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Developing AI-based Wildfire Evacuation Behavior (AI-WEB) Model

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Overview

- Motivation
- Goals
- Analyzing wildfire evacuation decisions and departure timing with GPS data
- Forecasting real-time travel demand during wildfire evacuations
 - *Situational-Aware Multi-Graph Convolutional Recurrent Network (SA-MGCRN)*
- Key take-aways

Motivation



Insider (2019)



Kent Porter / The Press Democrat (2019)

Research Needs:

- Understand household behavior and movements in wildfires;
- Provide real-time decision support for emergency managers.

Goals

Goal 1:

Improve understanding of people's evacuation decision-making using large-scale GPS data.

**Goal 2:**

Advance methodology of forecasting real-time travel demand during wildfire evacuations.

Analyzing wildfire evacuation decisions and departure timing with GPS data

Zhao, X., Xu, Y., Lovreglio, R., Kuligowski, E., Nilsson, D., Cova, T., Wu, A., & Yan, X. (2022). Estimating wildfire evacuation decision and departure timing using large-scale GPS data. Transportation Research Part D: Transport and Environment, 107, 103277.

Study site exploration

2019 Kincadee fire, Sonoma County, CA:

- Started at 9:27 pm on October 23, 2019 and was fully contained at 7:00 pm on November 6, 2019.
- Burned 77,758 acres, destroyed 374 structures, damaged 60 structures, and caused 4 injuries.

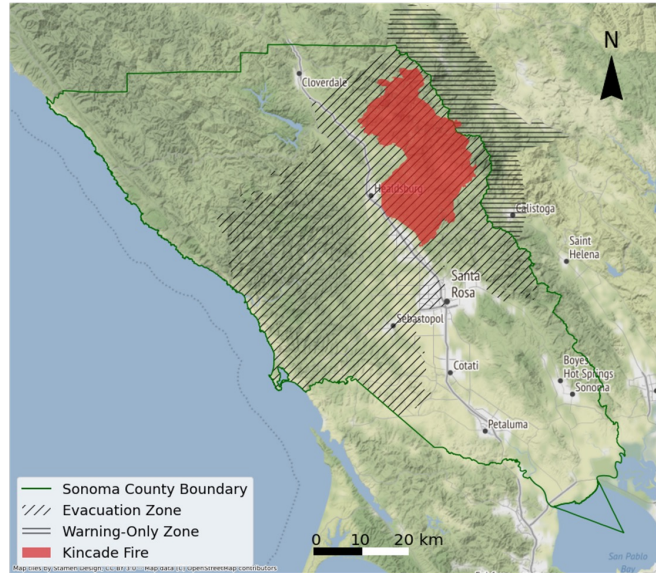


Figure. Sonoma County and the Kincadee Fire perimeter

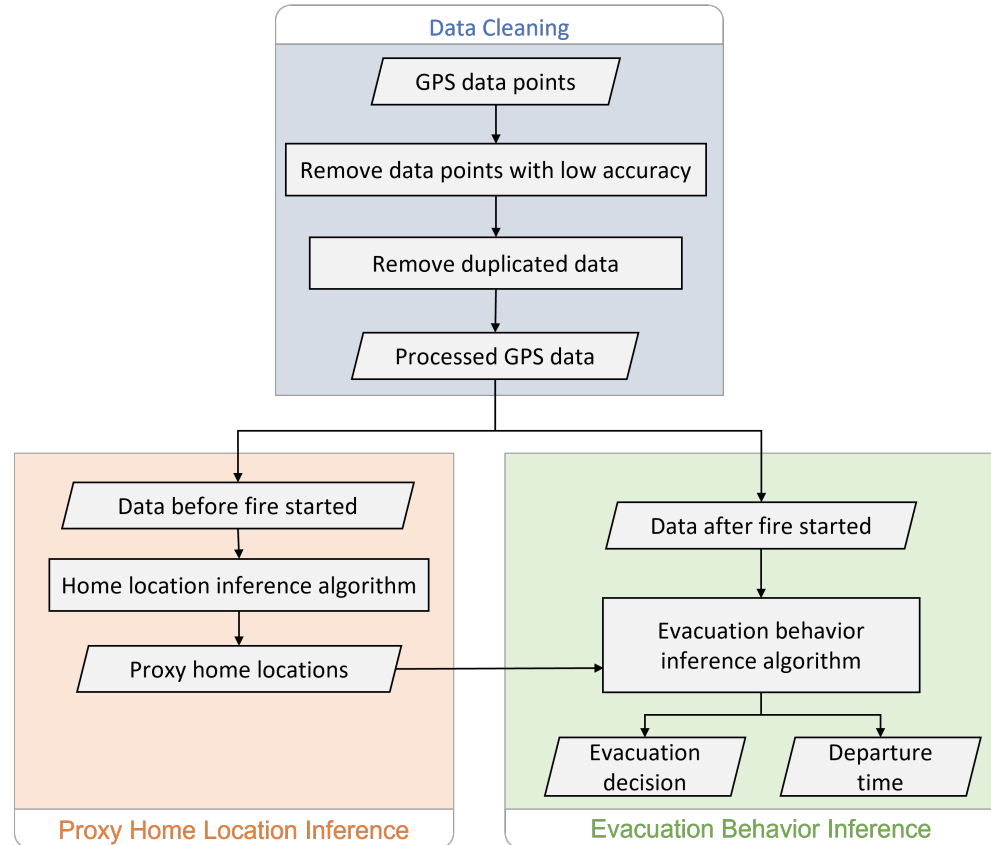
Data description & cleaning

- The GPS data was provided by Gravy Analytics and built on privacy-friendly mobile location data.
- After the data cleaning process, we retained **44,211,050** records, or a total of **5,338 residents** for analysis.

Table 1. Synthetic GPS Data Samples

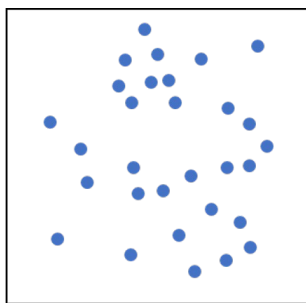
ID	LATITUDE	LONGITUDE	GEOHASH9	TIMESTAMP_EPOCH	TIMEZONE	FLAG
00001	y_1	x_1	9qbd*****	15715*****	TZ1	0
00002	y_2	x_2	9qbc*****	15715*****	TZ1	0
00003	y_3	x_3	9qbs*****	15712*****	TZ1	0
00003	y_4	x_4	9qbe*****	15726*****	TZ1	0
00004	y_5	x_5	9qbd*****	15713*****	TZ1	0
00004	y_6	x_6	9qbd*****	15714*****	TZ1	0

Methodological framework

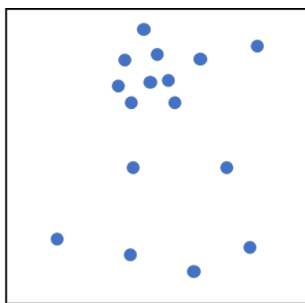


Proxy-home-location inference

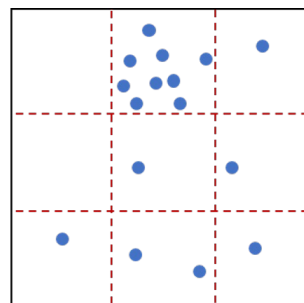
Apply **time-space heuristics method** accompanied by **clustering**.



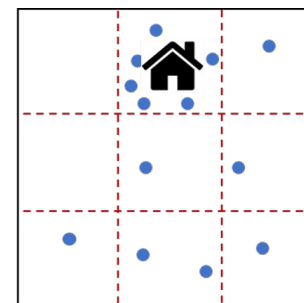
All data points of a resident



Extract the resident's data points at night



Divide the area by grid



Count the data points in each cell and determine the proxy home location

• Data point

— Area boundary

- - - Grid (cell boundary)



Inferred proxy home location

Evacuation-behavior inference

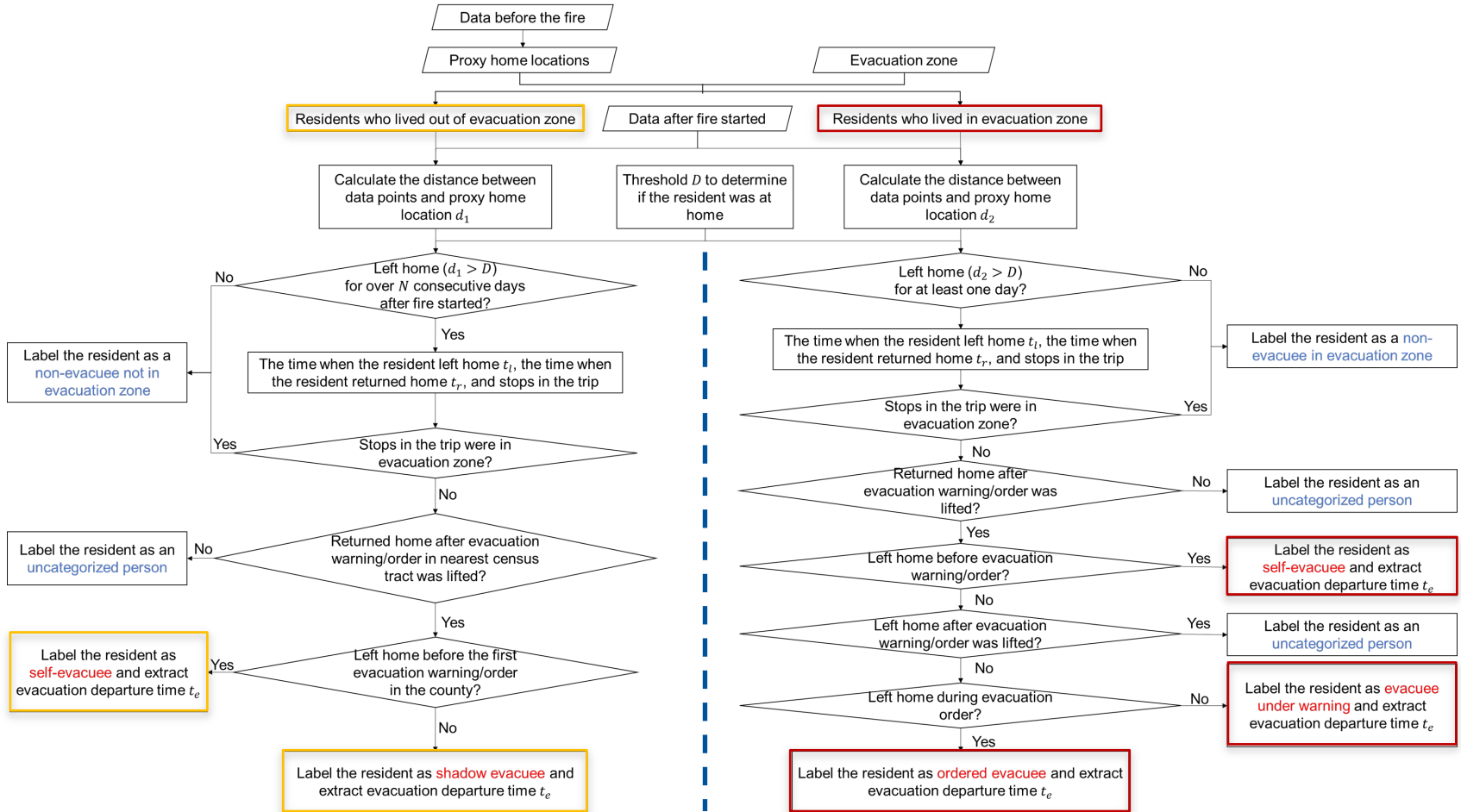
Note that we only analyze the evacuation behavior of **people who resided in or near the evacuation zones** (within 5 miles of the evacuation zones' boundaries).

- **Assumption 1:** All evacuees departed from home.
- **Assumption 2:** If the distance between the resident's current location and the resident's proxy home location was larger than D , the resident has left home.
- **Assumption 3:** A resident is considered as an evacuee, if they left the evacuation zone during the evacuation process.
- **Assumption 4:** The evacuation departure time is when the evacuee left home to evacuate.

Evacuation-behavior inference

Definitions of evacuee groups:

- **Self-evacuee**: The evacuee, located in or near the evacuation zone, left after the fire started but before any evacuation warning/order was issued.
- **Shadow evacuee**: The evacuee, located outside but near the evacuation zone, left after an evacuation warning/order was issued.
- **Evacuee under warning**: The evacuee was in the evacuation warning zone and evacuated after the warning was issued and before an order was issued (if any).
- **Ordered evacuee**: The evacuee lived in the evacuation order zone and evacuated after the order was issued.



An example to illustrate the algorithm

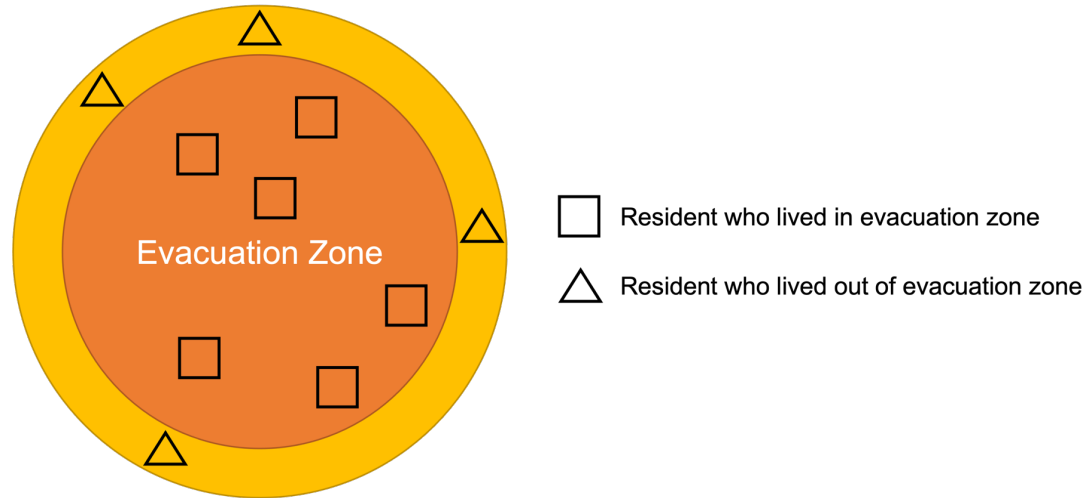
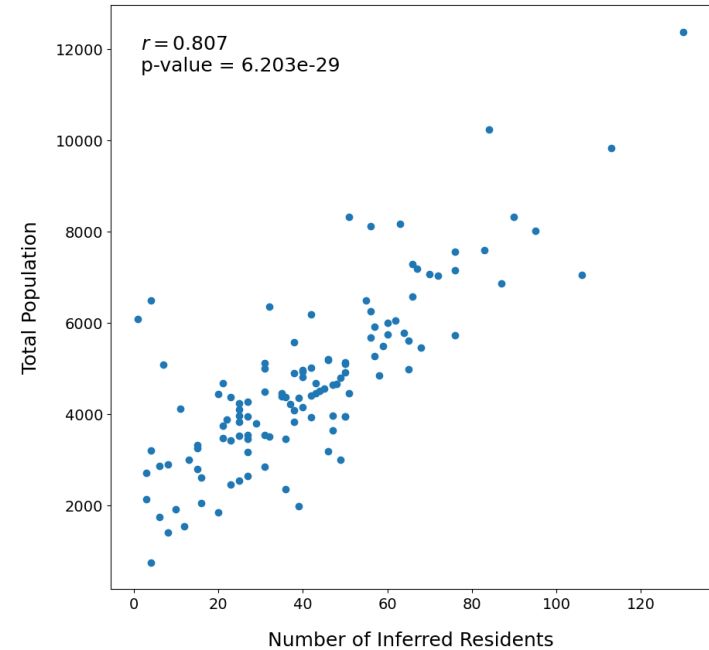
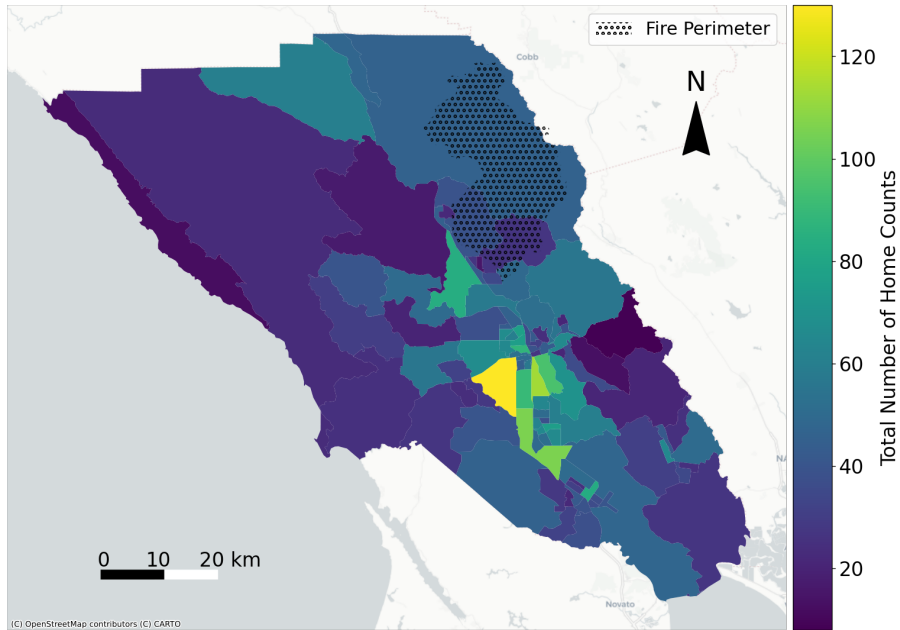


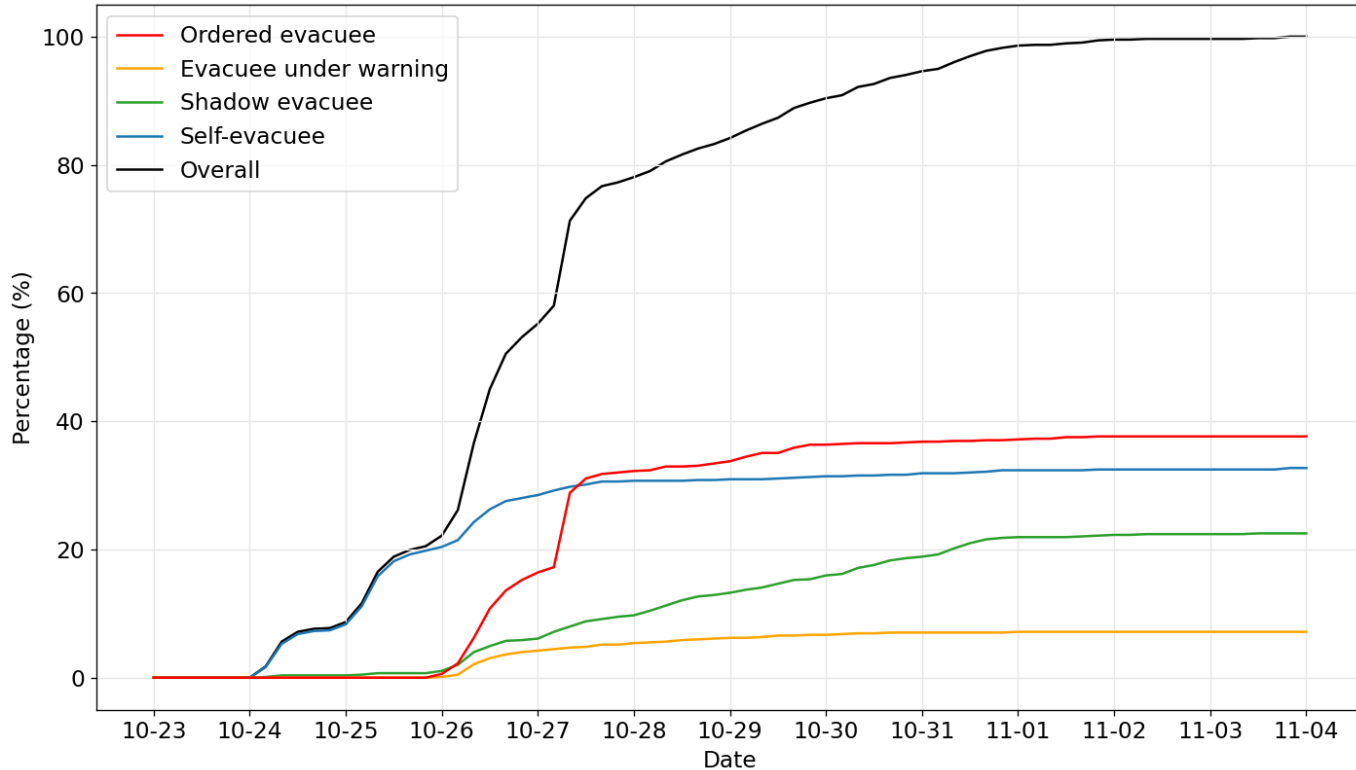
Table 1: Definitions of Different Evacuee Groups

	Day 1	Day 2	Day 3: Warning	Day 4	Day 5: Evacuation order
□	Self-evacuee	Self-evacuee	Evacuee under warning	Evacuee under warning	Ordered evacuee
△	Self-evacuee	Self-evacuee	Shadow evacuee	Shadow evacuee	Shadow evacuee

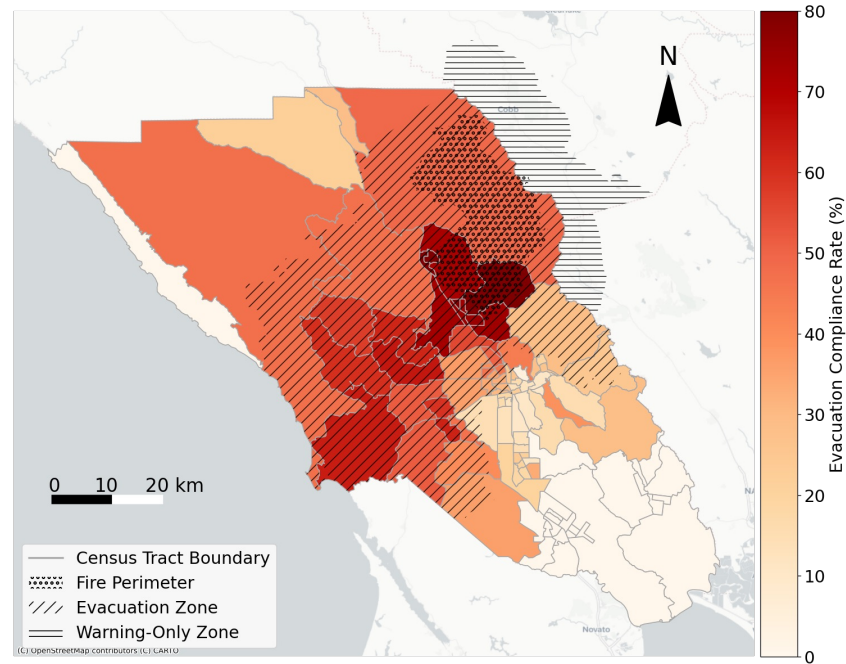
Results: Home location inference



Results: Temporal patterns



Results: Spatial patterns



GPS data: 46% evacuated v.s. Survey data: 80% evacuated

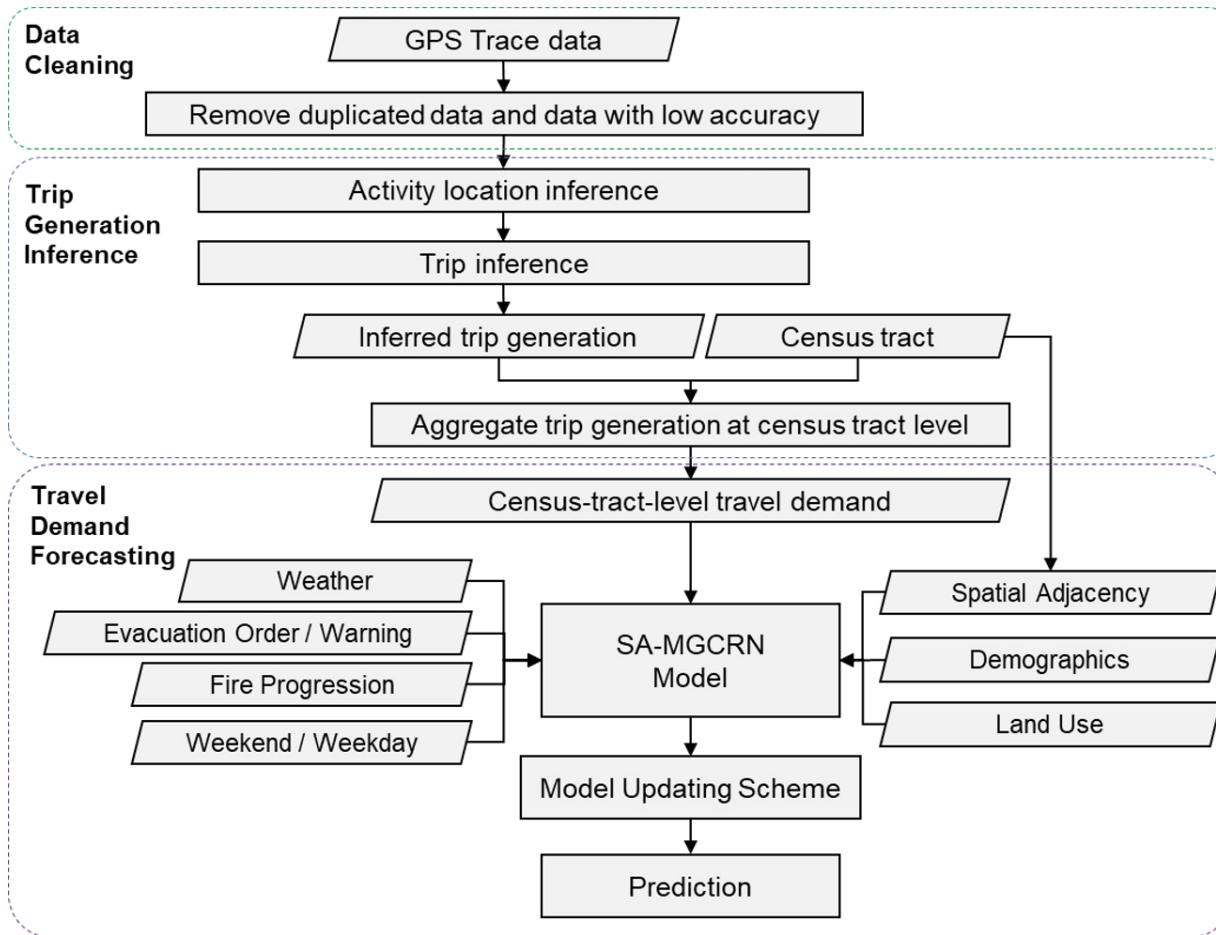
Key take-aways

- A set of novel methodologies are developed to systematically analyze wildfire evacuation process and identify different groups of evacuees.
- Self-evacuees and shadow evacuees consisted of more than half of evacuees during the Kincade Fire.
- The total evacuation compliance rate is around 50%, which shows some discrepancy from the results obtained from the separate survey study for the same fire conducted by our team (Kuligowski et al., 2022).

Forecasting real-time travel demand during wildfire evacuations

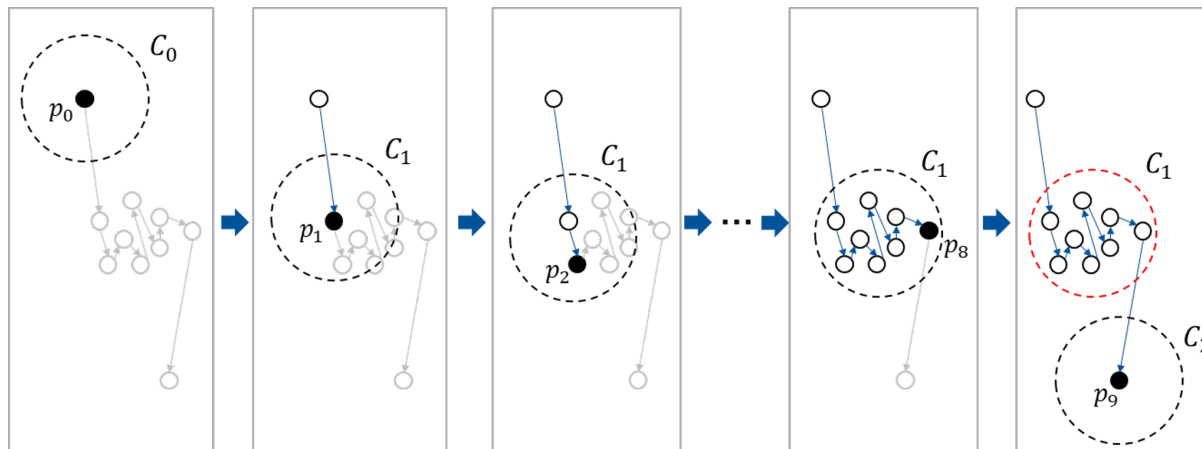
Xu, Y., Xiong, R., Lovreglio, R., Nilsson, D., & Zhao, X. (In Preparation). Forecasting real-time travel demand during wildfire evacuations: A Situational-Aware Multi-Graph Convolutional Recurrent Network (SA-MGCRN) approach. In Proceedings of Transportation Research Board 102nd Annual Meeting, Washington, D.C.

Department of Civil and Coastal Engineering



evacuation trips + other types of trips
(e.g., background trips, intermediate trips)

Trip generation inference – Incremental clustering



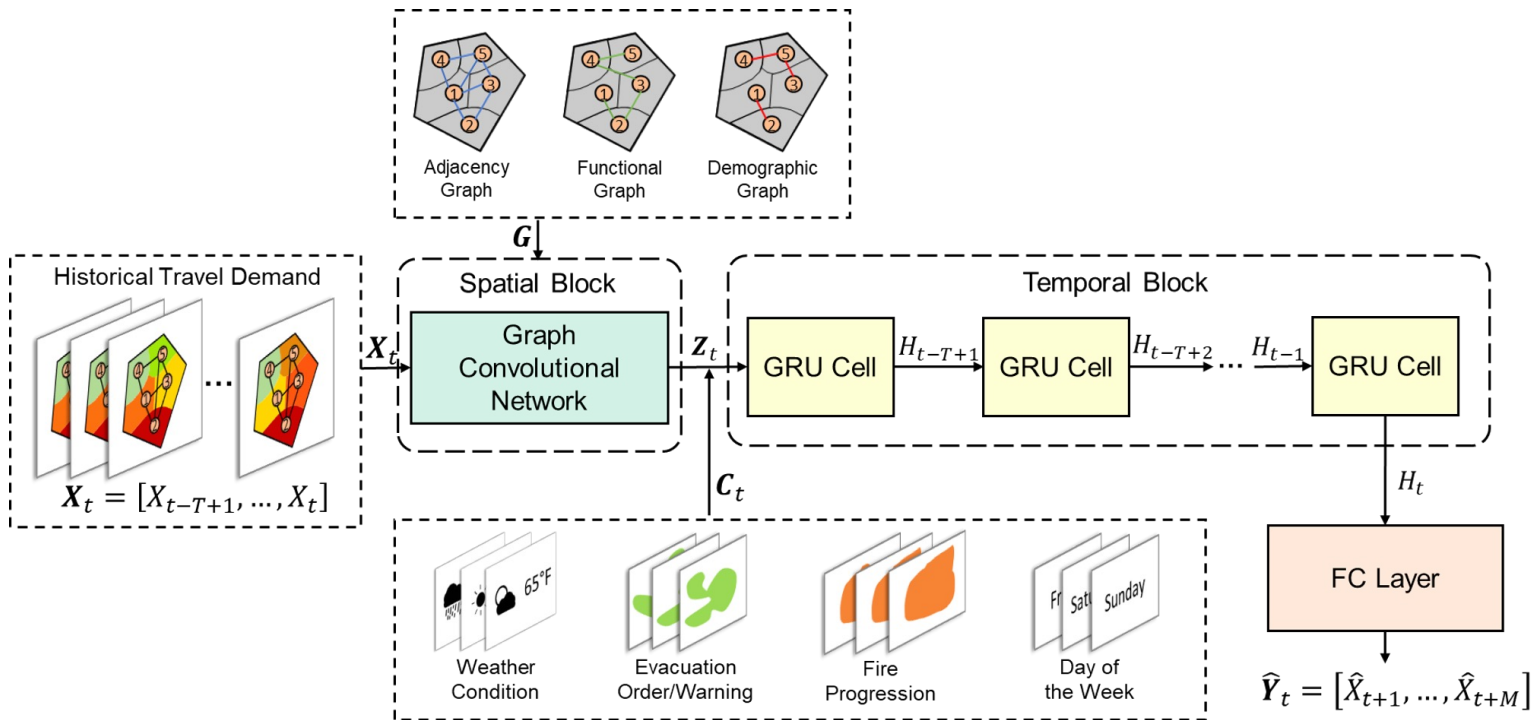
● Current GPS Point ○ Previous GPS Point ○ Subsequent GPS Point
- - - - Current Cluster Boundary - - - - Inferred Activity Location

Cluster radius: 500 meters
Time threshold: 5 minutes

1. Wang, F., & Chen, C. (2018). On data processing required to derive mobility patterns from passively-generated mobile phone data. *Transportation Research Part C: Emerging Technologies*, 87, 58-74.
2. Wang, F., Wang, J., Cao, J., Chen, C., & Ban, X. J. (2019). Extracting trips from multi-sourced data for mobility pattern analysis: An app-based data example. *Transportation Research Part C: Emerging Technologies*, 105, 183-202.
3. Chen, C., Bian, L., & Ma, J. (2014). From traces to trajectories: How well can we guess activity locations from mobile phone traces?. *Transportation Research Part C: Emerging Technologies*, 46, 326-337.
4. Calabrese, F., Diao, M., Di Lorenzo, G., Ferreira Jr, J., & Ratti, C. (2013). Understanding individual mobility patterns from urban sensing data: A mobile phone trace example. *Transportation research part C: emerging technologies*, 26, 301-313.

Architecture of the SA-MGCRN model

Situational-Aware Multi-Graph Convolutional Recurrent Network (SA-MGCRN)



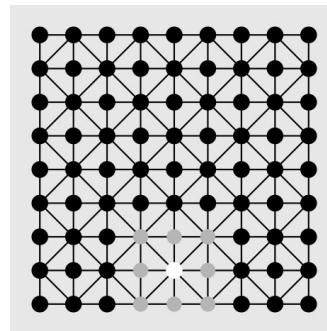
Graph Convolutional Network (GCN)

Why GCN? GCN v.s. CNN

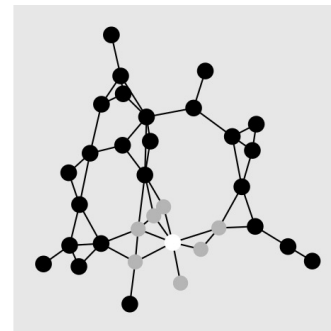
- CNN can only be performed in **Euclidean** space, while GCN can handle **graph-structured** data.
- The census tracts do **not** have a regular spatial structure but can be represented by a graph.

How does GCN work?

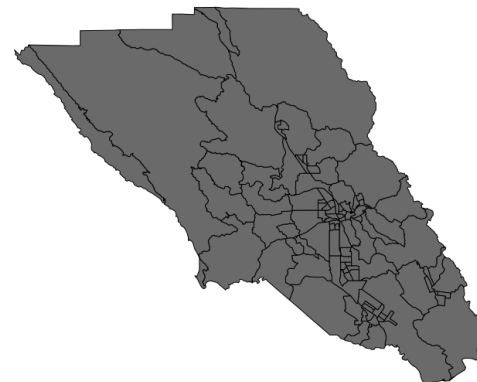
- GCN performs convolutional operation using a filter.
- The filter is applied on each node of the graph, thus capturing spatial dependency between a node and its adjacent nodes.



Euclidean data



Graph-structured data



Census Tracts (Sonoma County, CA)

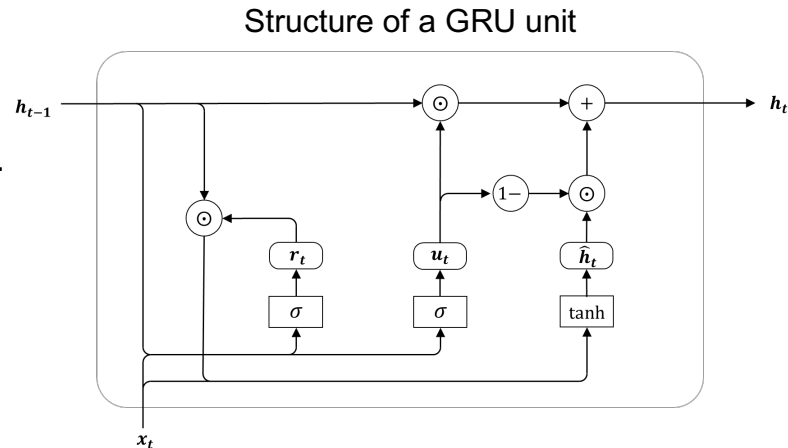
Gated Recurrent Unit (GRU)

Why GRU? GRU v.s. LSTM

- Widely-used RNN model to capture temporal dependency.
- GRU is faster to compute but still offers comparable performance in prediction compared with LSTM.
- Using the memorize long-term information, GRU can deal with the vanishing gradient problem.

How does GRU work?

- GRU uses two gates to determine what information should be kept and passed to the output.
- **Reset gate**: how much of the previous state information to remember.
- **Update gate**: how much of the previous information to pass to the new state.



x_t -- input at time t ;

h_{t-1}, h_t -- hidden states;

r_t -- reset gate;

u_t -- update gate;

\hat{h}_t -- candidate hidden state.

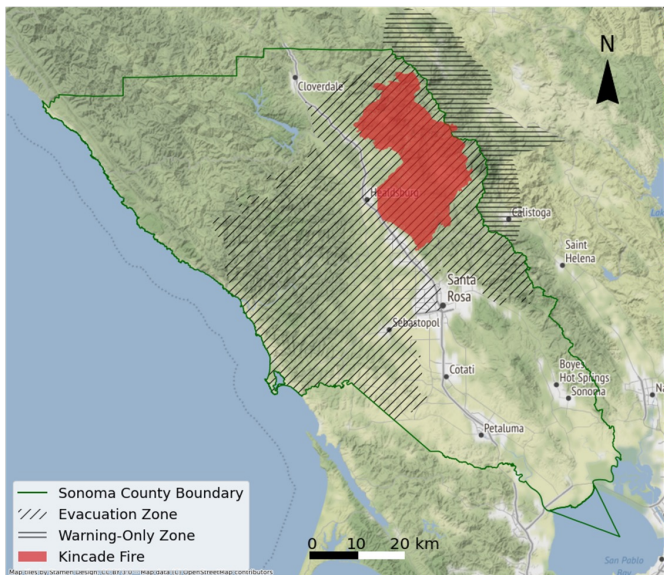
Model updating scheme



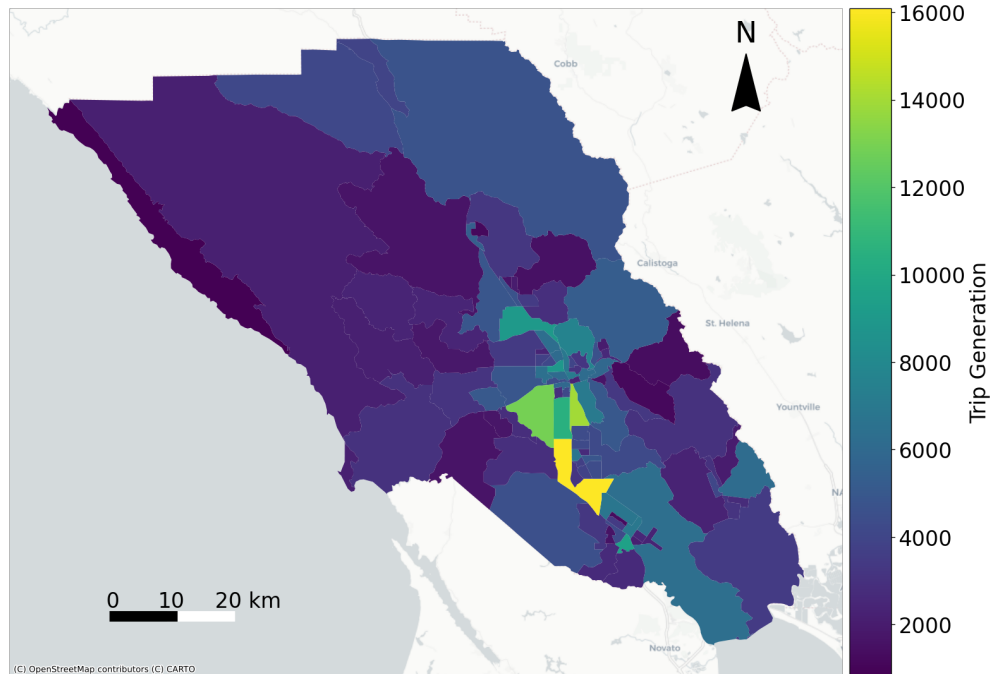
Case study: Kincadee fire

TABLE 1: Descriptive statistics of input variables

Variables	Mean	Std.	Min	Max	Category
Proportion of residential areas	38.15%	16.46%	5.23%	100%	Functional similarity graph
Proportion of commercial areas	22.40%	19.25%	1.82%	100%	
Proportion of agricultural areas	7.40%	16.32%	0.0%	100%	
Proportion of multi-family areas	26.74%	25.30%	0.0%	100%	
Population density (per sq. mile)	3339.79	3192.12	7.16	12474.63	Demographic similarity graph
Proportion of the young population	27.01%	7.68%	12.09%	54.98%	
Proportion of the white population	76.58%	12.90%	38.17%	95.54%	
Proportion of population with BA's degree and above	36.34%	12.65%	12.09%	63.62%	
Median household income (US dollar)	83823.67	20522.56	49856.0	145147.0	
Proportion of households own 0 car	7.46%	6.67%	0%	32.02%	
Proportion of households own 1 cars	36.77%	11.52%	3.65%	62.94%	
Proportion of households own 2 cars	35.60%	11.41%	10.66%	88.03%	
Proportion of households own 3 cars	13.86%	7.63%	0%	36.80%	Temporal Variables
Employment rate	95.65%	2.08%	88.96%	99.45%	
Fire distance	185.65	14.27	176.46	323.5	
Evacuation order/warning	0.10	0.29	0	1	
Day of the week	0.30	0.46	0	1	
Temperature	56.91	12.63	33.4	90.6	
Feels like temperature	56.69	12.41	33.4	86.4	
Wind speed	4.25	4.49	0.0	29.6	
Sea level pressure	1016.57	3.27	1005.9	1023.9	
Humidity	58.76	28.99	8.92	100	
Visibility	8.79	2.38	0.0	9.9	
Cloud cover	17.45	27.22	0.0	100	



Results: Trip generation inference



The mean of hourly travel demand for each census tract is 6.14, the standard deviation is 6.07, the maximum value is 56, and the minimum value is 0.

Figure. Distribution of total trip generation in Sonoma County (census-tract level)

Results: Model comparison

Performance Metrics

$$MAE = \frac{1}{n} \sum_{i=1}^n |y_i - \hat{y}_i|,$$

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2},$$

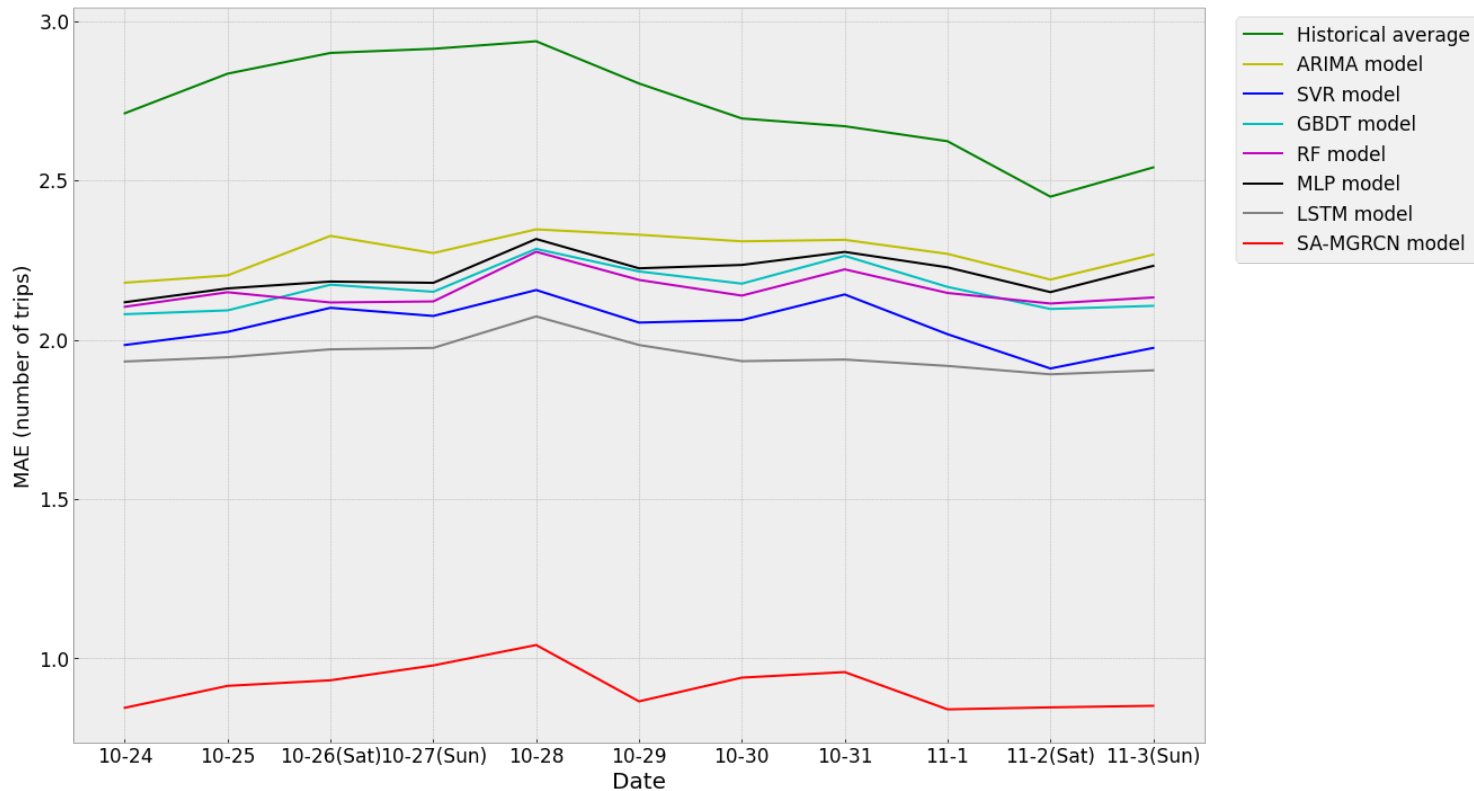
$$MAPE = \frac{100\%}{n} \sum_{i=1}^n \left| \frac{y_i - \hat{y}_i}{y_i} \right|,$$

where y_i is the observed value and \hat{y}_i is the predicted value.

TABLE 2: Prediction performance of SA-MGCRN and benchmark models

Methods	MAE	RMSE	MAPE	
HA	2.7347	3.5217	57.89%	} Statistical models
ARIMA	2.2732	2.6110	48.12%	
SVR	2.0455	2.6441	43.48%	} Classical machine learning models
GBDT	2.1641	2.3093	45.77%	
RF	2.1553	2.8008	45.63%	
MLP	2.2092	2.7356	46.77%	} Deep learning models
LSTM	1.9512	2.1262	41.27%	
SA-MGCRN	0.9095	1.1224	20.13%	

Results: Model comparison



Results: Ablation study

The ablation study examines the performance of the model by **removing certain components to see the contribution of the removed components.**

TABLE 3: Results of ablation study

Methods	MAE	RMSE	MAPE
SA-MGCRN	0.9095	1.1224	20.13%
W/O whether the day is weekend	0.9368	1.1644	20.82%
W/O evacuation order/warning information	0.9583	1.2135	21.21%
W/O spatial adjacency	1.0463	1.3356	23.16%
W/O functional similarity	1.0032	1.3098	22.20%
W/O demographic similarity	1.0369	1.3273	22.95%
W/O weather information	1.3781	1.4256	30.50%
W/O fire distance information	1.6133	1.7215	35.71%

Key take-aways

- A new deep learning model, SA-MGCRN, along with a model updating scheme, is developed to accurately forecast real-time travel demand in wildfire evacuations.
- SA-MGCRN can be directly deployed to facilitate real-time emergency management and revolutionize the state-of-the-practice.
- Fire proximity is the most important component of SA-MGCRN. In future work, other fire cues (e.g., smoke and embers) need to be incorporated.

Acknowledgement

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Thank you for your attention!

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