Teams Rotate Through Each Role

Each Pilot flies a 5-minute trial with help from others. A 3-4 person team completes all 5 tests in 2 hours.



Four person teams always have one person getting their aircraft ready to launch right after the previous lands.

Three person teams work too, but require some time

PILOT

- Maintain control of the aircraft.
- Call out each intention of movement be
- Call out each bucket alignment and acu kt gap.

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PROCTOR

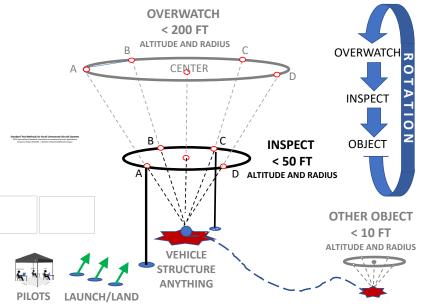
- Fill in the form header.
- Read the test procedures to the Pilot.
- Confirm, record, and attest to scoring after the trial.

VISUAL OBSERVER (VO)

- Maintain sight with the aircraft and surroundings.
- Repeat the Pilot's intention of movement to confirm.
- Call out corrections and warnings as necessary.

Teams Sequence Through Scenarios

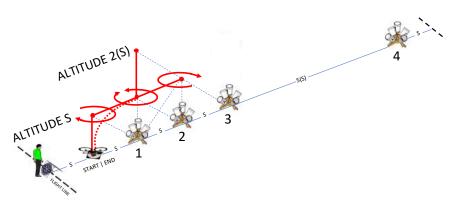
Each Pilot flies a 15-minute scenario, sequencing through 3 objectives for 5 minutes each.



- This scenario mechanization enables embedded bucket scoring tasks to be performed similarly by all participating Pilots. So the results are comparable within the same scenario layout. Additional tactics can be overlayed onto these scenarios at your facility.
- Up to 3 teams concurrently fly different scenario objectives from safe distances and altitudes apart.
- Teams move as necessary to maintain sight lines with their aircraft and communications with other teams. The overwatch team leads communications.
- Scenarios restart every 20 minutes with a different rotation of Pilot, Proctor, and VO.

Position (MAN/PAY 1)

Open Test Lane

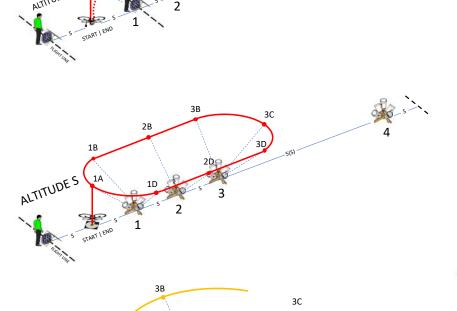


- Demonstrate positive aircraft control using basic flight MAN maneuvers between designated hover positions, orientations, and altitudes along the lane centerline.
- Perform a series of maneuvers including climb, wescend, vaw, pitch, and roll to simultaneously align with down waxd and forward buckets in each position.
- band accurately on the platform with the chassis CENTERED (5 pts) within the 60 cm (24 in) diameter circle, or OFFSET (1 pt) at least one motor in the circle.

• ORBIAlignment Points: Gapture a SINGLE IMAGE of each MANalignment ing throughout 1 ap through 10 positions with 20 buckets and accurate and ings to score up to 100 alignment points

Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to Core up to 100 acuity points.

OPEN TEST LANE POSITION	ALIGN	IMENT	ACUITY				
START TIMER	ALIGN BUCKET	IMAGE POINTS	CORRECT GAPS (1 POINT EACH)				
LAUNCH AND HOVER OVER STAND #1 ALIGN WITH BOTH BUCKETS CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	HOVER 2A	51 51	T BL R BR L L BR T TL R				
3 YAW LEFT 360° OVER STAND #1 ALIGN WITH BOTH BUCKETS 4 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	YAW L-360	51 51	T BL R BR L L BR T TL R				
5 YAW <u>RIGHT</u> 360° OVER STAND #1 ALIGN WITH BOTH BUCKETS 6 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	YAW R-360	51 51	T BL R BR L L BR T TL R				
7 CLIMB VERTICALLY OVER STAND #1 ALIGN WITH BOTH BUCKETS 8 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	CIMB 3A	5 1 5 1	T BL R BR L BR T TL R BI				
9 ALIGN WITH BOTH BUCKETS 10 C CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	DESCEND 2A	51 51	T BL R BR L L BR T TL R				
PITCH FORWARD TO STAND #2 ALIGN WITH BOTH BUCKETS 12 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	FWD 2 3A	5 1 5 1	BL T BR R TI BR T TL R BI				
13 ALIGN WITH BOTH BUCKETS 14 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	BKWD 2A	51 51	T BL R BR L L BR T TL R				
PITCH FWD TO STAND #2 THEN YAW LEFT 180° ALIGN WITH BOTH BUCKETS CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	FWD-L180	51 51	<u>TRBTLLB</u> BRRTLLB				
PITCH FWD TO LANDING THEN YAW <u>RIGHT</u> 180° ALIGN WITH BOTH BUCKETS (CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD	FWD-R180	51 51	B TR L BL T				
19 LAND IN CIRCLE CENTERED (5 PTS) OR OFFSET (1 PT) COUNT SINGLE LANDING TWICE FOR ALIGNMENT SCORE CAPTURE ONE IMAGE OF P1 AND P2 ACUITY TARGETS	AND P1 P2	5 1 5 1	BL R TL L BI				
STOP TIMER		/100	/10				
ELAPSED TIME (MM : SS)		FAIL .e one)	PASS FAIL (CIRCLE ONE)				



- Fly sideways parallel to objects while looking forward to videntify features as if along a road, truck, bus, while looking features as if along as road, truck, bus
- Maintain altitude (5) throughout to complete two laps in both directions around the first three omni stands.
- Land accurately on the platform with the chassis
 GENTERED (5 pts) within the 60 cm (24 in) diameter circle, or OFFSET (1 pt) at least one motor in the circle.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 2 laps with 20 buckets and accurate landings to score up to 100 alignment points.
 MANIPAY A
 Manual Points: While aligned with each bucket, identify
- Acuity Points: White stighted with each bucket, identify as many acuity target gaps as possible to score up to 100 ອະບັນັ້ນ points.

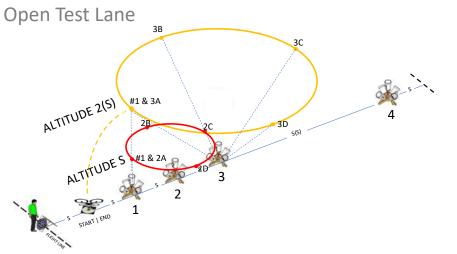
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OPEN TEST LANE TRAVERSE		ALIGN	IMENT		ACUITY					
START TIMER		lign Cket	IMAGE POINTS		CORRECT GAP (1 POINT EACH					
1 HOVER OVER THE LAUNCH AT ALTITUDE S		1A	51	TR	В	TR	L	BR		
2 ORBIT 90° LEFTWARD AROUND STAND #1		1B	5 1	R	TL	т	BL	В		
3 ROLL LEFTWARD TO STAND #2		2B	51	TL	R	TR	L	BR		
4 ROLL LEFTWARD TO STAND #3	ALT S	3B	51	в	TR	R	BL	т		
5 ORBIT 90° LEFTWARD AROUND STAND #3	1	3C	51	BL	R	BL	т	BR		
6 ORBIT 90° LEFTWARD AROUND STAND #3	LEFTWARD	3D	51	L	TL	R	BR	т		
7 ROLL LEFTWARD TO STAND #2		2D	51	TR	В	TL	В	BL		
8 ROLL LEFTWARD TO STAND #1		1D	51	в	TL	R	BL	т		
9 ORBIT 90° LEFTWARD AROUND STAND #1		1A	51	TR	В	TR	L	BR		
0 LAND IN CIRCLE (5 PTS CENTERED, 1 PT OFFSET)		P1	51	BL	R	TL	L	BL		
		1A	5 1	TR	В	TR	L	BR		
2 ORBIT 90° RIGHTWARD AROUND STAND #1		1D	51	В	TL	R	BL	Н		
3 ROLL RIGHTWARD TO STAND #2		2D	5 1	TR	В	TL	В	BL		
4 ROLL RIGHTWARD TO STAND #3	ALT S	3D	5 1	L	TL	R	BR	т		
15 ORBIT 90° RIGHTWARD AROUND STAND #3	- RIGI	3C	5 1	BL	R	BL	т	BR		
6 ORBIT 90° RIGHTWARD AROUND STAND #3	- RIGHTWARD	3B	51	В	TR	R	BL	Т		
7 ROLL RIGHTWARD TO STAND #2	RD	2B	5 1	TL	R	TR	L	BR		
8 ROLL RIGHTWARD TO STAND #1		1B	5 1	R	TL	т	BL	В		
I9 ORBIT 90° RIGHTWARD AROUND STAND #1		1A	51	TR	В	TR	L	BR		
20 LAND IN CIRCLE (5 PTS CENTERED, 1 PT OFFSET)		P2	51	L	BR	T	TL	В		
STOP TIMER										
			/10	0				/100		
ELAPSED TIME	F	PASS	P	PASS FAIL						
(MM : SS)		(CIRCL	E ONE)		(CIRCLE ONE)					

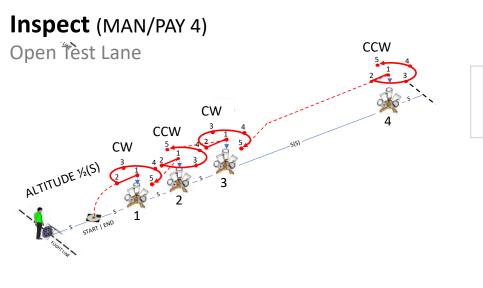
Orbit (MAN/PAY 3)



- Orbit an object at an equal altitude and radius while looking inward to identify features on four sides.
- Each orbit includes 5 bucket alignments: 1 downward radius check plus 4 angled buckets all around.
- Start aligned over omni stand #1 at altitude 2(S) to set the orbit radius around omni stand #3. Orbit both directions ending at the start point.
- Descend over omni stand #1 to altitude S to set the orbit radius around omni stand #2. Orbit both directions. Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 4 orbits (leftward and rightward at each altitude) with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

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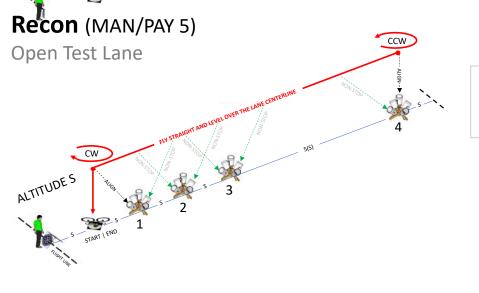
OPEN TEST LANE ORBIT		ALIGN	IMENT	ACUITY				
START TIMER		lign Cket	IMAGE POINTS	CORRECT GAPS (1 POINT EACH)				
1 ALIGN OVER STAND #1 AT ALT 2(S) CHECK RADIUS	A	1	51	T BL R BR L				
2 ALIGN WITH BUCKET 3A CHECK ALTITUDE	ALT 2(S) -	3A	51	BR T TL R BL				
3 ORBIT LEFTWARD 90°		3B	51	B TR R BL T				
4 ORBIT LEFTWARD 90°	LEFTWARD	3C	51	BL R BL T BR				
5 ORBIT LEFTWARD 90°		3D	51	L TL R BR T				
6 ALIGN OVER STAND #1 AT ALT 2(S) CHECK RADIUS	AL	1	51	T BL R BR L				
7 ALIGN WITH BUCKET 3A CHECK ALTITUDE	ALT 2(S)	3A	51	BR T TL R BL				
8 ORBIT RIGHTWARD 90°	– RIGHTWARD	3D	51	L TL R BR T				
9 ORBIT RIGHTWARD 90°	HTWA	3C	5 1	BL R BL T BR				
10 ORBIT RIGHTWARD 90°	RD	3B	51	B TR R BL T				
11 ALIGN OVER STAND #1 AT ALT S CHECK RADIUS		1	5 1	T BL R BR L				
12 ALIGN WITH BUCKET 2A CHECKALTITUDE	ALT S	2A	5 1	L BR T TL R				
13 ORBIT LEFTWARD 90°		2B	5 1	TL R TR L BR				
14 ORBIT LEFTWARD 90°	LEFTWARD	2C	5 1	T BL R TL B				
15 ORBIT LEFTWARD 90°		2D	51	TR B TL B BL				
16 ALIGN OVER STAND #1 AT ALT S CHECK RADIUS	1	1	5 1	T BL R BR L				
17 ALIGN WITH BUCKET 2A CHECKALTITUDE	ALT S -	2A	5 1	L BR T TL R				
18 ORBIT RIGHTWARD 90°	- RIGH	2D	5 1	TR B TL B BL				
19 ORBIT RIGHTWARD 90°	RIGHTWARD	2C	51	T BL R TL B				
20 ORBIT RIGHTWARD 90°		2B	51	TL R TR L BR				
STOP TIMER								
STOT HIMEN			/100	/100				
ELAPSED TIME		PASS	FAIL	PASS FAIL				
(MM : SS)		(CIRCI	E ONE)	(CIRCLE ONE)				



- Fly around objects in close proximity to inspect detailed features on the top and all four sides.
- Maintain altitude 1/2(S) throughout starting on top of each omni stand then rotate around all four omni bucket stands in alternating clockwise (A-B-C-D) and counter clockwise (A-D-C-B) directions.
- Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 4 omni stands with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

8

OPEN TEST LANE INSPECT	ALIG	NMENT	ACUITY				
START TIMER	ALIGN BUCKET	IMAGE POINTS	CORRECT GAPS (1 POINT EACH)				
1 HOVER OVER STAND #1 AT ALTITUDE 1/2(S)	1	5 1	T BL R BR L				
2 PITCH BACKWARD	ALT ½(S) – LEFTWARD	5 1	TR B TR L BR				
3 ORBIT LEFTWARD 90°	1B	5 1	R TL T BL B				
4 ORBIT LEFTWARD 90°		5 1	BR R TL L BR				
5 ORBIT LEFTWARD 90°	ິ 1D	5 1	B TL R BL T				
6 HOVER OVER STAND #2 AT ALTITUDE 1/2(S)		51	BL T BR R TL				
7 PITCH BACKWARD	لم الم الم الم الم الم الم الم الم الم ا	51	L BR T TL R				
8 ORBIT RIGHTWARD 90°	RIGH 2D	5 1	TR B TL B BL				
9 ORBIT RIGHTWARD 90°	RIGHTWARD	51	T BL R TL B				
10 ORBIT RIGHTWARD 90°	[□] 2B	51	TL R TR L BR				
11 HOVER OVER STAND #3 AT ALTITUDE 1/2(S)	3	5 1	R TL B BL R				
12 PITCH BACKWARD	Г ½ ЗА	5 1	BR T TL R BL				
13 ORBIT LEFTWARD 90°	ALT ½(S) – LEFTWARD	5 1	B TR R BL T				
14 ORBIT LEFTWARD 90°	ARI 3C	5 1	BL R BL T BR				
15 ORBIT LEFTWARD 90°	⁰ 3D	5 1	L TL R BR T				
16 HOVER OVER STAND #4 AT ALTITUDE 1/2(S)		51	TL B TR R BR				
17 PITCH BACKWARD	אַ(s) - 4A	5 1	T BL B TR L				
18 ORBIT RIGHTWARD 90°		5 1	BR B TL B TR				
19 ORBIT RIGHTWARD 90°	ALT ½(S) - RIGHTWARD	51	R BL T TR B				
20 ORBIT RIGHTWARD 90°	□ 4B	51	TRLBLRTL				
STOP TIMER							
		/100	/100				
ELAPSED TIME		S FAIL	PASS FAIL				
, (MM : SS)	(CIRC	CLE ONE)	(CIRCLE ONE)				



- Fly straight and level at a sustainable speed directly over the lane centerline to establish a stable hover over an object and perform quick reconnaissance tasks.
- Maintain altitude (S) throughout starting over the launch/land platform to align with the designated targets at both ends of the lane.
- A complete trial totals a distance of 80(S).
- Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 5 laps with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

18

7

OPEN TEST LANE RECON	ALIGNMENT					ACUITY					
START TIMER	ALIGN BUCKET		IMA POI		CORRECT GAPS (1 POINT EACH)						
1 FLY AT ALTITUDE S TO STAND #4		4	5	1	TL	В	TR	R	BR		
2 YAW LEFT 180°	LAP	7	5	1	<u>BR</u>	I	BL	Ŀ	<u>TL</u>		
3 FLY TO THE LAUNCH AND YAW RIGHT 180°	1	L	5	1	в	TR	L	BL	т		
4 HOVER IN PLACE CHECK ALTITUDE S		1A	5	1	TR	в	TR	L	BR		
5 FLY AT ALTITUDE S TO STAND #4	ļ	4	5	1	TL	в	TR	R	BR		
6 YAW LEFT 180°	LAP	7	5	1	<u>BR</u>	I	<u>BL</u>	L	ΤL		
7 FLY TO THE LAUNCH AND YAW RIGHT 180°	2	L	5	1	в	TR	L	BL	т		
8 HOVER IN PLACE CHECK ALTITUDE S		1A	5	1	TR	в	TR	L	BR		
9 FLY AT ALTITUDE S TO STAND #4	LAP 3	4	5	1	TL	в	TR	R	BR		
10 YAW LEFT 180°		7	5	1	BR	I	BL	Ŀ	TL		
11 FLY TO THE LAUNCH AND YAW RIGHT 180°		L	5	1	в	TR	L	BL	т		
12 HOVER IN PLACE CHECKALTITUDE S		1A	5	1	TR	в	TR	L	BR		
13 FLY AT ALTITUDE S TO STAND #4		4	5	1	TL	в	TR	R	BR		
14 YAW LEFT 180°	LAP 4	7	5	1	<u>BR</u>	I	<u>BL</u>	L	TL		
15 FLY TO THE LAUNCH AND YAW RIGHT 180°		L	5	1	в	TR	L	BL	т		
16 HOVER IN PLACE CHECKALTITUDE S		1A	5	1	TR	в	TR	L	BR		
17 FLY AT ALTITUDE S TO STAND #4		4	5	1	TL	в	TR	R	BR		
18 YAW LEFT 180°	LAP 5	7	5	1	<u>BR</u>	I	<u>BL</u>	Ŀ	TL		
19 FLY TO THE LAUNCH AND YAW RIGHT 180°		L	5	1	В	TR	L	BL	Т		
20 HOVER IN PLACE CHECK ALTITUDE S		1A	5	1	TR	В	TR	L	BR		
STOP TIMER				/100					/100		
ELAPSED TIME	PASS FAIL				PASS FAIL						
(MM : SS)	(CIRCLE ONE)				(CIRCLE ONE)						