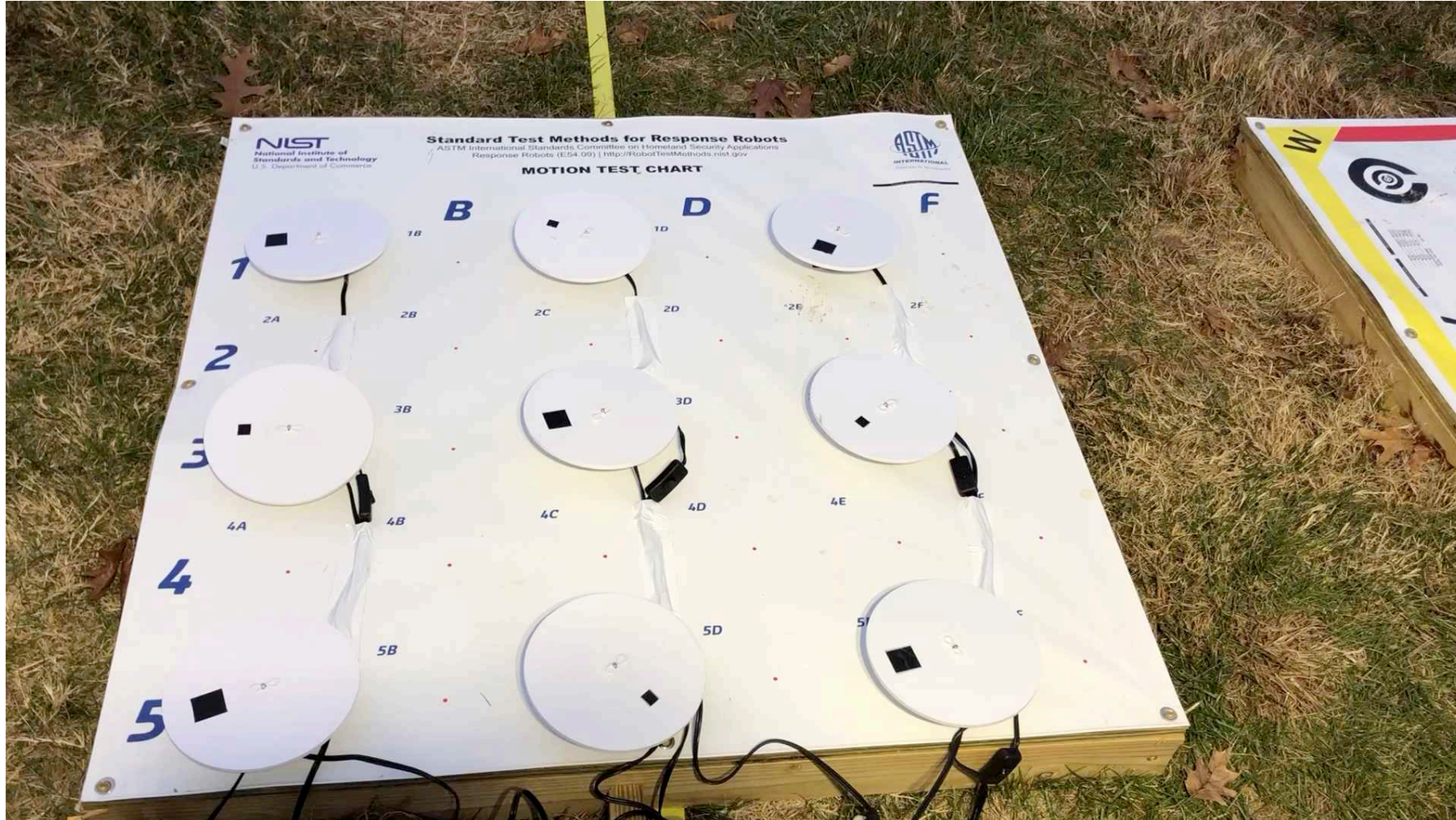


A simpler approach is to fold a hand warmer into roughly a line and staple it to the panel vertical, horizontal, or diagonal



Sensing: Motion Detection

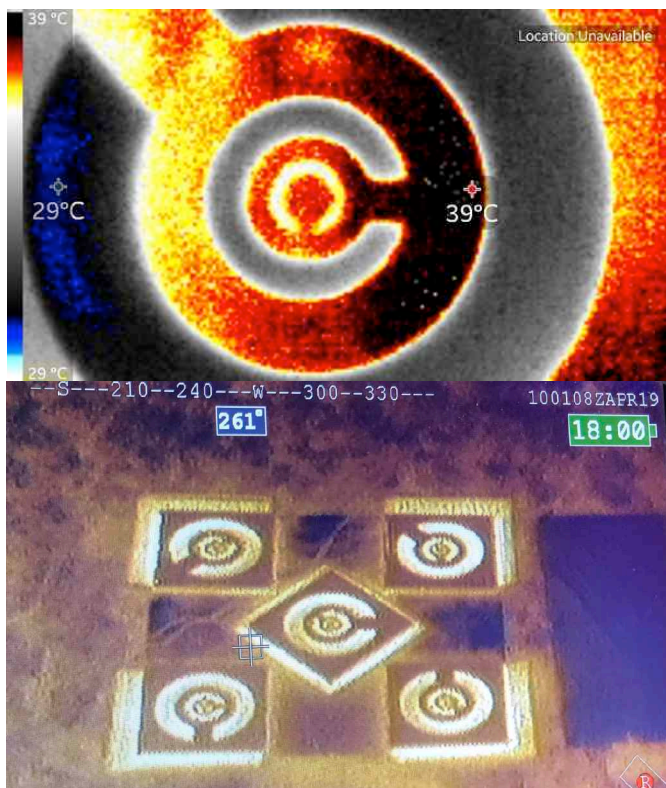
ASTM WK _____



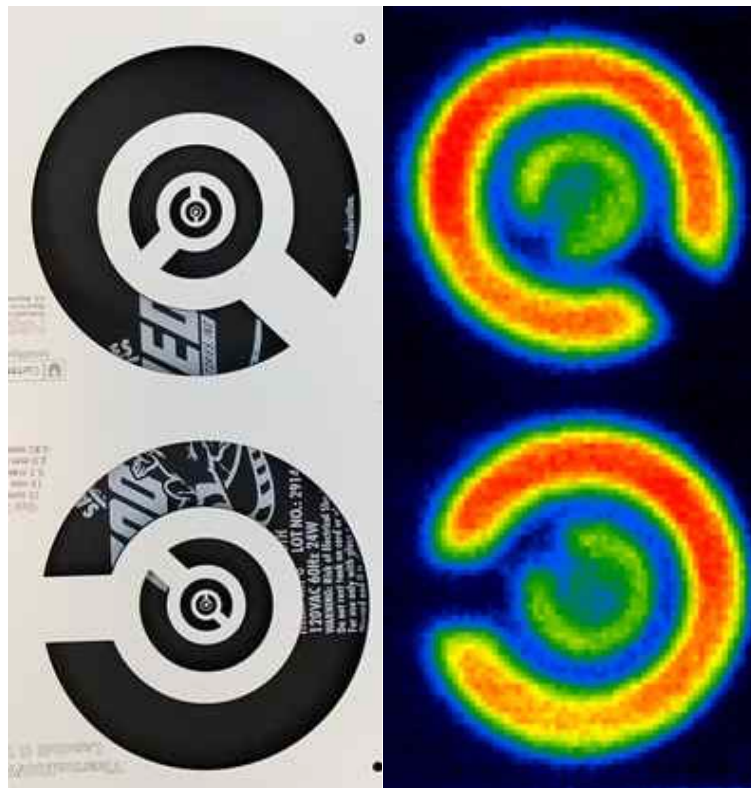
Sensing: Thermal Image Acuity

ASTM WK57967

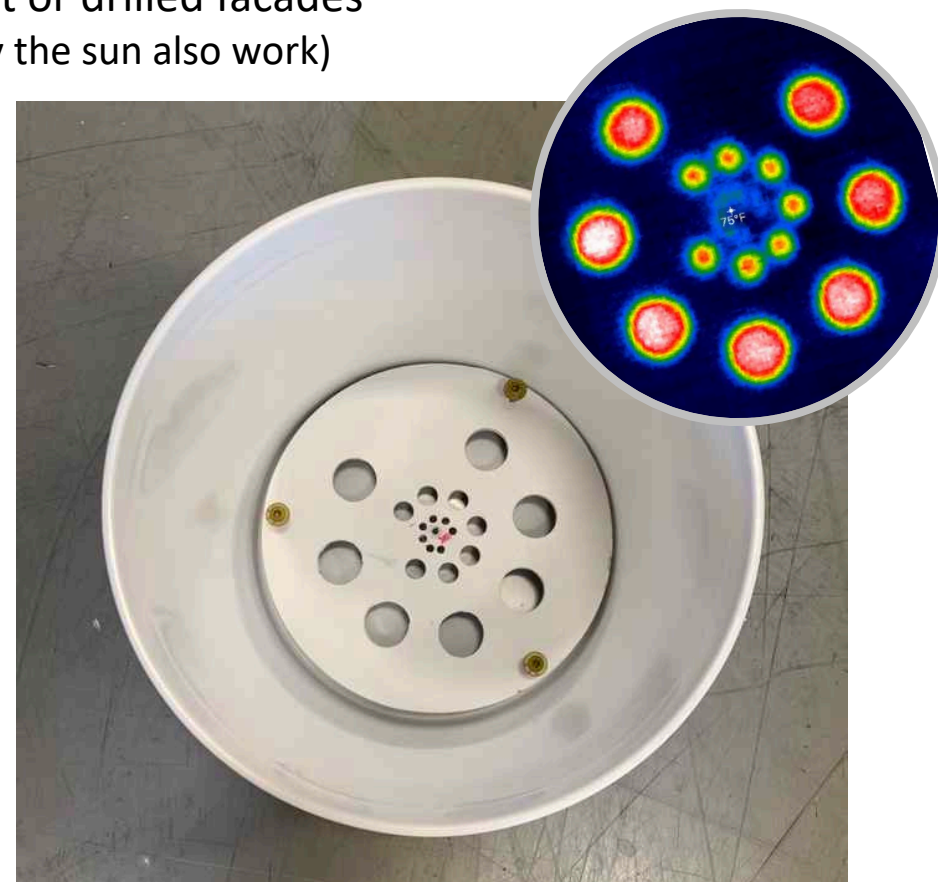
Heated reptile pads or hand warmers behind laser cut or drilled facades
(Indoor or outdoor use – typical sticker targets warmed by the sun also work)



An array of Concentric C thermal targets placed throughout a scenario (needs power).



Concentric Cs laser cut into MDF with a reptile heater. A metal backing helps diffuse the heat.



Drill Holes (1in, 1/2in, 1/4in) through plastic disks with hand warmers heating a metal disk backing.

Sensing: Video Latency

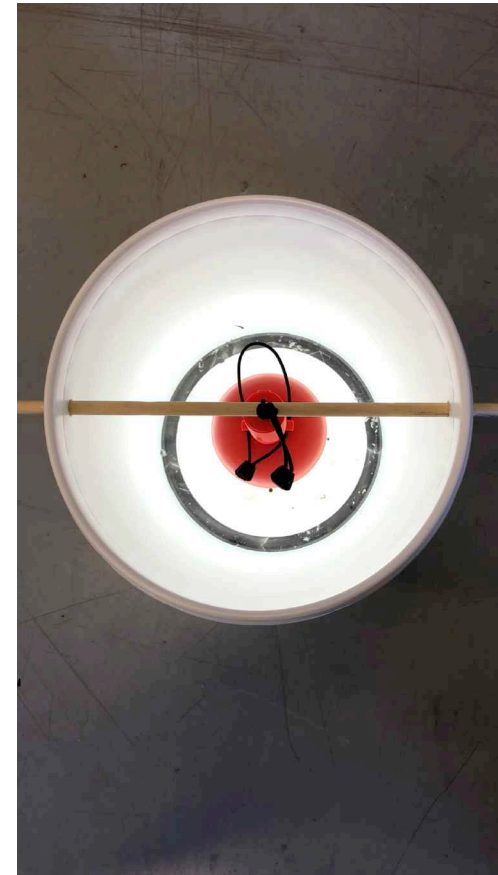
ASTM WK46478

Latency test with flashing “SOS” beacon or other light

High speed camera video (240 fps) captures flash in field AND flash on display views simultaneously.



Count the frames
between flashes



Sensing: Remote Latency and Packet Loss

ASTM WK46478

COMPUTER READABLE CODES
SYNCRONIZED AT BOTH ENDS

HUMAN READABLE CLOCKS
SYNCRONIZED AT BOTH ENDS

UP RANGE WITH OCU
(VIDEO CAPTURE WITH INTERFACE)

UP RANGE WITH OCU
(VIDEO CAPTURE WITH INTERFACE)



DOWN RANGE WITH ROBOT
(VIEWED THROUGH INTERFACE)

DOWN RANGE WITH ROBOT
(VIEWED THROUGH INTERFACE)

Sensing: Audio Acuity (2-Way)

ASTM WK60783

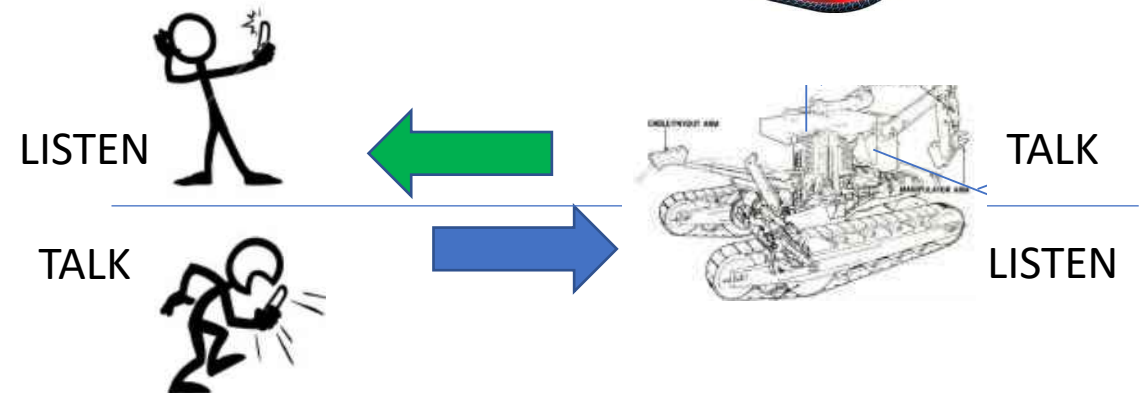
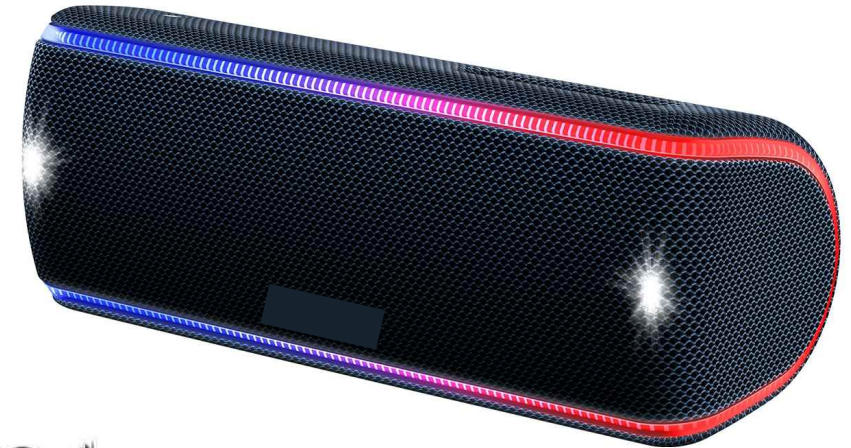
Alpha-numeric list read by a computer voice

Loudness set to 75-80 dB

AUDIO ACUITY TEST1.

0 MISSES IN 2 LINES ALLOWED. 0 IN 10 NUMBERS.
1 MISS IN 3 LINES ALLOWED. 1 IN 15 NUMBERS.
2 MISSES IN 5 LINES ALLOWED. 2 IN 25 NUMBERS.
3 MISSES IN 6 LINES ALLOWED. 3 IN 30 NUMBERS.

A!	1.	2.	3.	4.	5.	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>
B!	6.	2.	3.	5.	4.	<u>6</u>	<u>2</u>	<u>3</u>	<u>5</u>	<u>4</u>
C!	2.	5.	9.	8.	7.	<u>2</u>	<u>5</u>	<u>9</u>	<u>8</u>	<u>7</u>
D!	7.	2.	8.	9.	5.	<u>7</u>	<u>2</u>	<u>8</u>	<u>8</u>	<u>5</u>
E!	3.	4.	9.	1.	0.	<u>3</u>	<u>4</u>	<u>9</u>	<u>1</u>	<u>0</u>
F!	5.	8.	0.	2.	9.	<u>5</u>	<u>8</u>	<u>0</u>	<u>2</u>	<u>9</u>
G!	6.	9.	7.	3.	8.	<u>6</u>	<u>9</u>	<u>7</u>	<u>3</u>	<u>8</u>
H!	2.	0.	5.	2.	7.	<u>2</u>	<u>0</u>	<u>5</u>	<u>2</u>	<u>7</u>
I!	3.	5.	2.	8.	9.	---	---	---	---	---
J!	7.	2.	6.	1.	6.	---	---	---	---	---
K!	8.	3.	3.	4.	5.	---	---	---	---	---



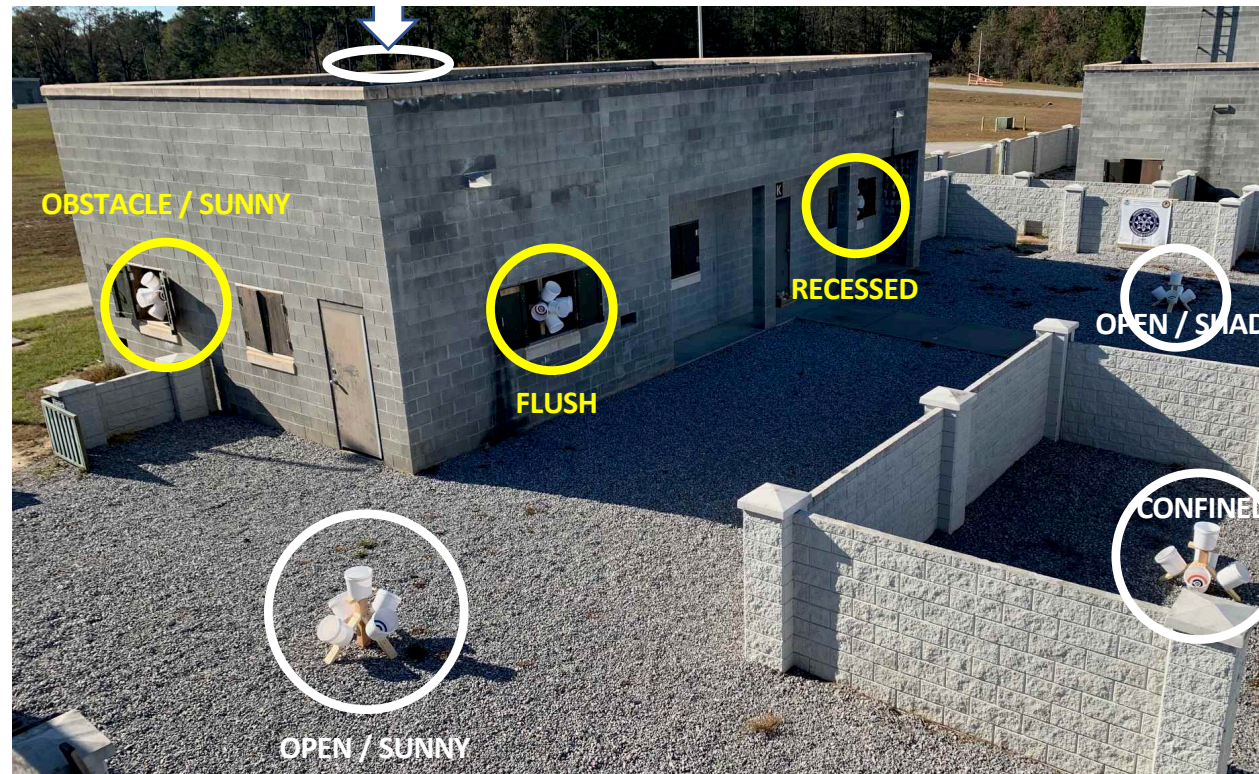
Sensing: 3D Range Imagers and Scanners

ASTM WK _____

Resolution



Mapping



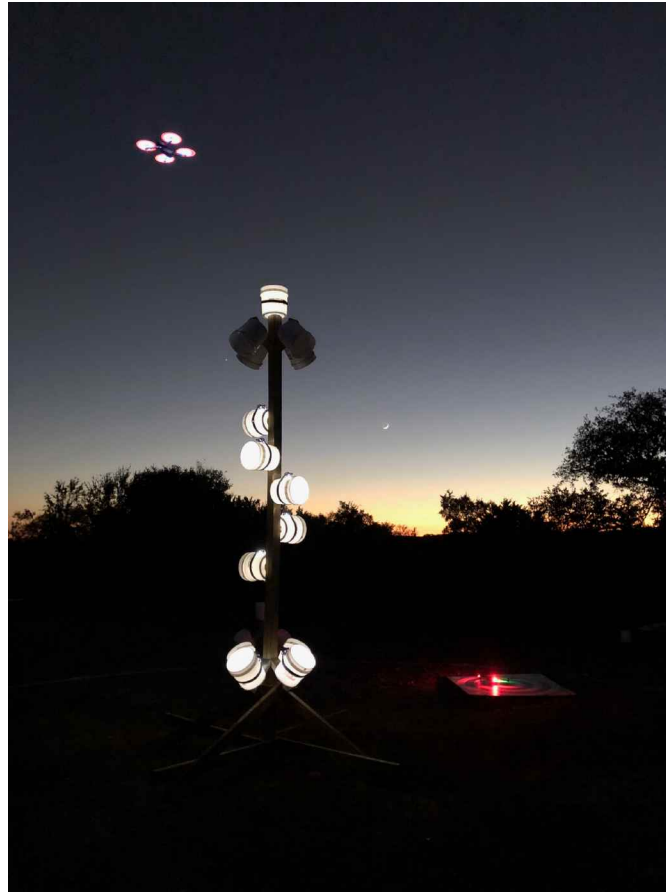
Sensing: Light Emissions

ASTM WK _____

WHITE OR RED HEADLAMPS
WRAPPED AROUND BUCKETS POINTED INWARD



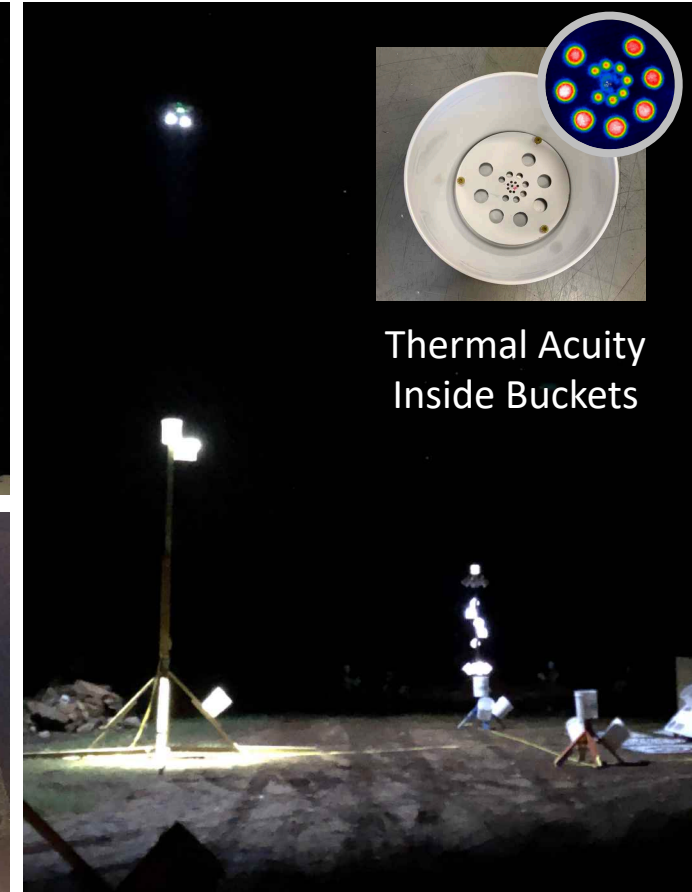
Position accuracy for range to target
using lighted buckets (red or white)



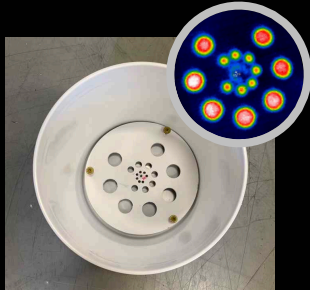
Inspect objects of interest
using lighted buckets (red or white)



Identify objects
lighted from the aircraft



Measure additional
sensor capabilities



Thermal Acuity
Inside Buckets

Sensing: Combined Sensor/Dexterity Crates (aka "Victim" Crates)

WK _____



LIGHTED CRATES



CENTER DEXTERITY PIPE TASKS
(BLOCKS VIEWS WHEN NOT CENTERED.
BUT IS USED ONLY TO DETERMINE ROBOT
DEXTERITY CONFIGURATION MULTIPLIERS)



HAZMAT LABEL
IDENTIFICATION
(x2)

VISUAL/COLOR
ACUITY
(x2)



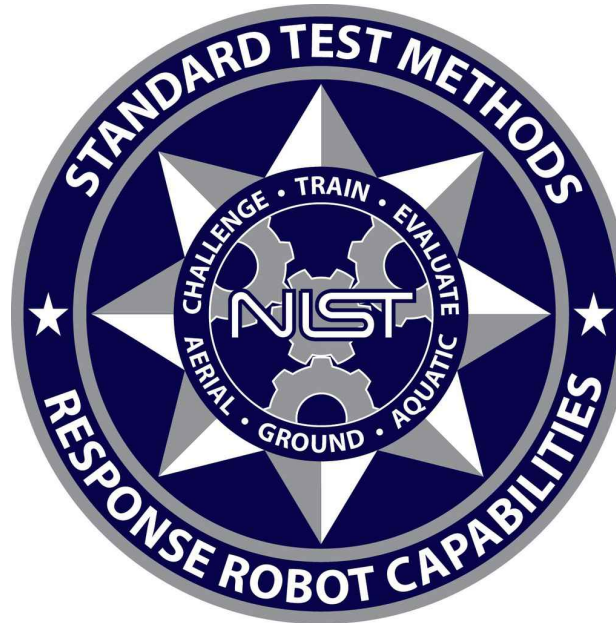
MOTION
DETECTION
(x2)

THERMAL IMAGE
RESOLUTION
(x2)

PROXIMITY SAMPLING
MAGNETS IN CORNERS
AND CENTER (x5)

Radio Comms Range Tests

Ground Robots



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U.S. Department of Commerce

Sponsor:

Phil Mattson

Science and Technology Directorate
U.S. Department of Homeland Security

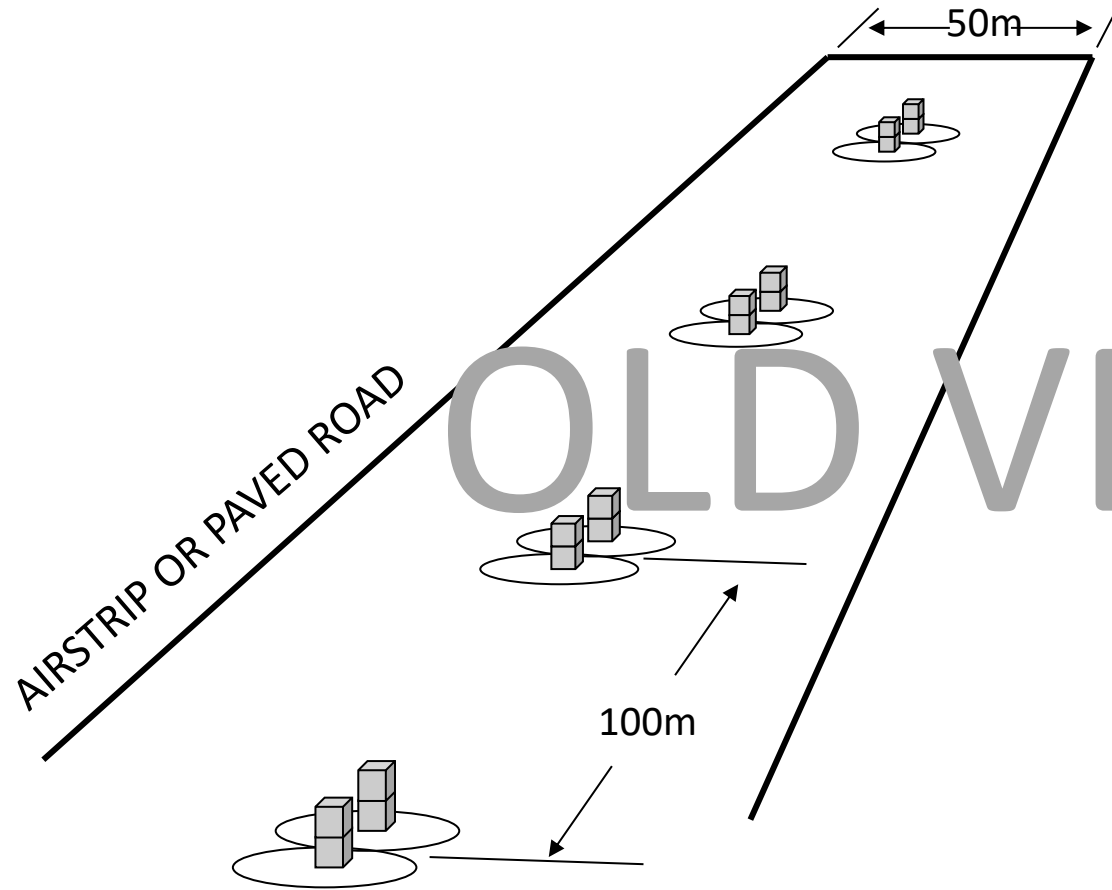
Internet
RobotTestMethods.nist.gov



Email
RobotTestMethods@nist.gov

Radio Comms: Line-of-Sight Range

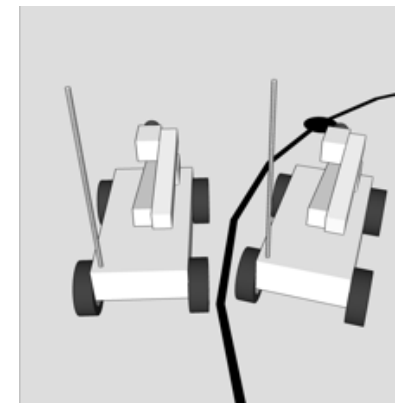
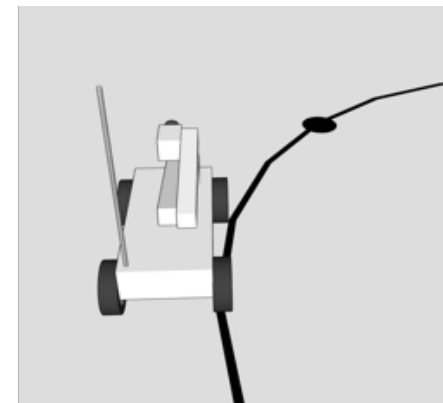
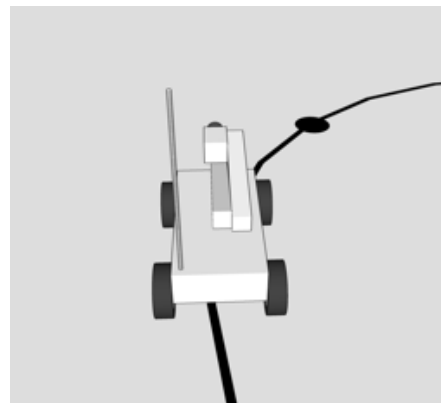
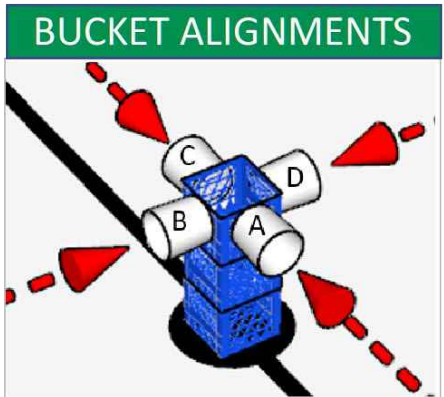
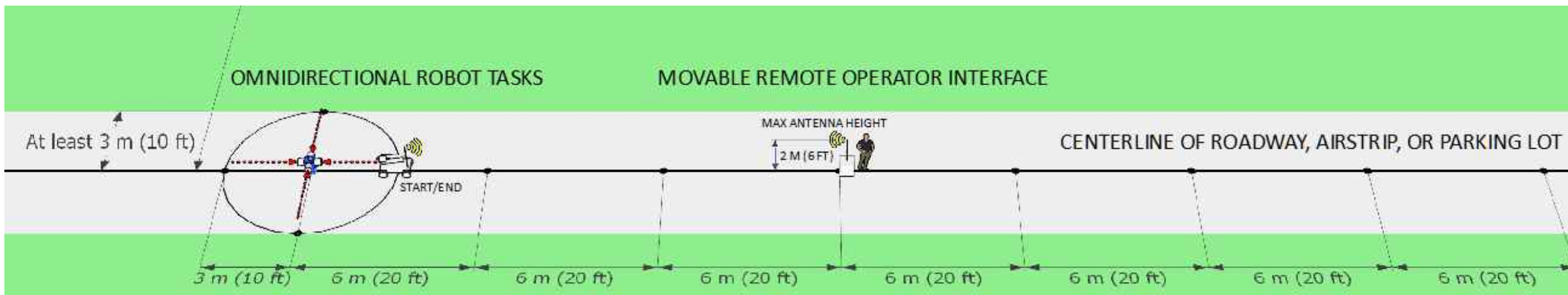
ASTM E2854-2013



OLD VERSION

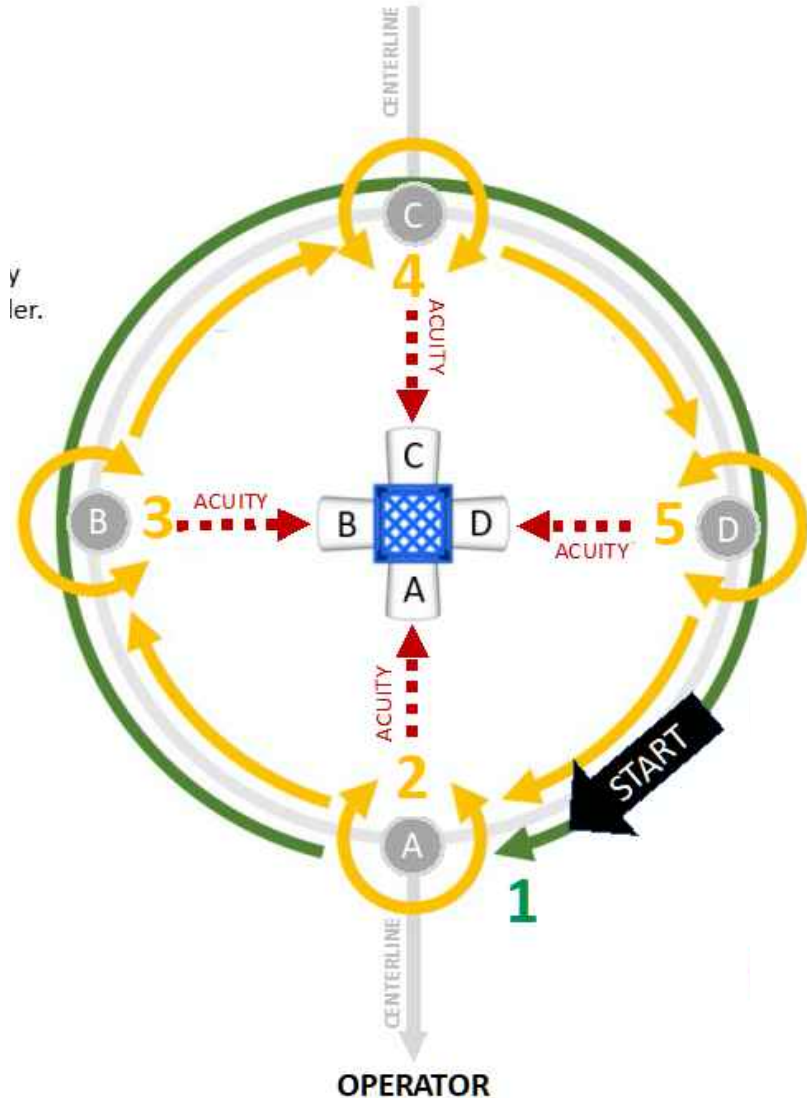
Radio Comms: Line-of-Sight Range

ASTM E2854-2020

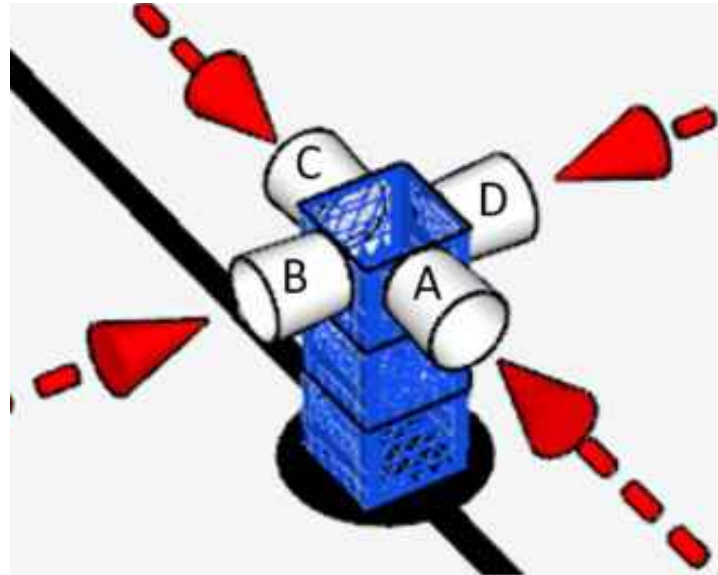


Radio Comms: Line-of-Sight Range

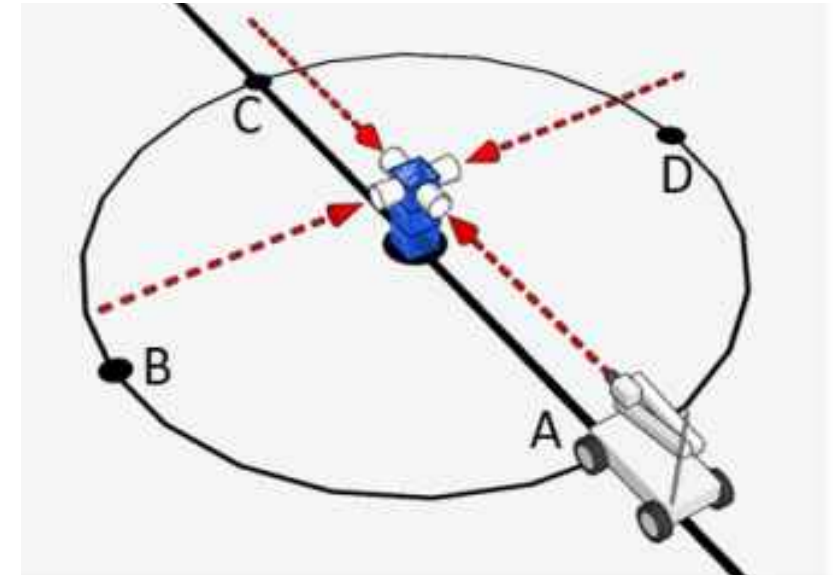
ASTM E2854-2020



PERPENDICULAR BUCKETS



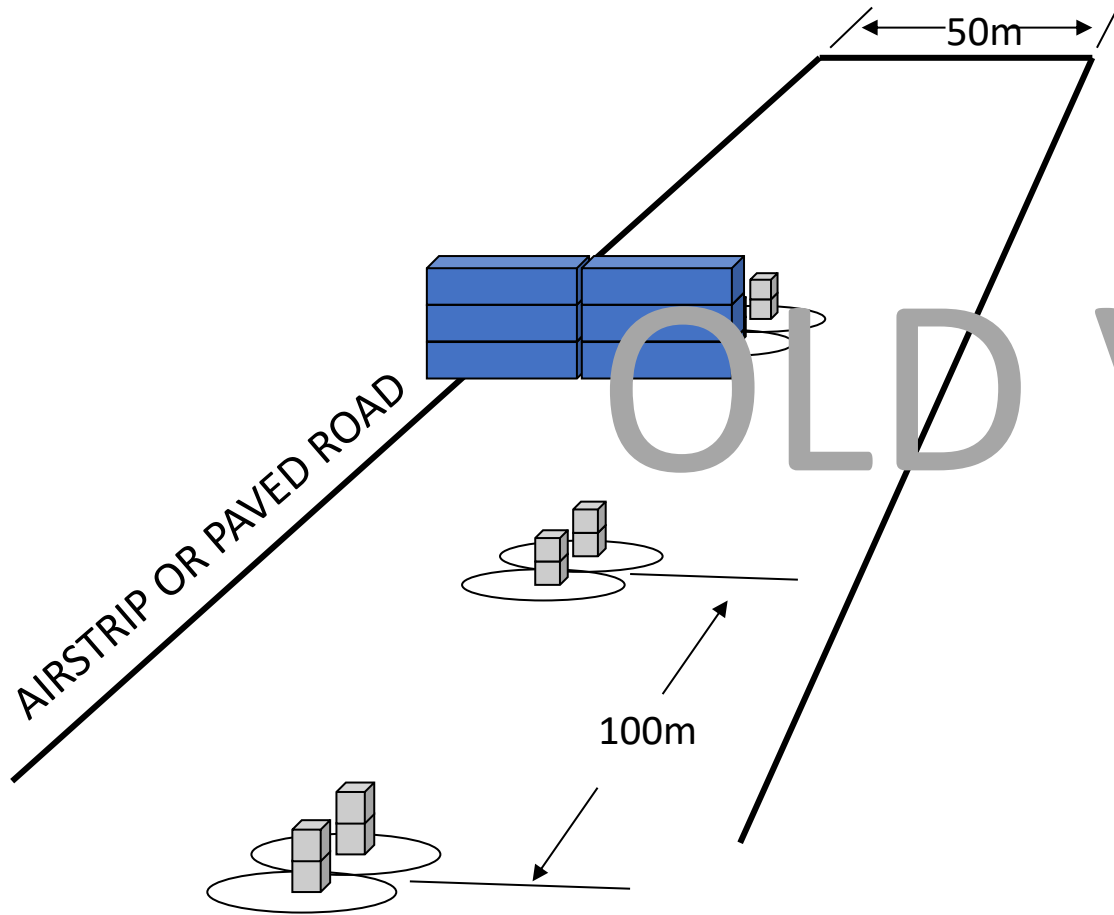
BUCKET IDENTIFICATION POSITION



Maneuvering Tasks (5 points) and Visual Acuity Tasks (20 Points)

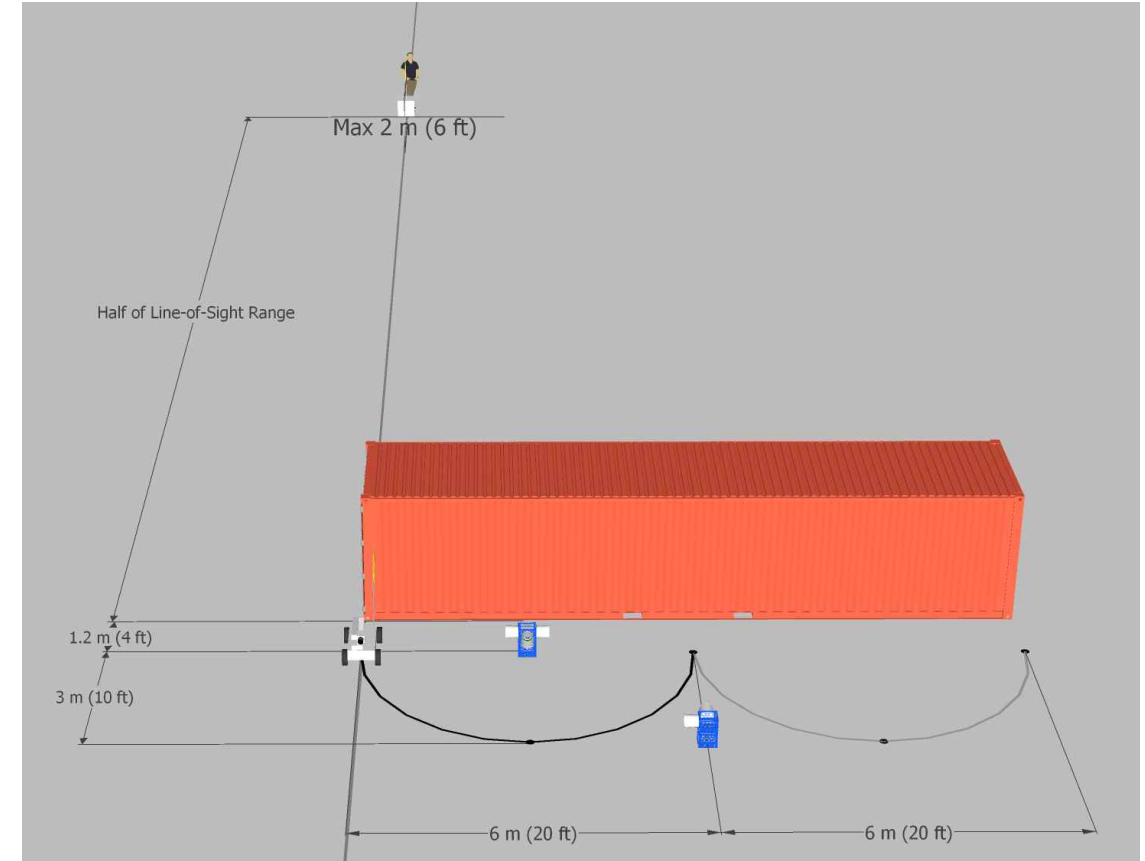
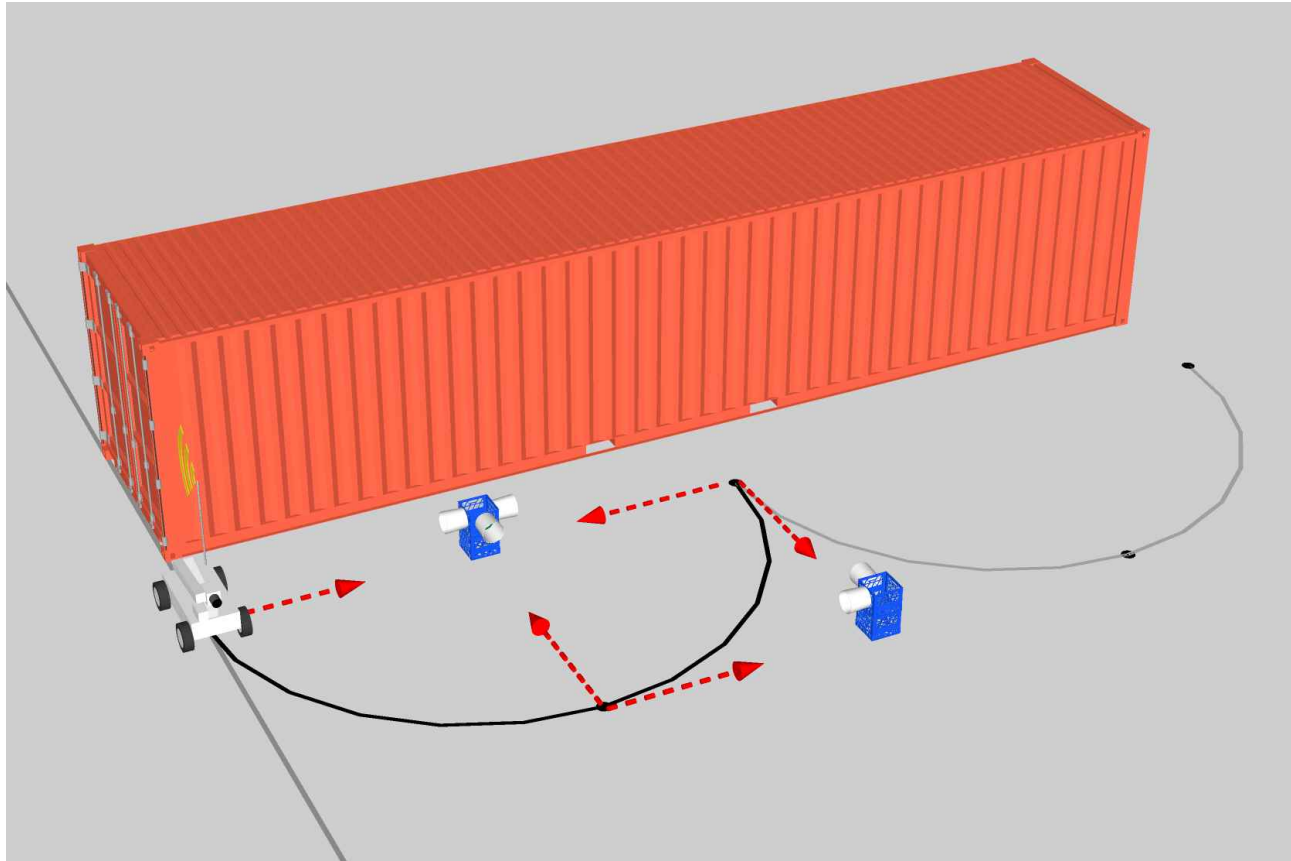
Radio Comms: Non-Line-of-Sight Range

ASTM E2855-2013



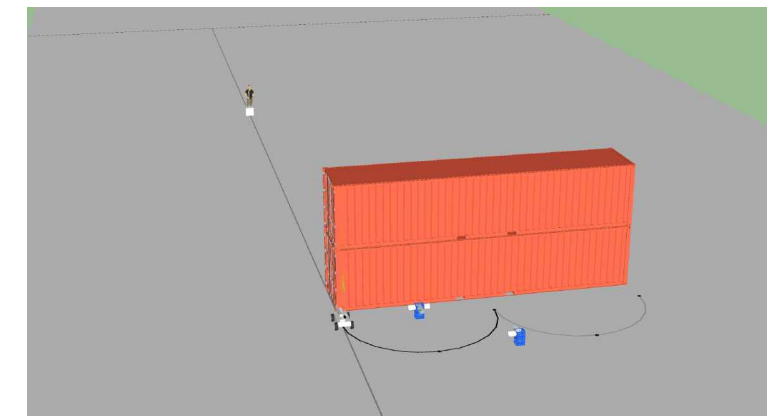
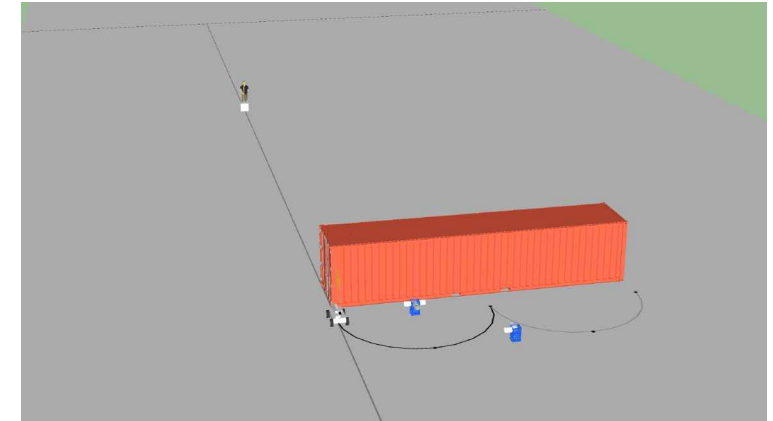
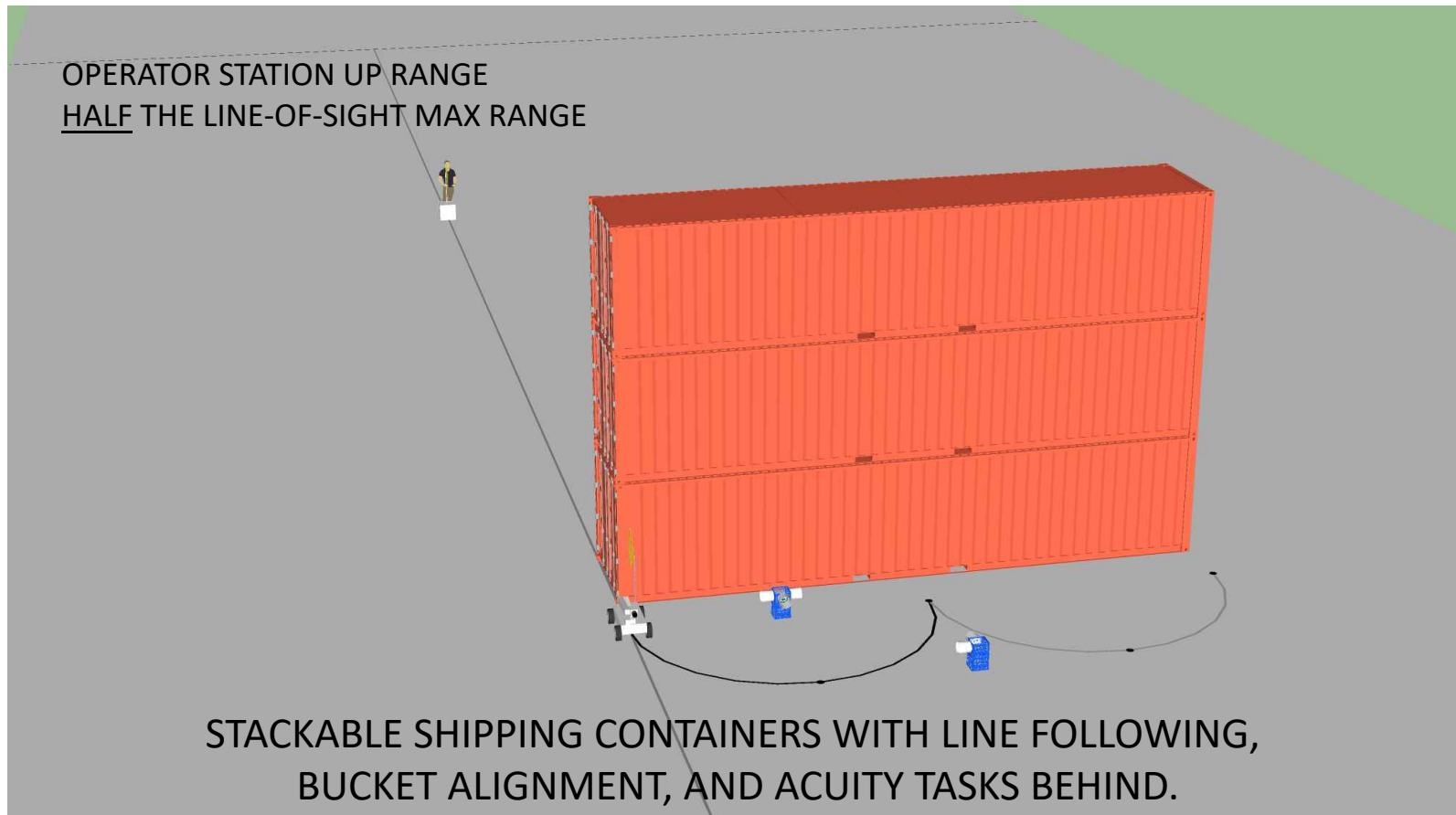
Radio Comms: Non-Line-of-Sight Range

ASTM E2855-2021



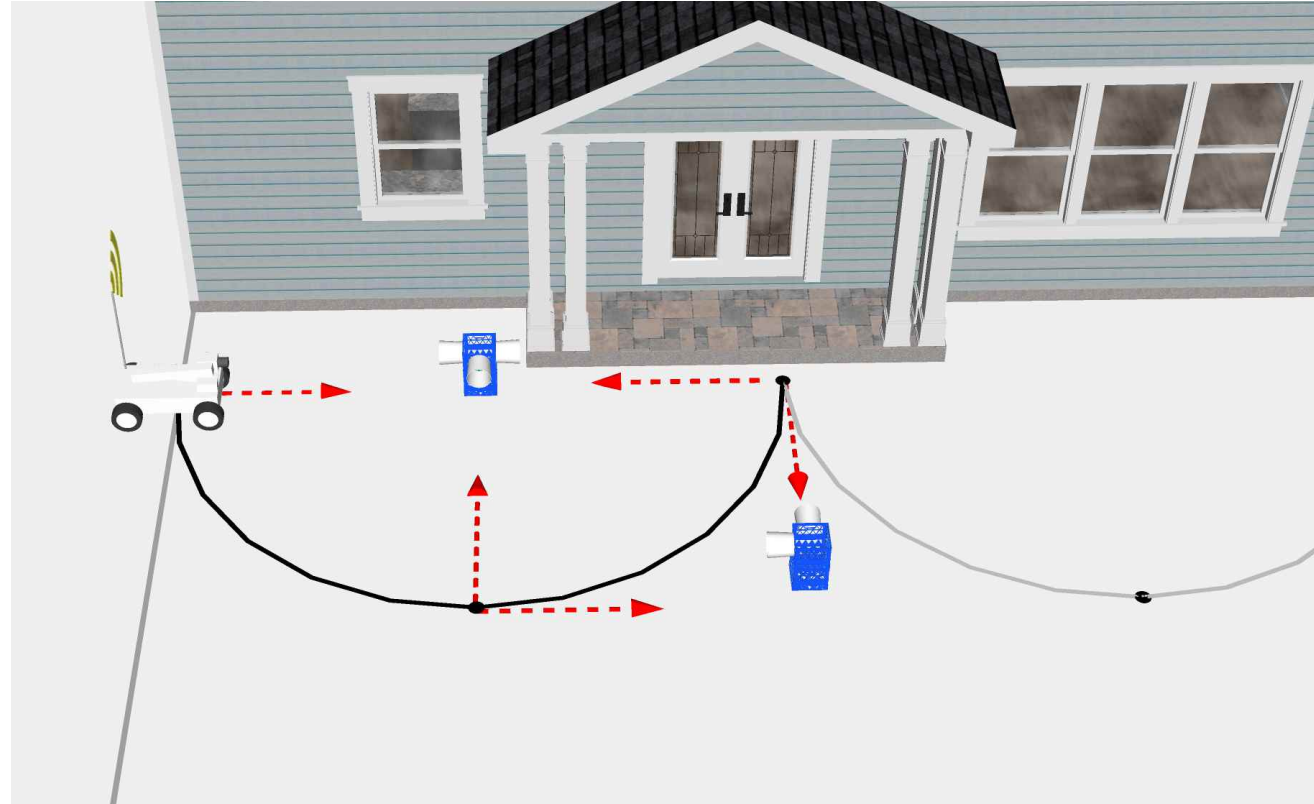
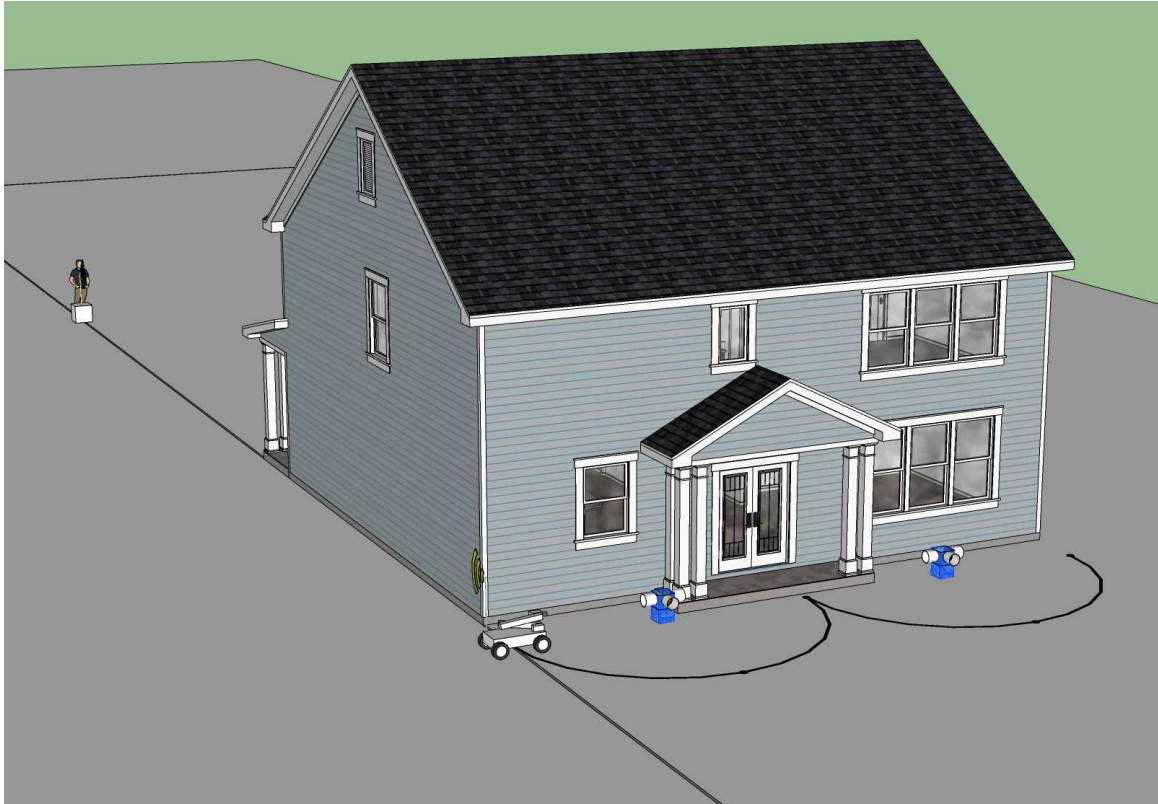
Radio Comms: Non-Line-of-Sight Range

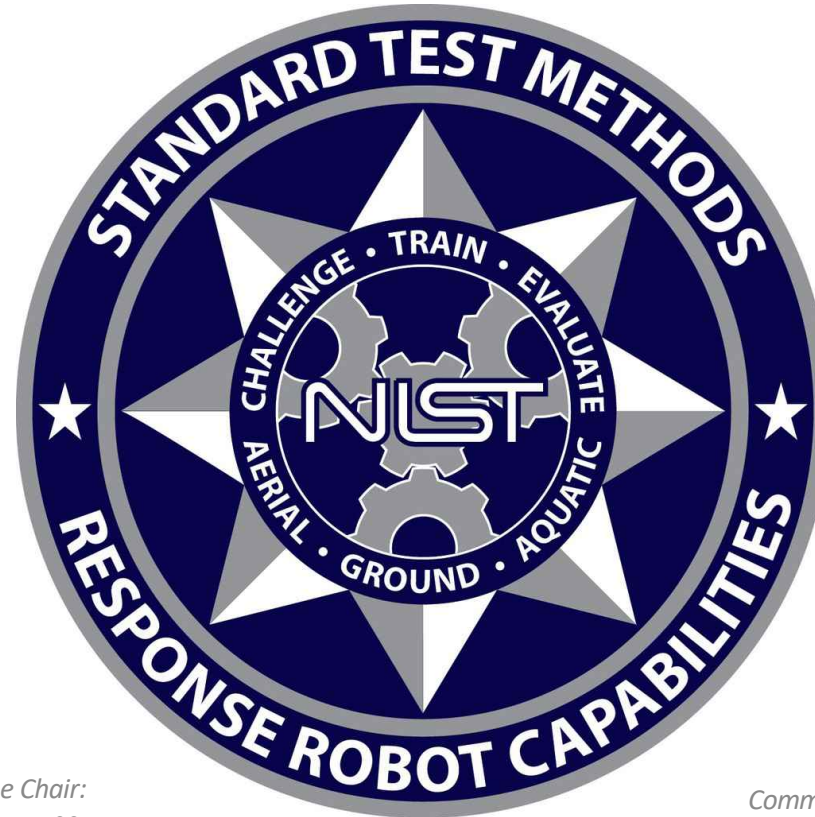
ASTM E2855-2021



Radio Comms: Non-Line-of-Sight Range

ASTM E2855-2021





Sub Committee Chair:

Adam Jacoff

Intelligent Systems Division
National Institute of Standards and Technology
U.S. Department of Commerce

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