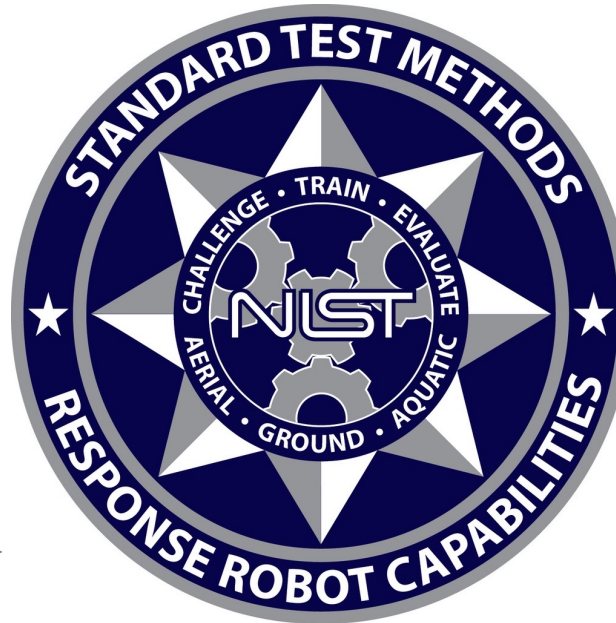


# ASTM E54.09 Homeland Security Applications; Response Robots Ground Tests: Sensors and Mapping

Version 2022A



**STARTS AT 10:00 AM EST  
WASHINGTON, DC TIME**

*Sub Committee Chair*

**Adam Jacoff**

Intelligent Systems Division  
National Institute of Standards and Technology  
U.S. Department of Commerce

*Committee Chair:*

**Phil Mattson**

Science and Technology Directorate  
U.S. Department of Homeland Security

Internet  
[RobotTestMethods.nist.gov](https://RobotTestMethods.nist.gov)



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[RobotTestMethods@nist.gov](mailto:RobotTestMethods@nist.gov)

# Sensing: Visual Acuity Test

## ASTM E2566-2017

MORE CONTINUOUS TARGETS

DIFFERENT LEVELS OF ACUITY

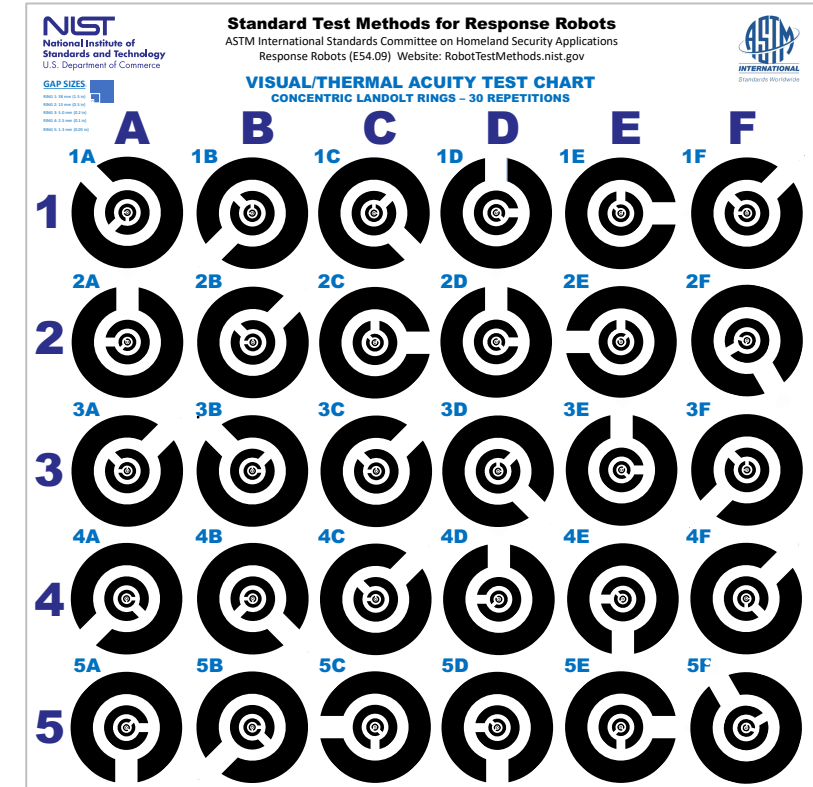
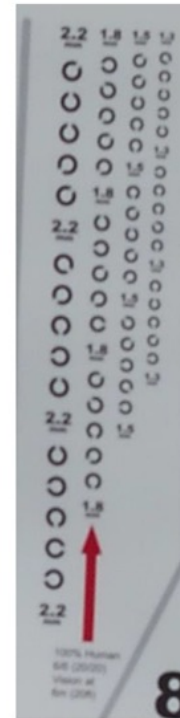
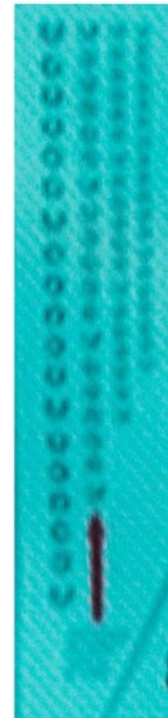
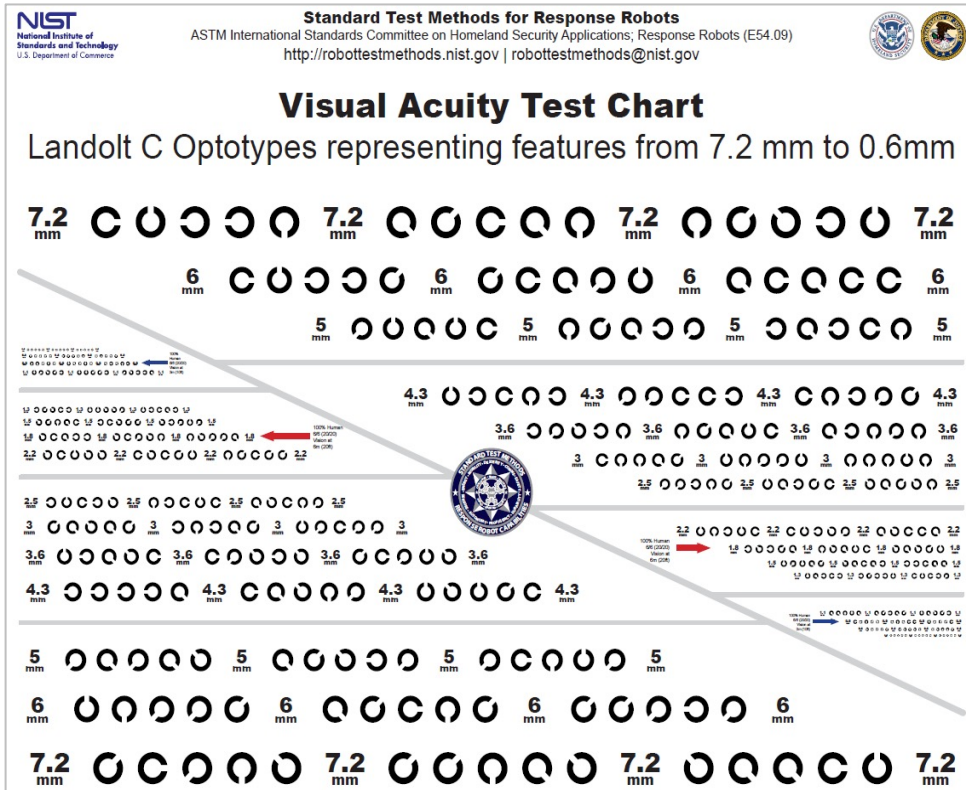
5 DEEP CONCENTRIC C TARGETS

Interface Streamed Recovered

LIVE

BETTER

BEST



# Sensing: Color Acuity Test

## ASTM WK54755

### COLOR DOTS

### ROTATING HAZMAT LABELS

**NIST**  
National Institute of  
Standards and Technology  
U.S. Department of Commerce

**Standard Test Methods for Response Robots**  
ASTM International Standards Committee on Homeland Security Applications  
Response Robots (E54.09) | <http://RobotTestMethods.nist.gov>

**ASTM**  
INTERNATIONAL  
Standards Worldwide

**COLOR ACUITY TEST CHART**  
6 RANDOM HAZMAT LABEL COLORS - 30 REPETITIONS  
Colors as specified in 49 CFR (Code of Federal Regulations) 172.407(d)

Colors:  
Red (phone 300-0)  
Orange (phone 300-0)  
Yellow (phone 300-0)  
Green (phone 300-0)  
Blue (phone 300-0)  
Black

	A	B	C	D	E	F
<b>1</b>	1A	1B	1C	1D	1E	1F
<b>2</b>	2A	2B	2C	2D	2E	2F
<b>3</b>	3A	3B	3C	3D	3E	3F
<b>4</b>	4A	4B	4C	4D	4E	4F
<b>5</b>	5A	5B	5C	5D	5E	5F

**NIST**  
National Institute of  
Standards and Technology  
U.S. Department of Commerce

**Standard Test Methods for Response Robots**  
ASTM International Standards Committee on Homeland Security Applications  
Response Robots (E54.09) | <http://RobotTestMethods.nist.gov>

**ASTM**  
INTERNATIONAL  
Standards Worldwide

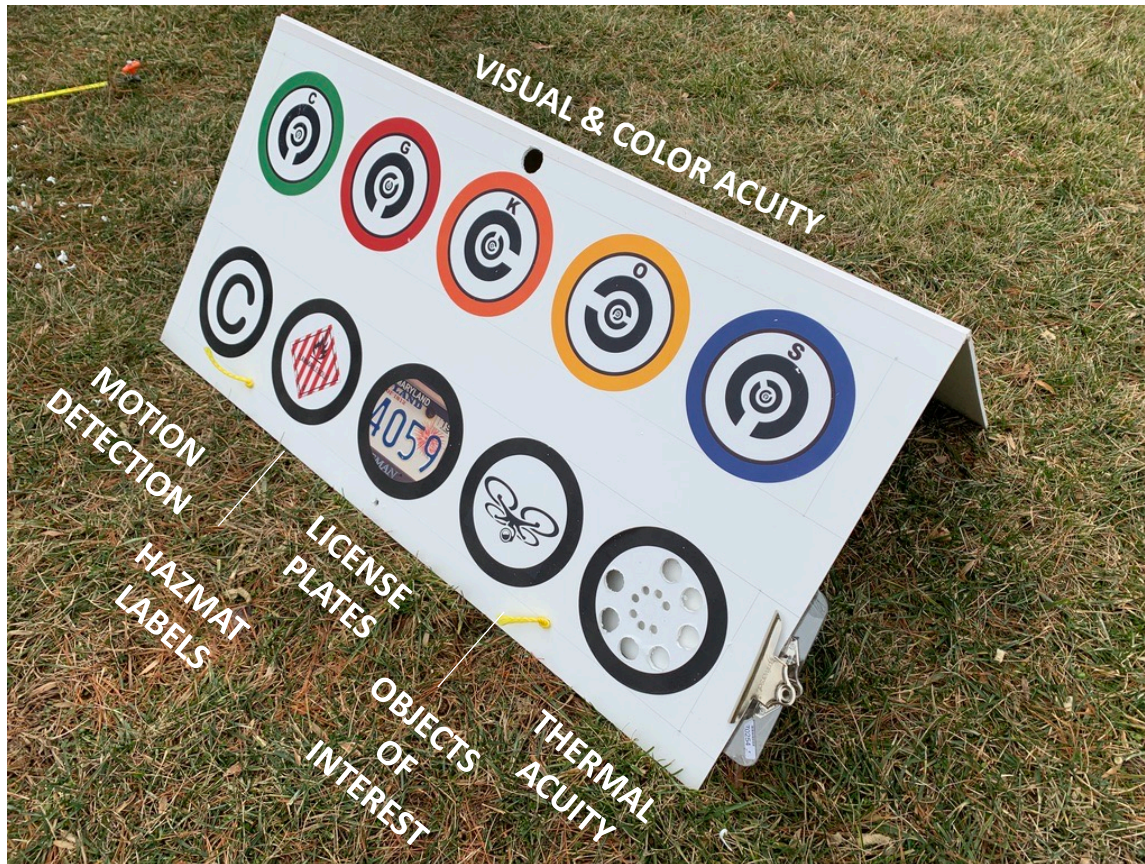
**HAZARDOUS MATERIAL LABEL TEST CHART**  
30 RANDOM, RANDOMLY ORIENTED 100 MM (4 IN) LABELS

	A	B	C	D	E	F
<b>1</b>	1A	1B	1C	1D	1E	1F
<b>2</b>	2A	2B	2C	2D	2E	2F
<b>3</b>	3A	3B	3C	3D	3E	3F
<b>4</b>	4A	4B	4C	4D	4E	4F
<b>5</b>	5A	5B	5C	5D	5E	5F

# Sensing: Point and Zoom Camera Test

## ASTM WK33261

Visual, Color, Motion, Thermal, and Operationally Significant Objects



LICENSE  
PLATES

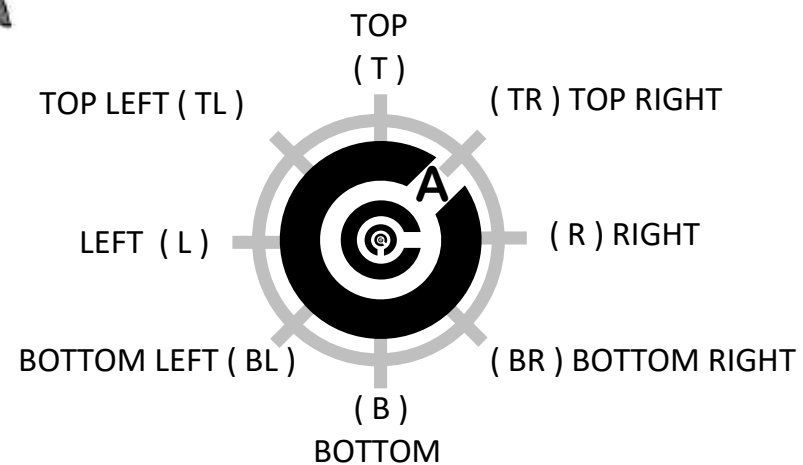
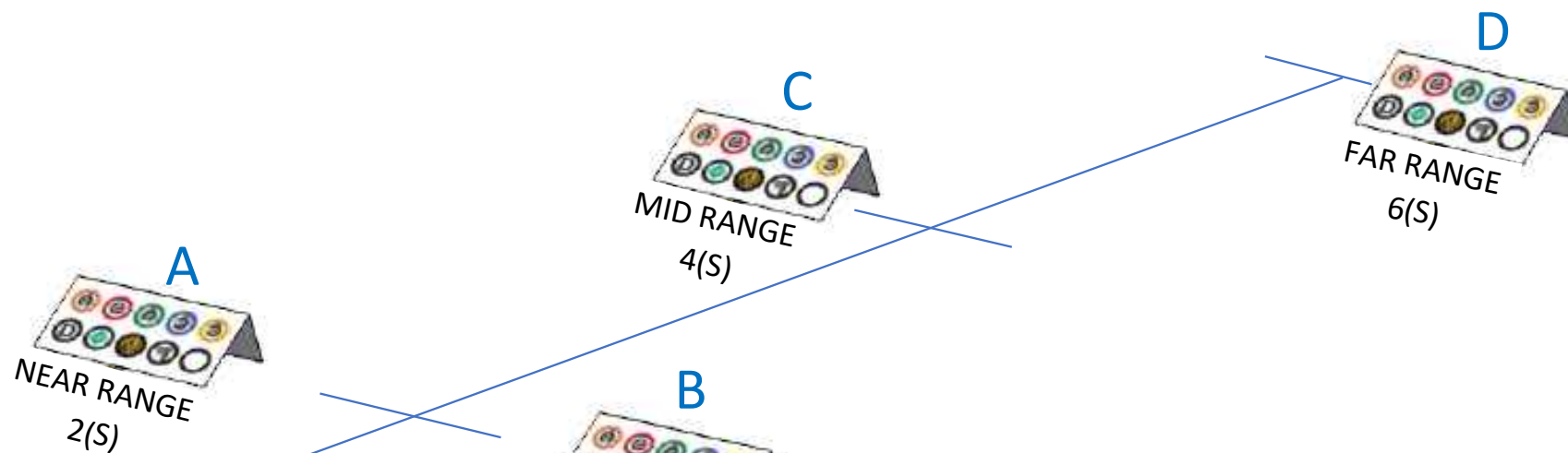
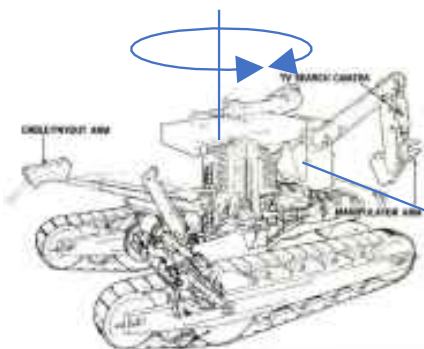
OBJECTS OF  
INTEREST

THERMAL  
HAND WARMER

# Sensing: Point and Zoom Camera Test

## ASTM WK33261

ROBOT ROTATES IN PLACE AND STAYS ENTIRELY BEHIND THE LINE



# Sensing: Point and Zoom Camera Test

## ASTM WK33261

[WATCH MOVIE OF ASSEMBLY PROCESS HERE](#)



Thermal acuity circular hole patterns. The large holes are 1 inch diameter and small holes are 1/2 inch diameter. One of the 8 directions is missing, like the gap on the visual acuity targets. There is a sticker template to drill through in the Disk Insert file.



A simpler approach is to fold a hand warmer into roughly a line and staple it to the panel vertical, horizontal, or diagonal



# Sensing: Motion Detection

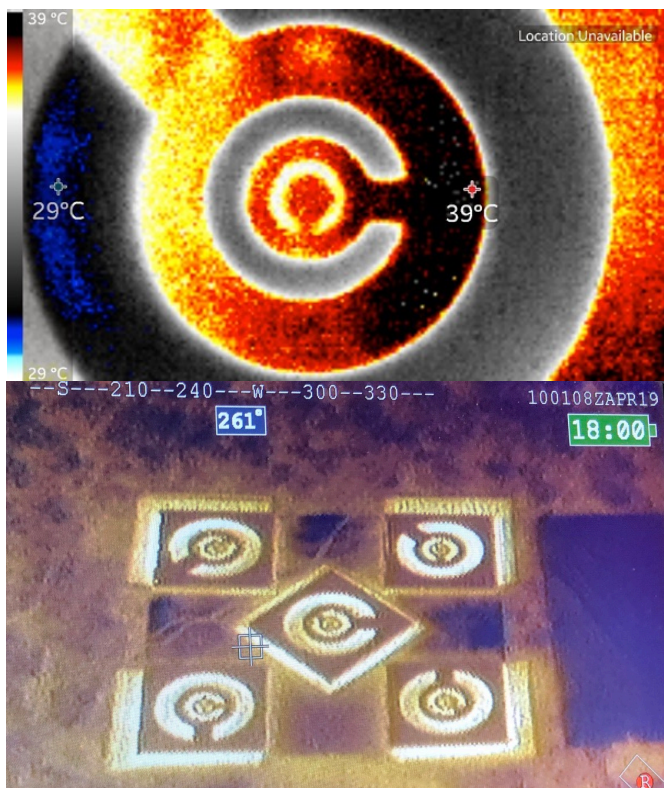
ASTM WK \_\_\_\_\_



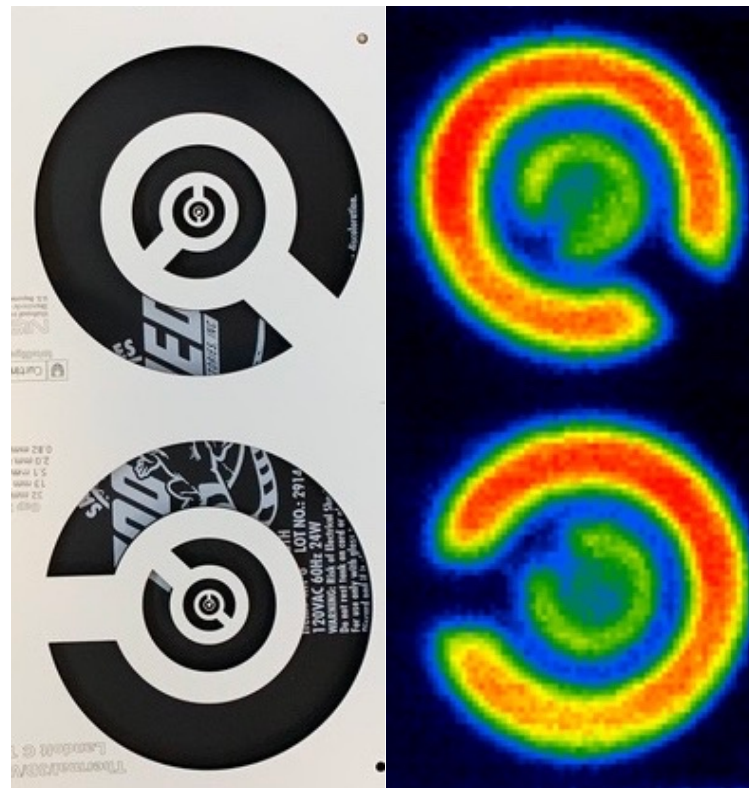
# Sensing: Thermal Image Acuity

## ASTM WK57967

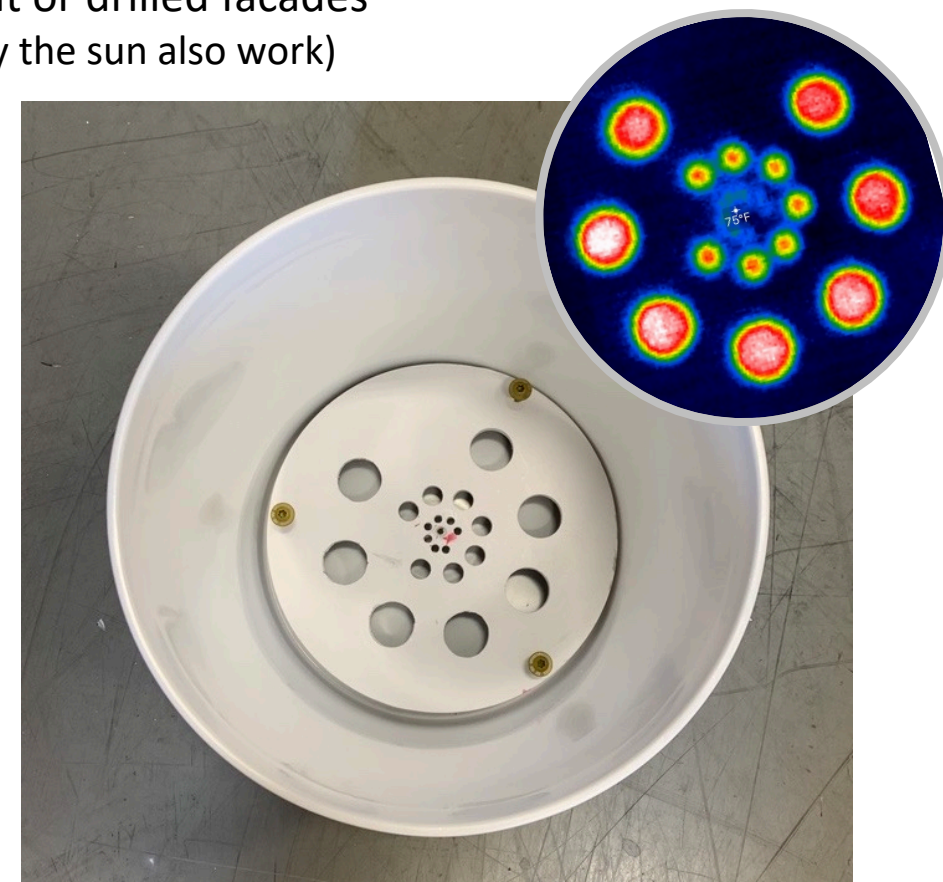
Heated reptile pads or hand warmers behind laser cut or drilled facades  
(Indoor or outdoor use – typical sticker targets warmed by the sun also work)



An array of Concentric C thermal targets placed throughout a scenario (needs power).



Concentric Cs laser cut into MDF with a reptile heater. A metal backing helps diffuse the heat.



Drill Holes (1in, 1/2in, 1/4in) through plastic disks with hand warmers heating a metal disk backing.



# Sensing: Video Latency

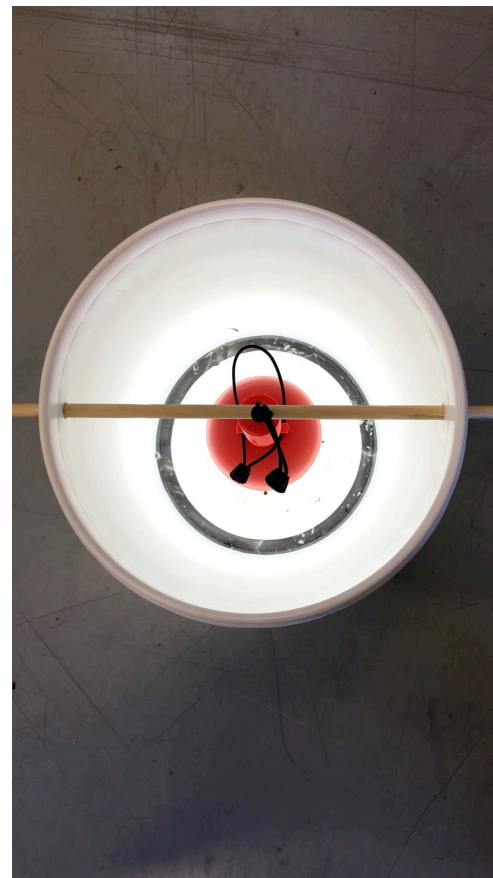
## ASTM WK46478

Latency test with flashing “SOS” beacon or other light

High speed camera video (240 fps) captures flash in field AND flash on display views simultaneously.



Count the frames  
between flashes



# Sensing: Remote Latency and Packet Loss

## ASTM WK46478

COMPUTER READABLE CODES  
SYNCRONIZED AT BOTH ENDS

HUMAN READABLE CLOCKS  
SYNCRONIZED AT BOTH ENDS

UP RANGE WITH OCU  
(VIDEO CAPTURE WITH INTERFACE)

UP RANGE WITH OCU  
(VIDEO CAPTURE WITH INTERFACE)



DOWN RANGE WITH ROBOT  
(VIEWED THROUGH INTERFACE)

DOWN RANGE WITH ROBOT  
(VIEWED THROUGH INTERFACE)

# Sensing: Audio Acuity (2-Way)

ASTM WK60783

Alpha-numeric list read by a computer voice

Loudness set to 75-80 dB

AUDIO ACUITY TEST1.

0 MISSES IN 2 LINES ALLOWED. 0 IN 10 NUMBERS.  
1 MISS IN 3 LINES ALLOWED. 1 IN 15 NUMBERS.  
2 MISSES IN 5 LINES ALLOWED. 2 IN 25 NUMBERS.  
3 MISSES IN 6 LINES ALLOWED. 3 IN 30 NUMBERS.

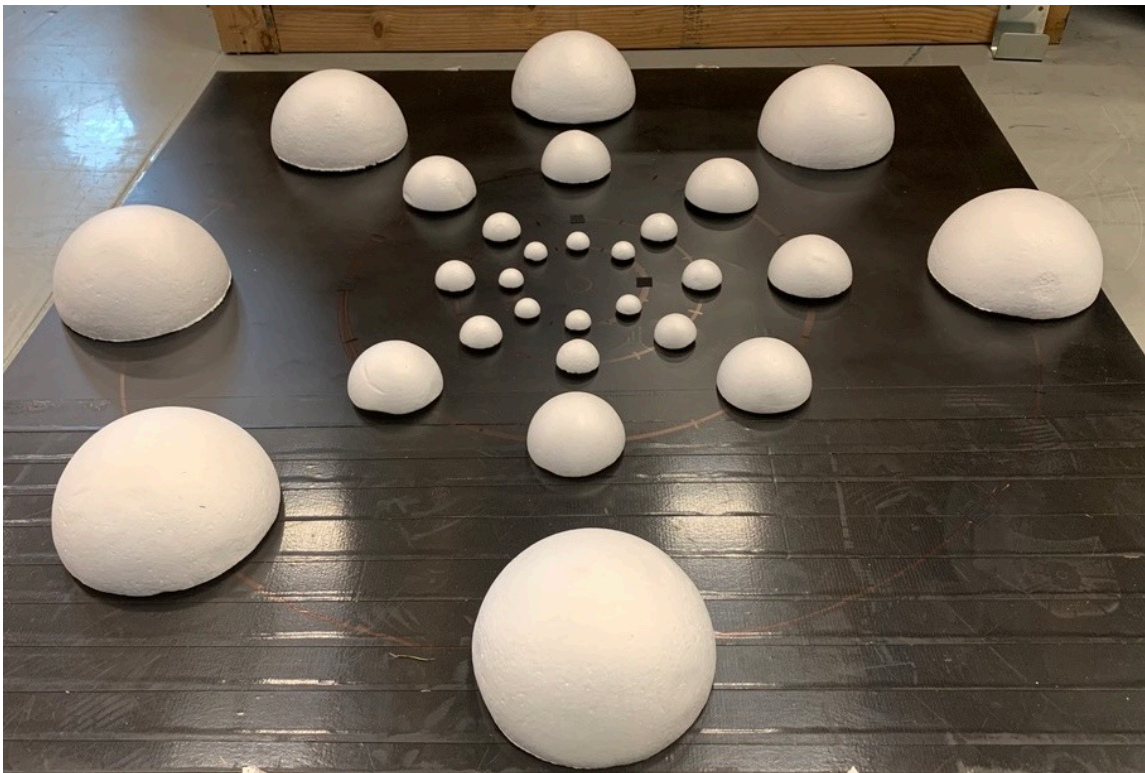
A!	1.	2.	3.	4.	5.	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>
B!	6.	2.	3.	5.	4.	<u>6</u>	<u>2</u>	<u>3</u>	<u>5</u>	<u>4</u>
C!	2.	5.	9.	8.	7.	<u>2</u>	<u>5</u>	<u>9</u>	<u>8</u>	<u>7</u>
D!	7.	2.	8.	9.	5.	<u>7</u>	<u>2</u>	<u>8</u>	<del><u>8</u></del>	<u>5</u>
E!	3.	4.	9.	1.	0.	<u>3</u>	<u>4</u>	<u>9</u>	<u>1</u>	<u>0</u>
F!	5.	8.	0.	2.	9.	<u>5</u>	<u>8</u>	<u>0</u>	<u>2</u>	<u>9</u>
G!	6.	9.	7.	3.	8.	<u>6</u>	<u>9</u>	<u>7</u>	<u>3</u>	<u>8</u>
H!	2.	0.	5.	2.	7.	<u>2</u>	<u>0</u>	<u>5</u>	<u>2</u>	<u>7</u>
I!	3.	5.	2.	8.	9.	---	---	---	---	---
J!	7.	2.	6.	1.	6.	---	---	---	---	---
K!	8.	3.	3.	4.	5.	---	---	---	---	---



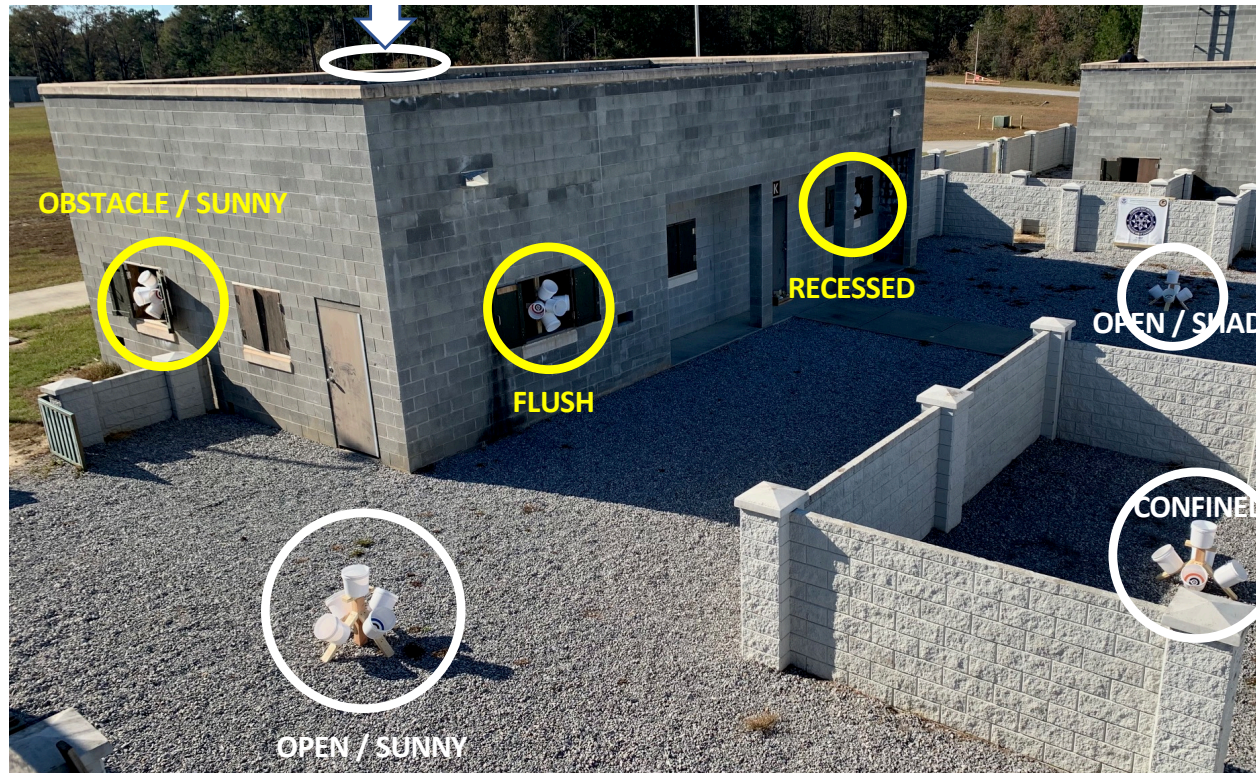
# Sensing: 3D Range Imagers and Scanners

ASTM WK \_\_\_\_\_

## Resolution



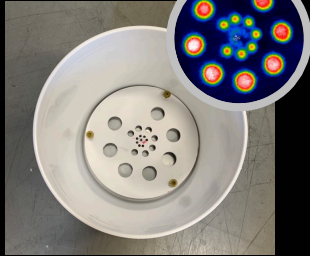
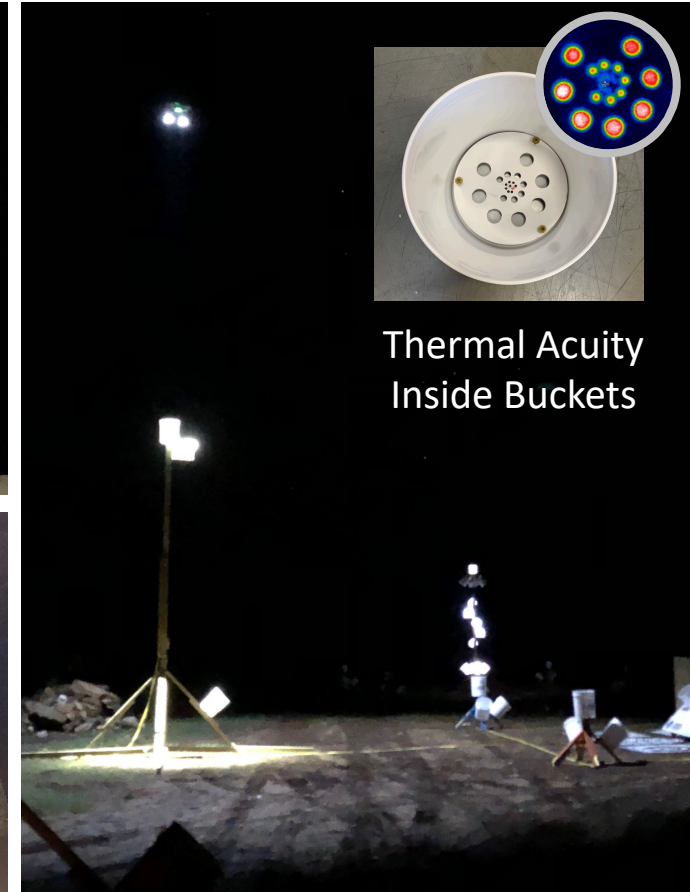
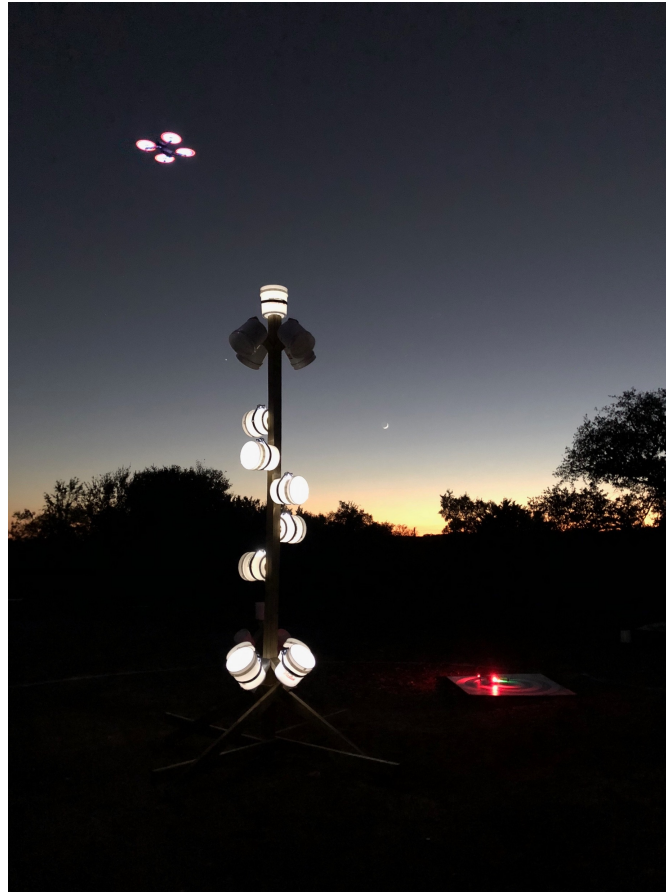
## Mapping



# Sensing: Light Emissions

ASTM WK \_\_\_\_\_

WHITE OR RED HEADLAMPS  
WRAPPED AROUND BUCKETS POINTED INWARD



Thermal Acuity  
Inside Buckets

Position accuracy for range to target  
using lighted buckets (red or white)

Inspect objects of interest  
using lighted buckets (red or white)

Identify objects  
lighted from the aircraft

Measure additional  
sensor capabilities

# Sensing: Combined Sensor/Dexterity Crates (aka "Victim" Crates)

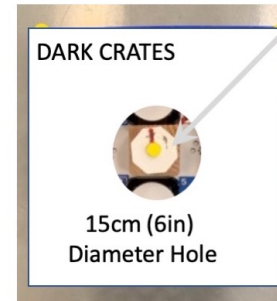
WK \_\_\_\_\_



LIGHTED CRATES



CENTER DEXTERITY PIPE TASKS  
(BLOCKS VIEWS WHEN NOT CENTERED.  
BUT IS USED ONLY TO DETERMINE ROBOT  
DEXTERITY CONFIGURATION MULTIPLIERS)



HAZMAT LABEL  
IDENTIFICATION  
(x2)

VISUAL/COLOR  
ACUITY  
(x2)



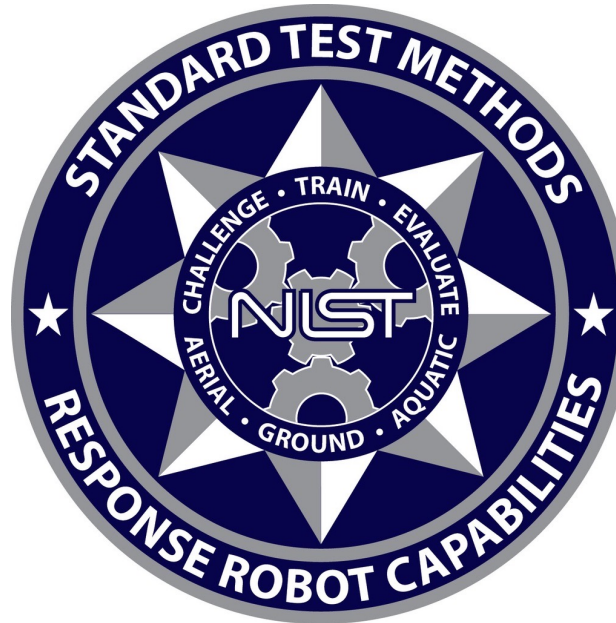
MOTION  
DETECTION  
(x2)

THERMAL IMAGE  
RESOLUTION  
(x2)

PROXIMITY SAMPLING  
MAGNETS IN CORNERS  
AND CENTER (x5)

# Radio Comms Range Tests

## Ground Robots



*Test Director:*

**Adam Jacoff**

Intelligent Systems Division  
National Institute of Standards and Technology  
U.S. Department of Commerce

*Sponsor:*

**Phil Mattson**

Science and Technology Directorate  
U.S. Department of Homeland Security

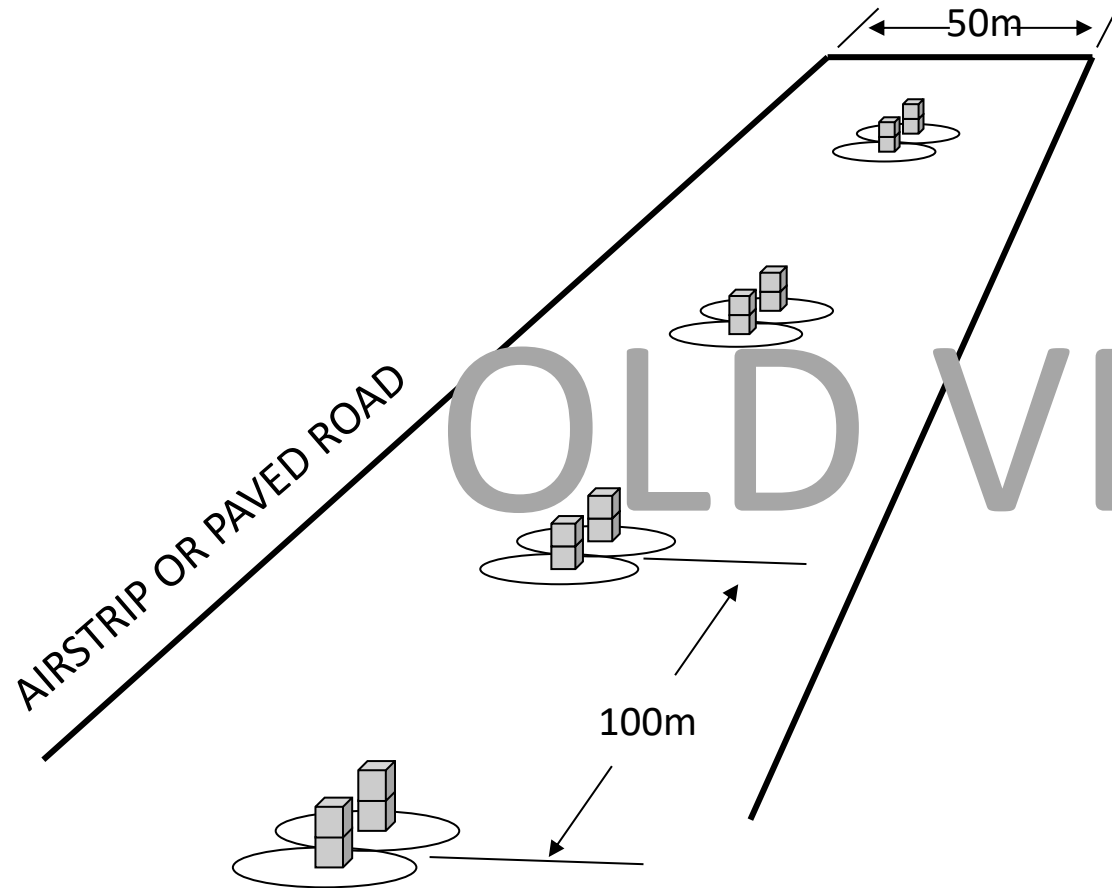
Internet  
[RobotTestMethods.nist.gov](http://RobotTestMethods.nist.gov)



Email  
[RobotTestMethods@nist.gov](mailto:RobotTestMethods@nist.gov)

# Radio Comms: Line-of-Sight Range

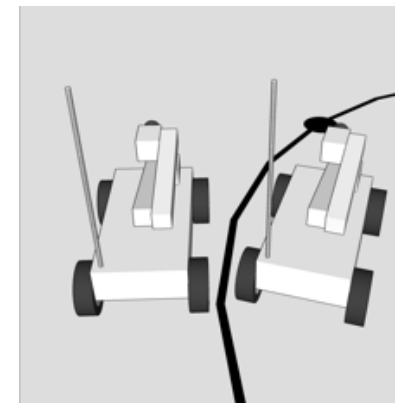
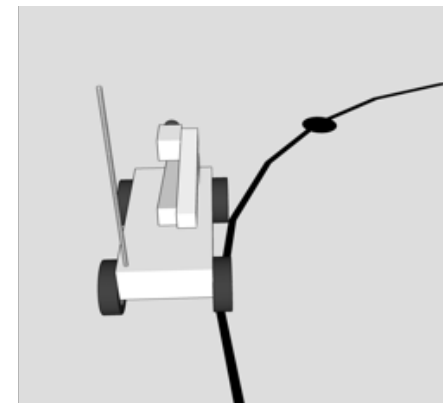
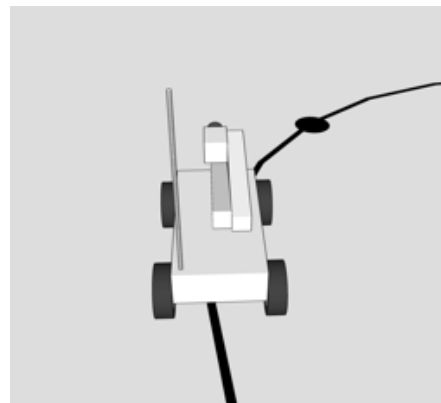
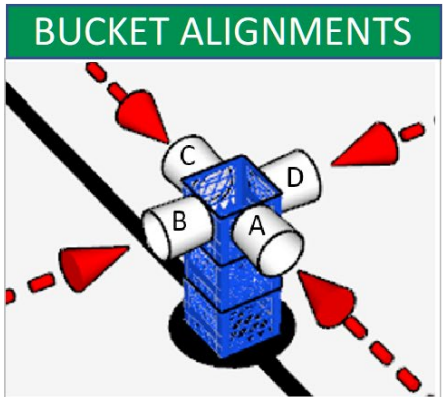
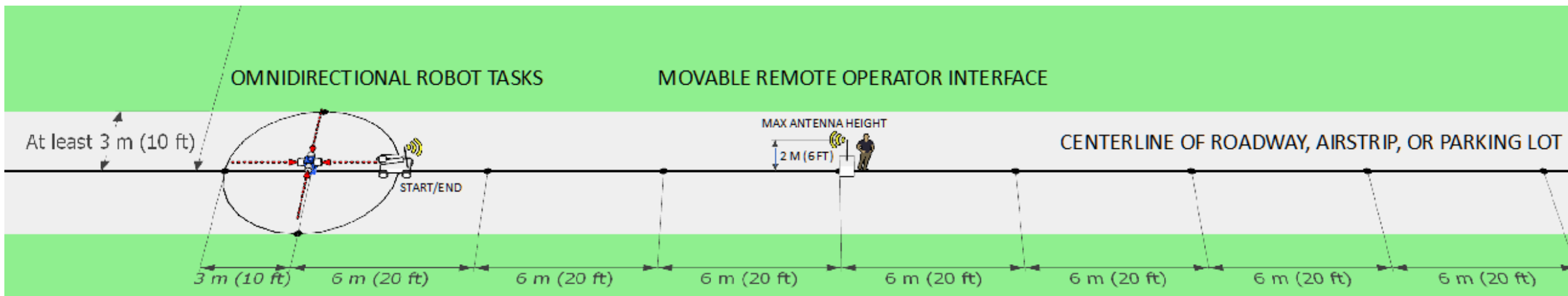
ASTM E2854-2013





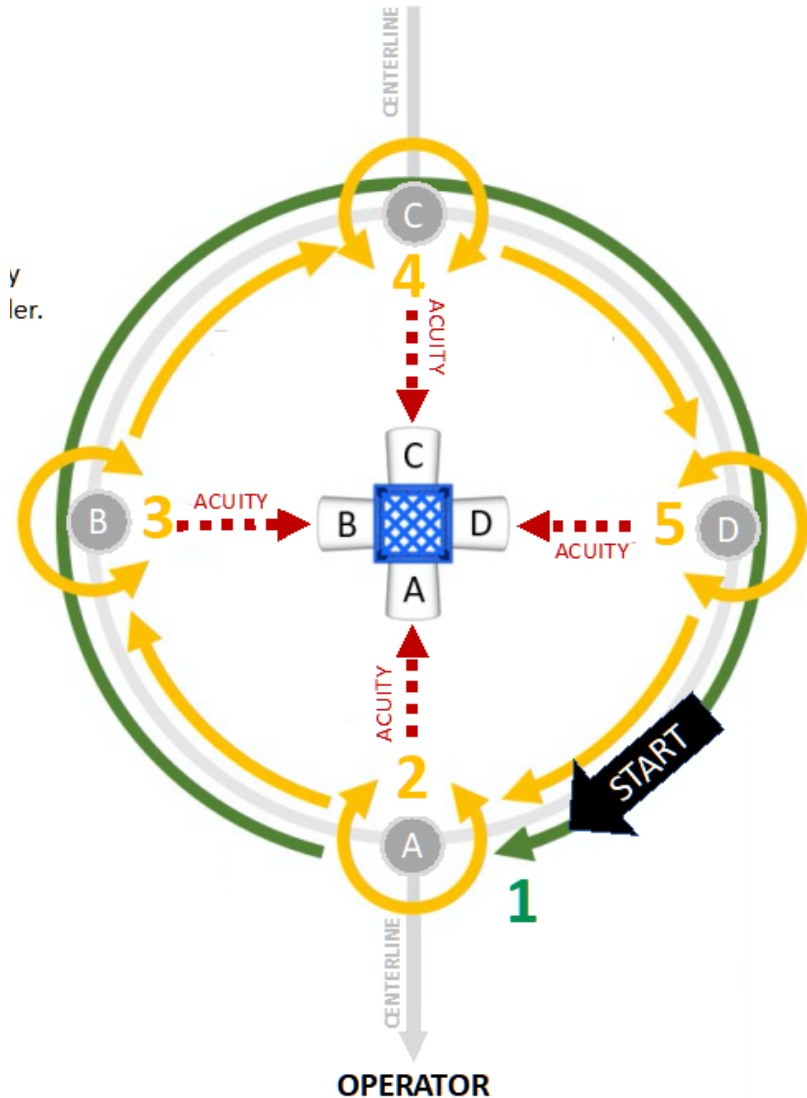
# Radio Comms: Line-of-Sight Range

## ASTM E2854-2020

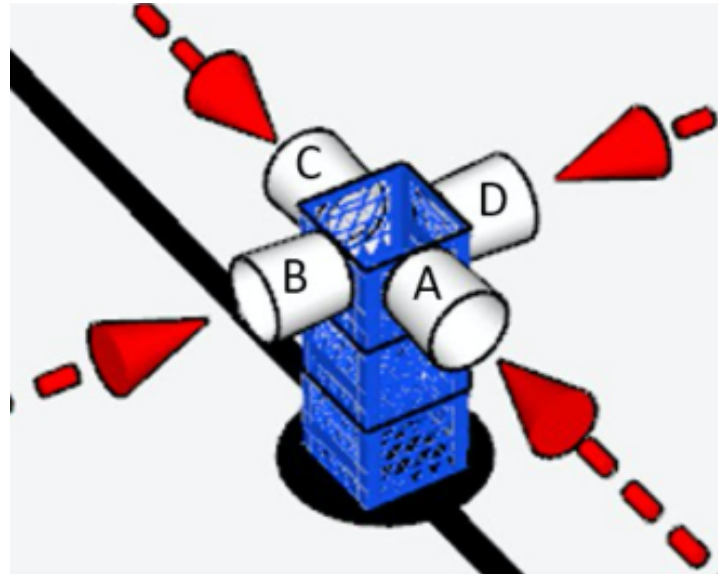


# Radio Comms: Line-of-Sight Range

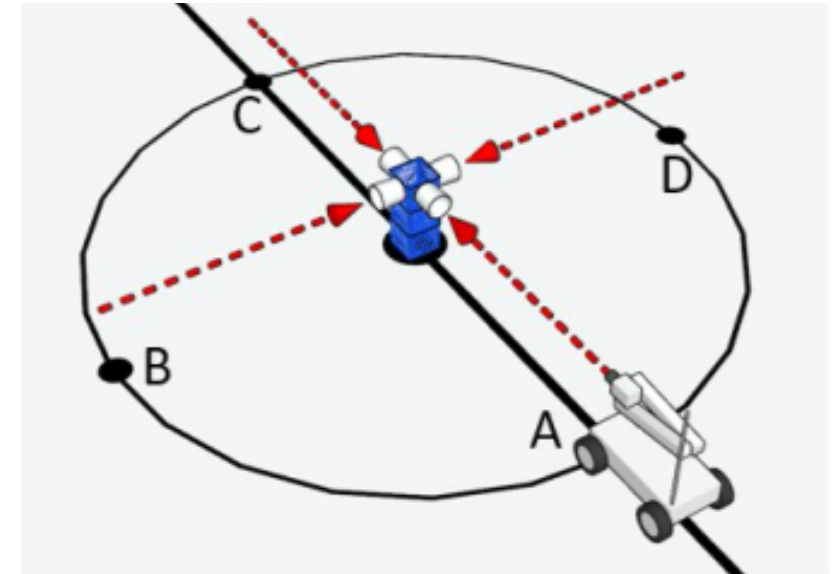
ASTM E2854-2020



PERPENDICULAR BUCKETS



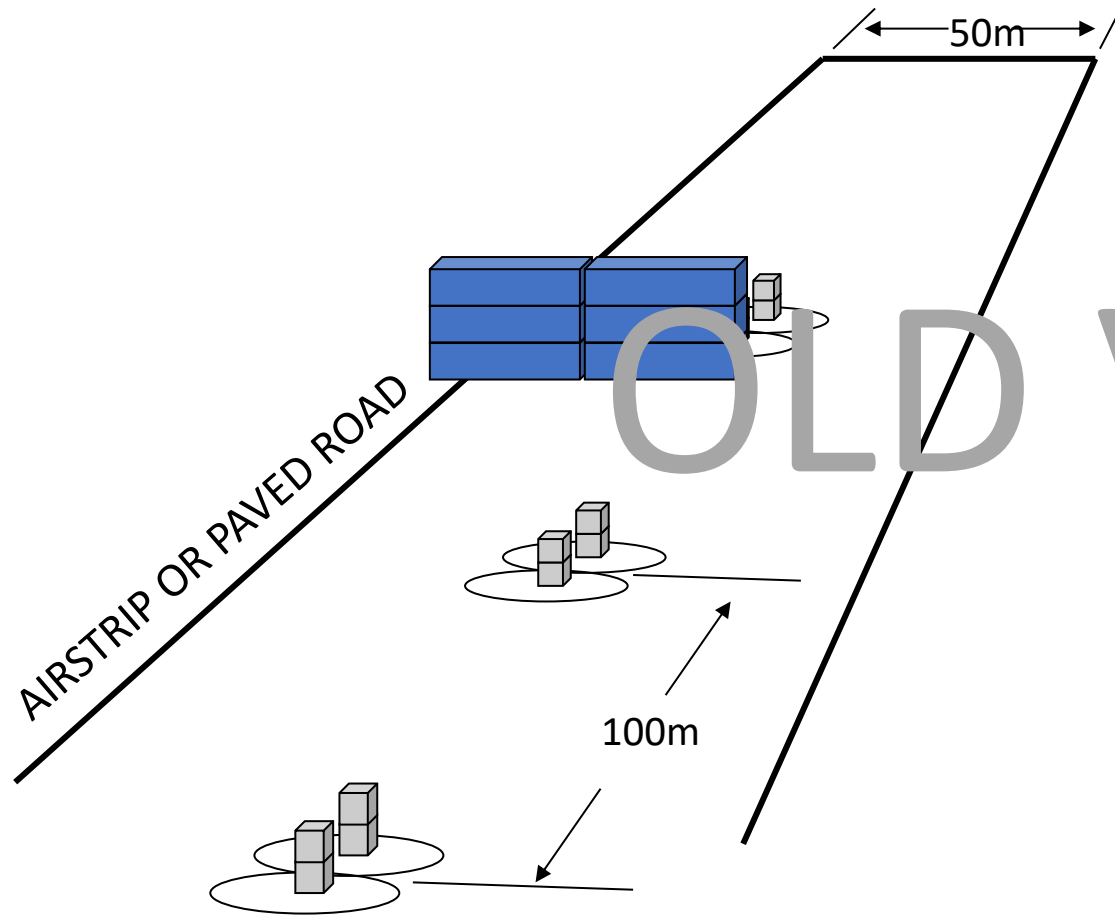
BUCKET IDENTIFICATION POSITION



Maneuvering Tasks (5 points) and Visual Acuity Tasks (20 Points)

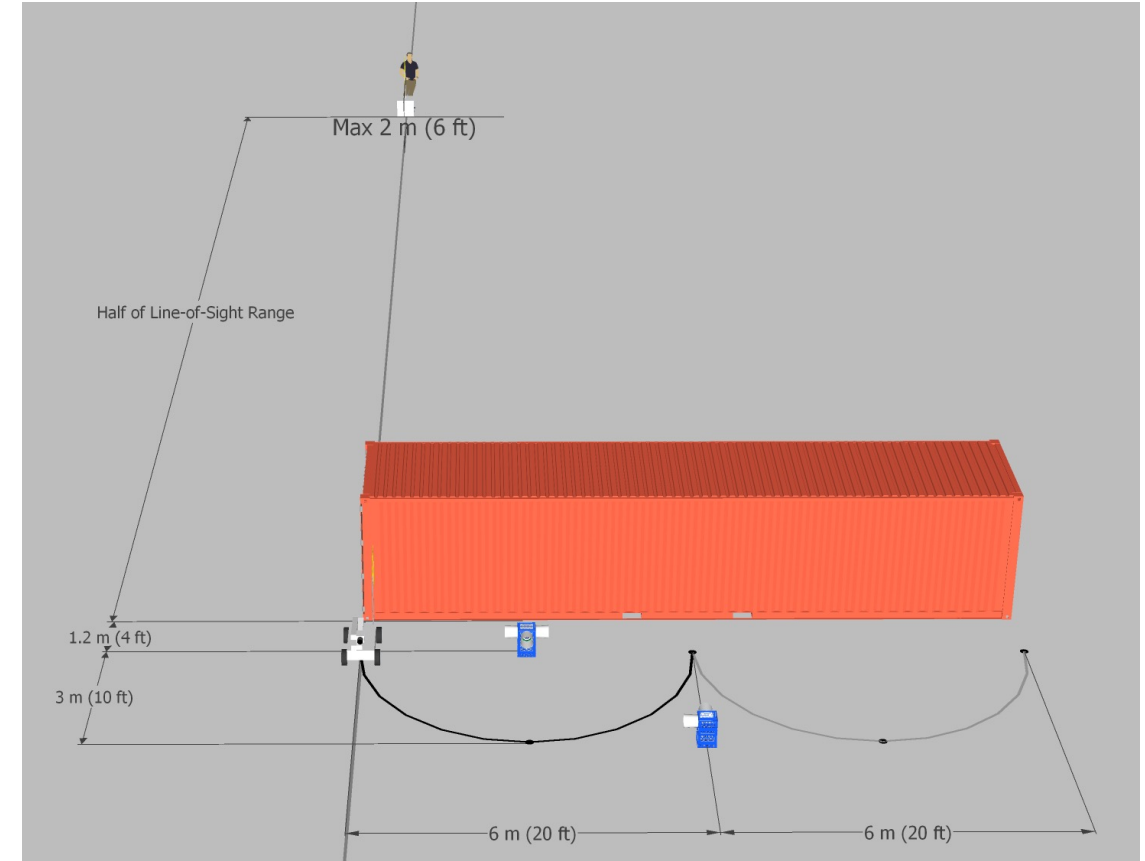
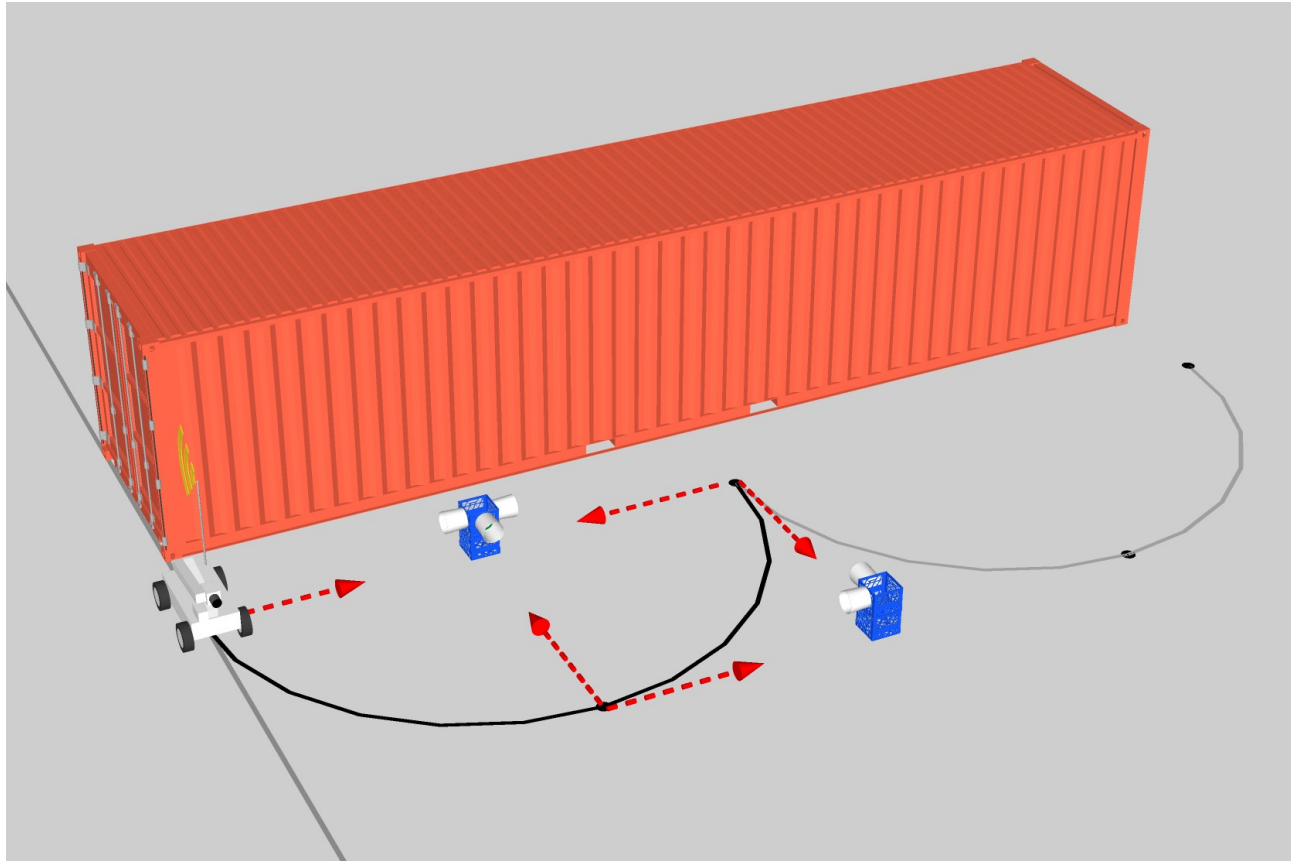
# Radio Comms: Non-Line-of-Sight Range

ASTM E2855-2013



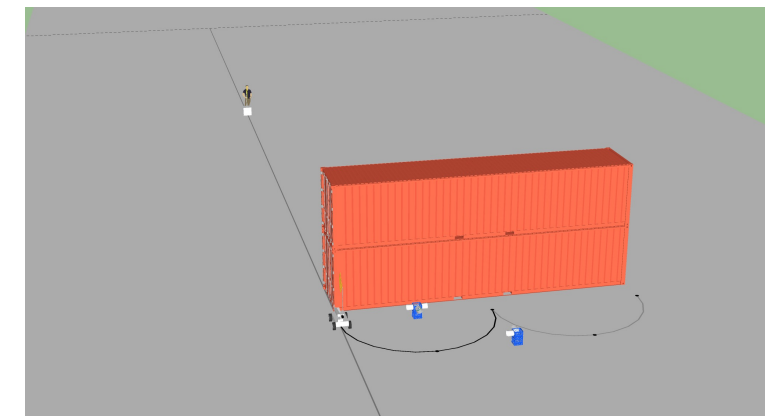
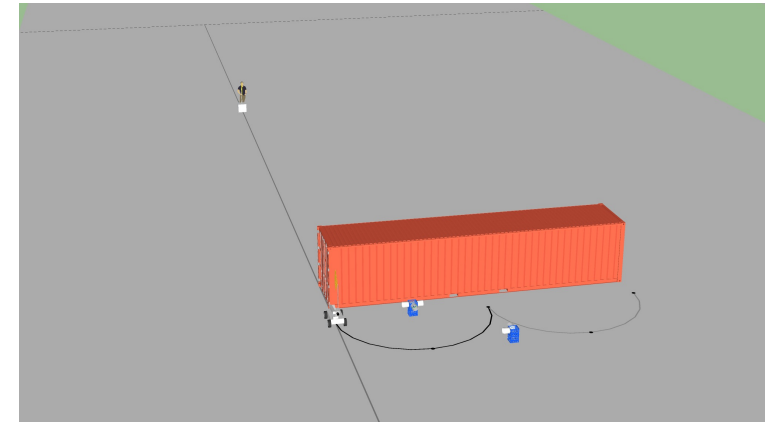
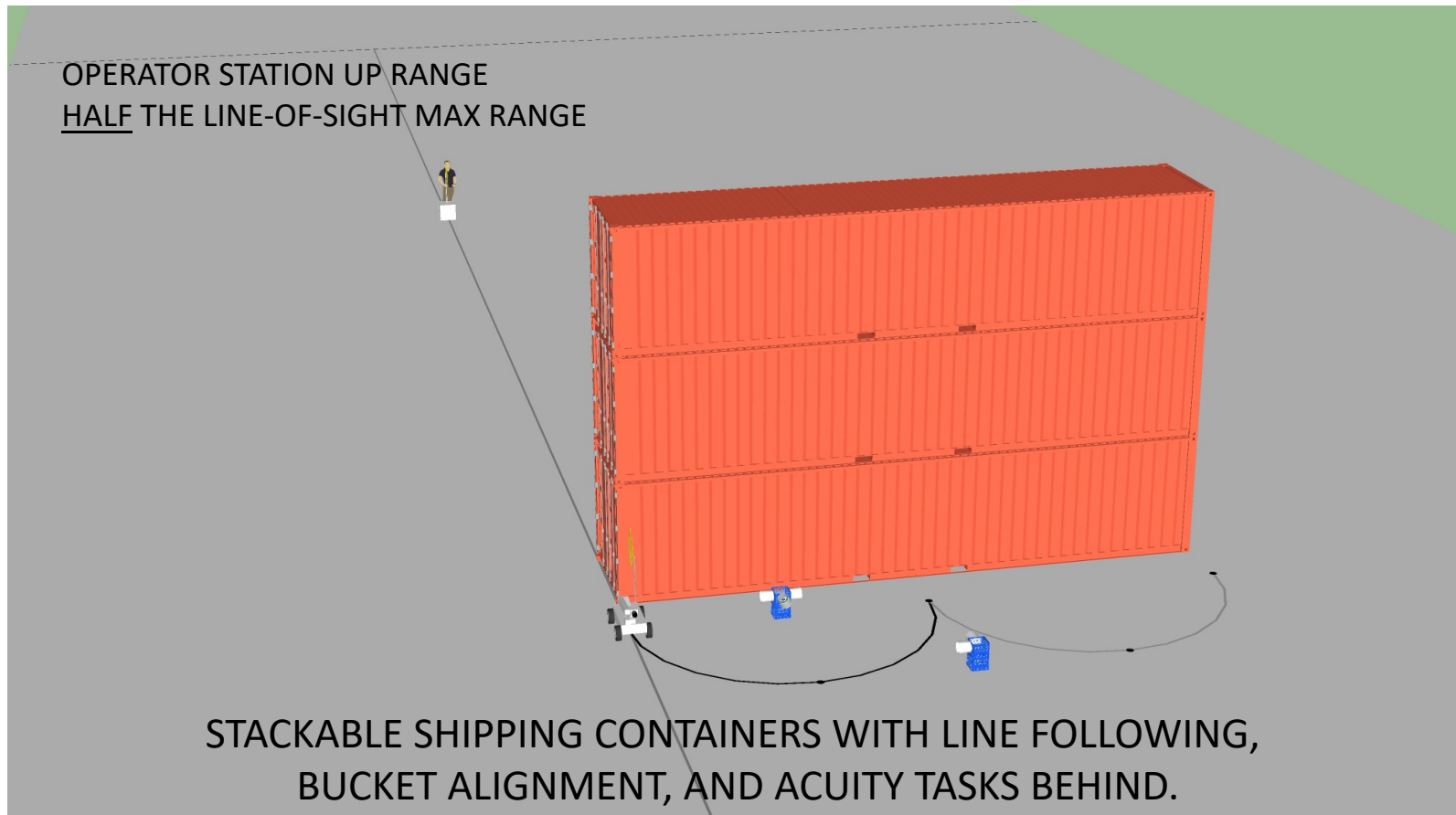
# Radio Comms: Non-Line-of-Sight Range

## ASTM E2855-2021



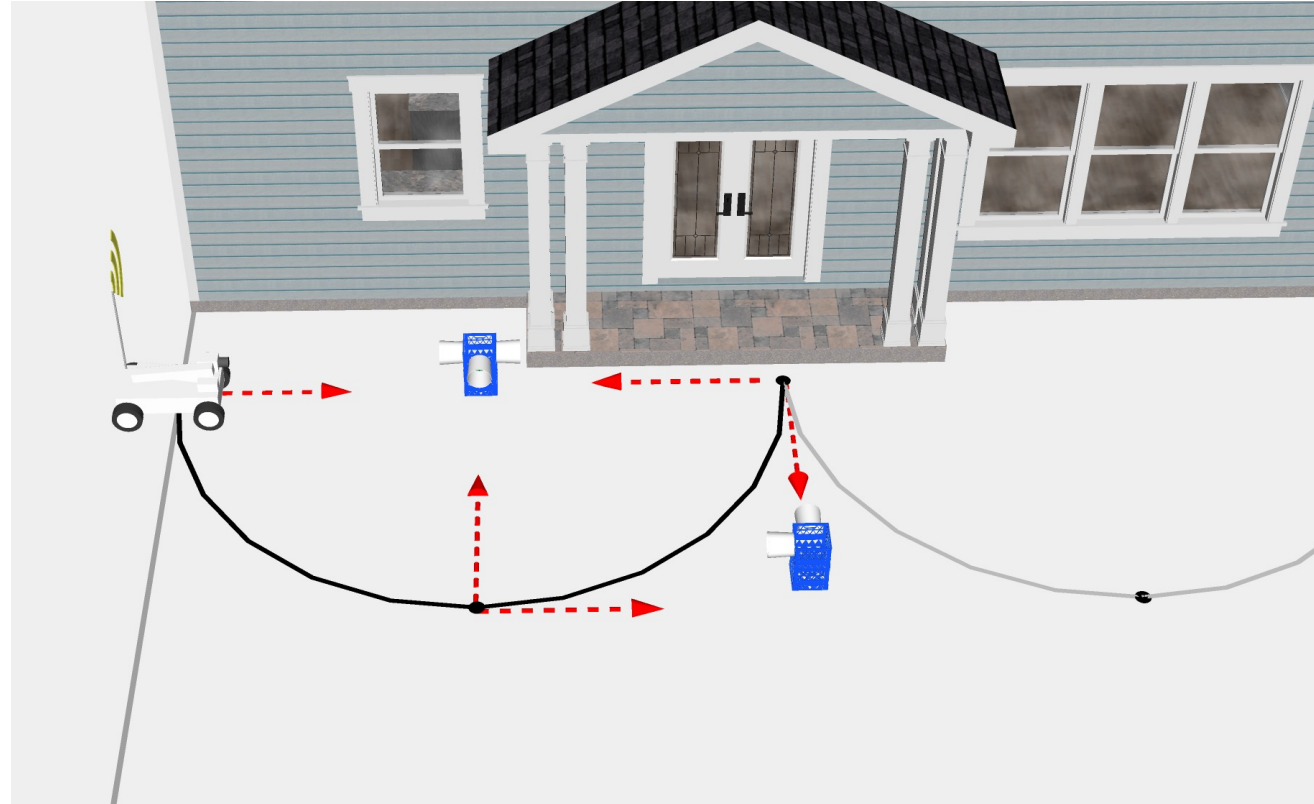
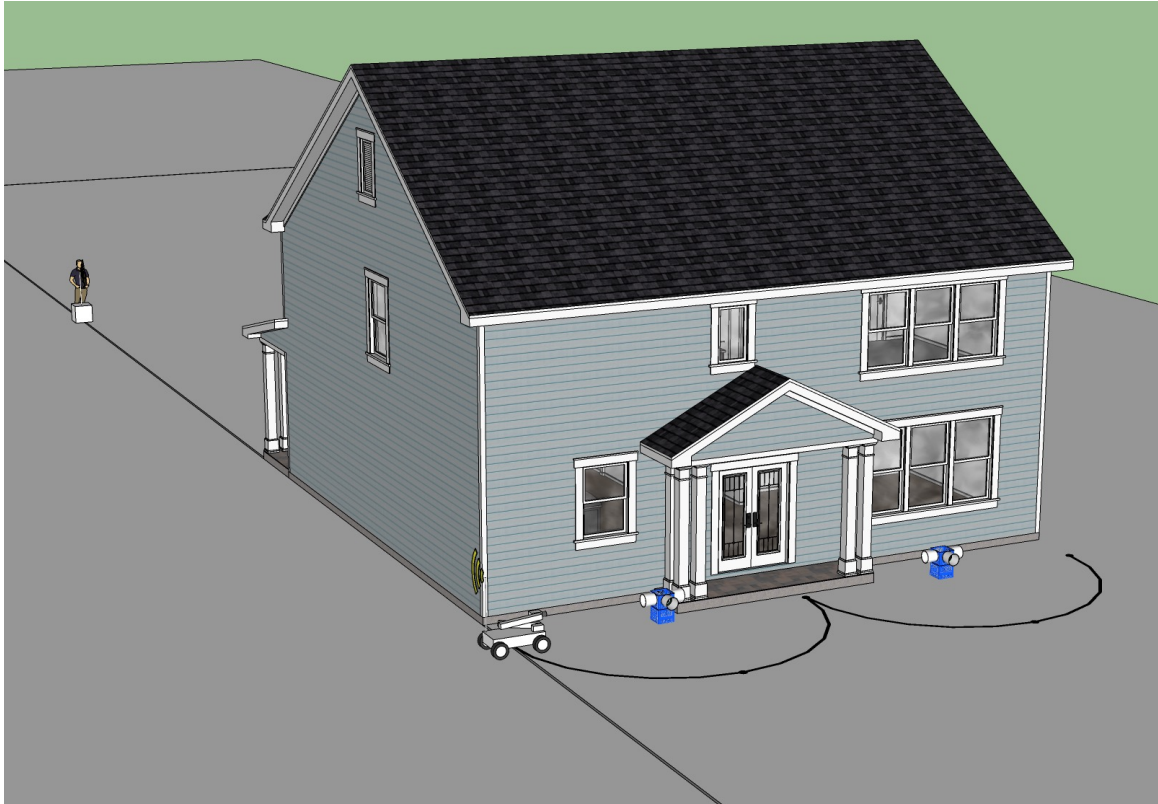
# Radio Comms: Non-Line-of-Sight Range

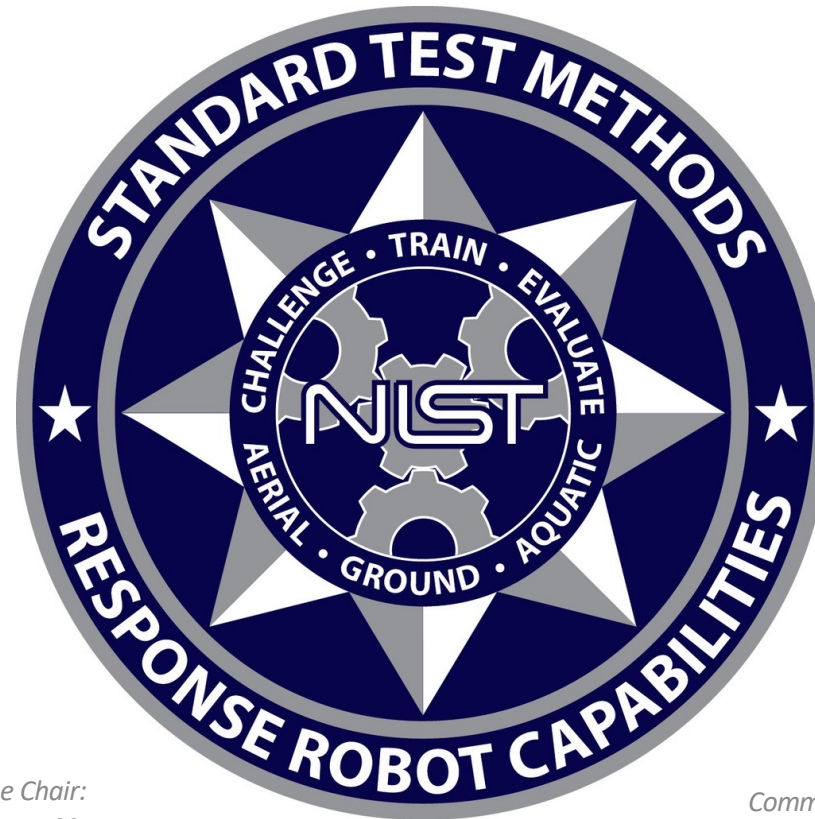
## ASTM E2855-2021



# Radio Comms: Non-Line-of-Sight Range

## ASTM E2855-2021





*Sub Committee Chair:*

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Intelligent Systems Division  
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