## **Scorable Obstructed Scenarios**





WHITE BUCKET ALIGNMENTS **BLACK BUCKET ALIGNMENTS** 







**Pocket Guide for Aerial Drones** 

**OBSTRUCTED (9)** 

ASTM Internation Standard Test Methods for Small Unmanned Aircraft Systems

Response Response 14 09 1 Website: Robot Test Methods nist gov

Response Robot Test Methods nist gov

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Response Robots (E54.09) | Website: RobotTestMethods.nist.gov









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National Institute of Standards and Technology

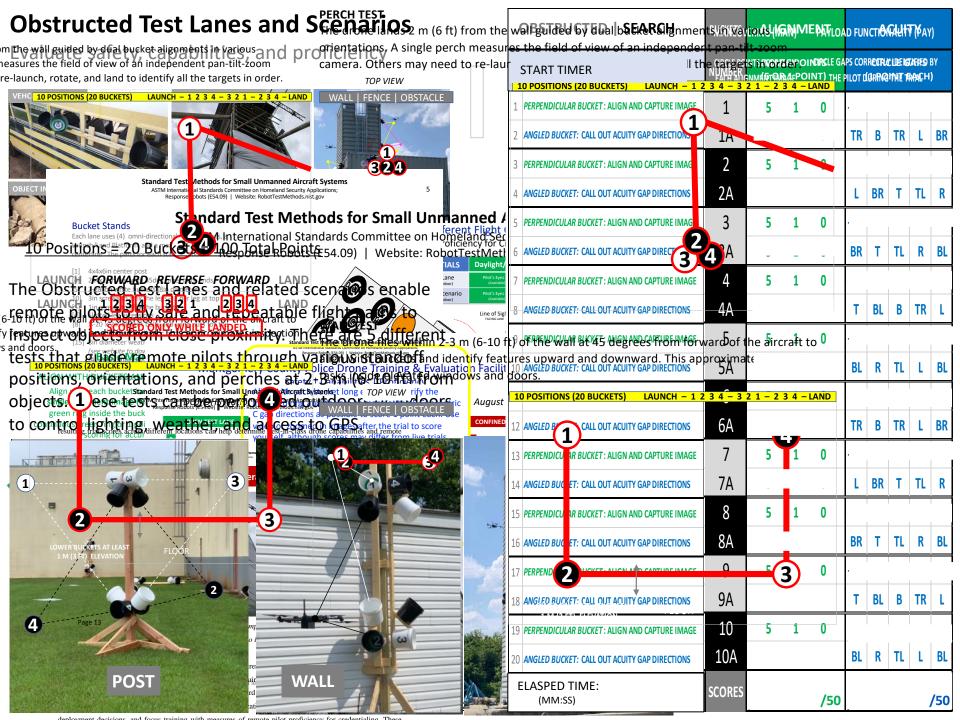
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mail obotTestMethods@nist.gov







# **Obstructed Search Scenarios**

Day and Night Trials

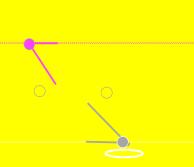
## **USE SETS OF 5 "OFFSET" DU**

HORIZONTALS DISTRIBUT

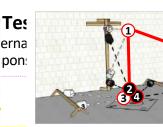


**VERTICALS IN ELE** 





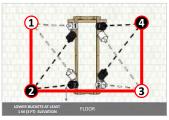


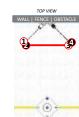


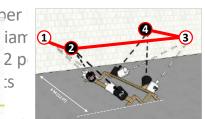
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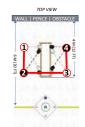
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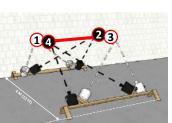


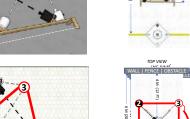














[4] 2x4x12in legs with 45dag taner

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(4) omni-d

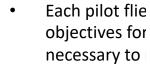
Platform, and

e parts for e

- 2-gallon white bucke [5]
- 3in screws to affix th 10] 1in screws to affix th
- [5] [4] Slotted leg extensior— ...
- 14-20 x 2in hanger boits and wil [8] leg extensions to sling
- [15] 8in diameter weath (see website to dov
- [4] Big letters A-B-ALIGN WITH BUCKETS AND

Align with each bucket lor single alignment image (N green ring inside the buck

continuous green ring or 1 poi



Teams concur

safe distance: designated ar

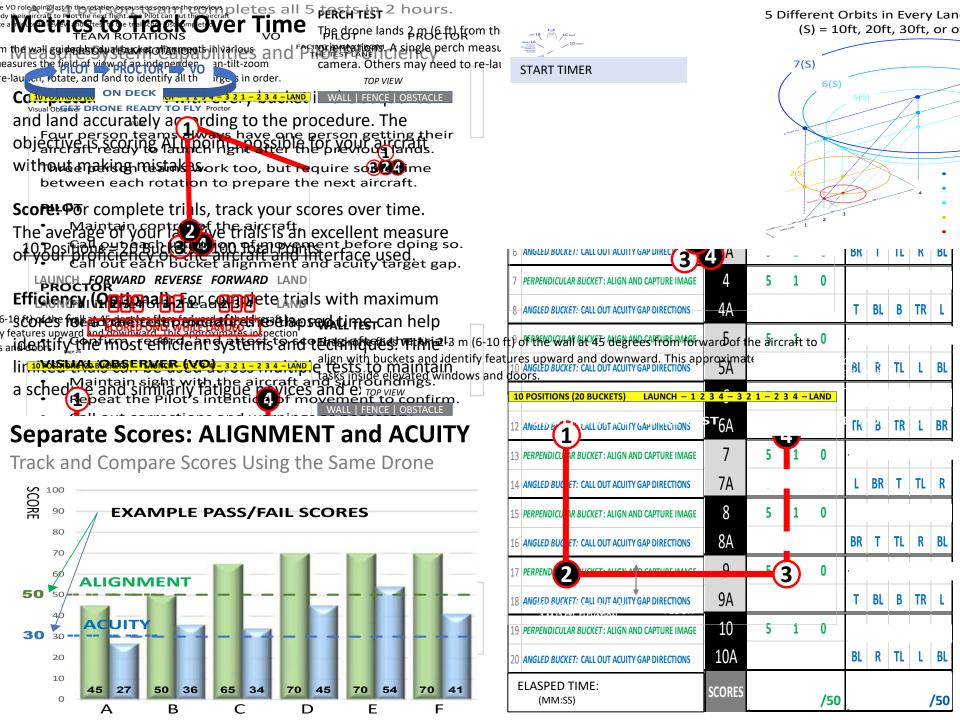
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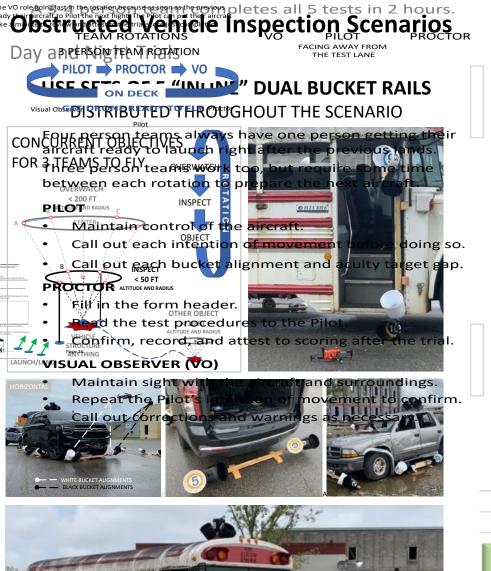
















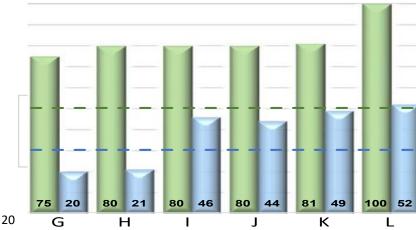
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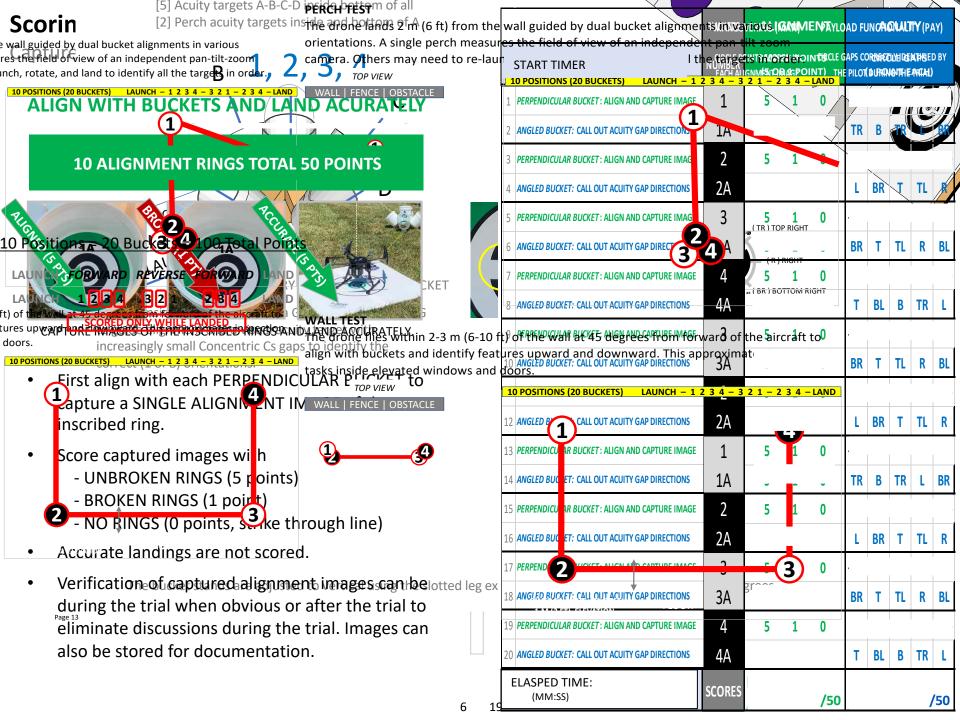
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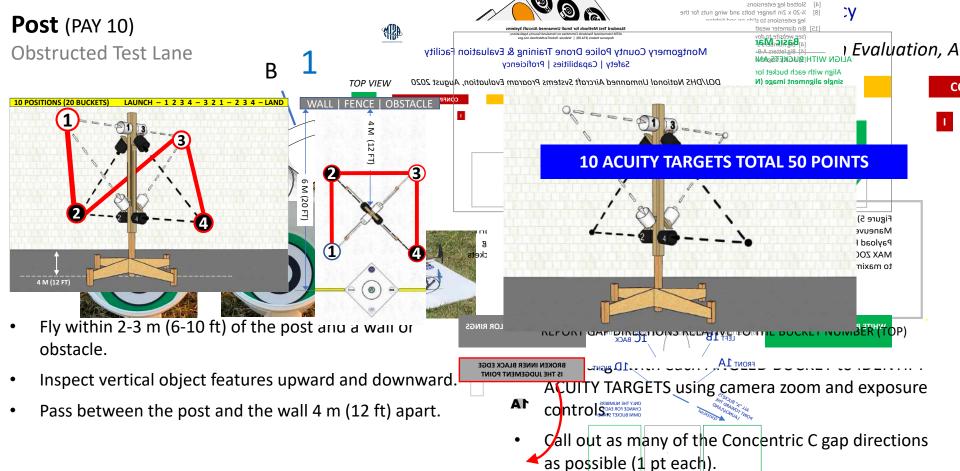
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7(S)

The WALL test shown with alternating pairs of white and black buckets to increase the need for exposure control.







#### **SCORING**

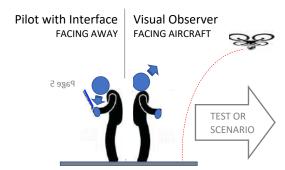
## **Alignment Points in Perpendicular Buckets (50 Total):**

Align with each perpendicular bucket to CAPTURE A SINGLE IMAGE OF THE ALIGNMENT RING for scoring during or after the trial.

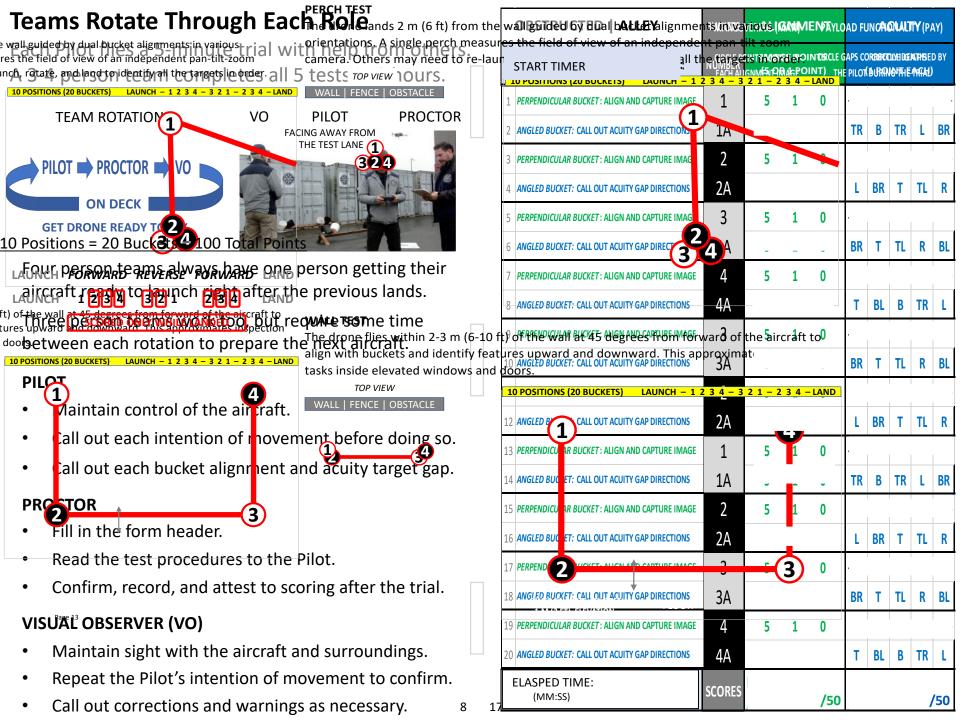
## **Acuity Points in Angled Buckets (50 Total):**

Align with each angled bucket to IDENTIFY ACUITY GAPS through the pilot interface. Images are optional for documentation but use the answer key for scoring.

Foir a nonce the expired of the typical starting point for novice pilots. Test lanes with alternating white and black buckets are used to the typical starting point for novice pilots. Test lanes with alternating white and black buckets are used to the typical starting point for novice pilots. Test lanes with alternating white and black buckets are used to the typical starting point for novice pilots. Test lanes with alternating point for novice pilots.

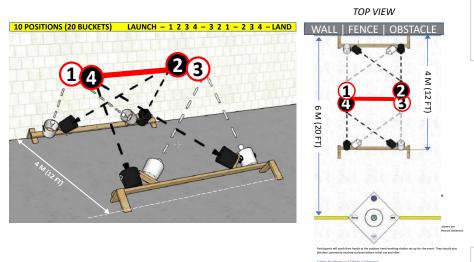


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# **Alley** (PAY 9)

**Obstructed Test Lane** 



- Fly within 2-3 m (6-10 ft) of a wall or obstacle in front of the aircraft (0 degrees) and behind the aircraft (180 degrees).
- Inspect horizontal object features leftward and rightward.

#### **SCORING**

# **Alignment Points in Perpendicular Buckets (50 Total):**

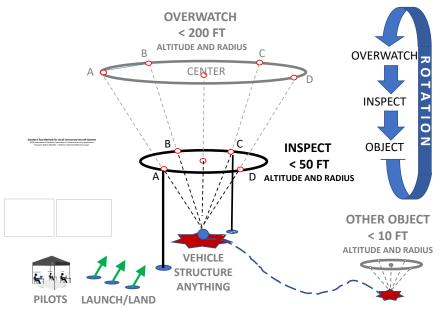
Align with each perpendicular bucket to CAPTURE A SINGLE IMAGE OF THE ALIGNMENT RING for scoring during or after the trial.

## **Acuity Points in Angled Buckets (50 Total):**

Align with each angled bucket to IDENTIFY ACUITY GAPS through the pilot interface. Images are optional for documentation but use the answer key for scoring.

# **Teams Sequence Through Scenarios**

Each Pilot flies a 15-minute scenario, sequencing through 3 objectives for 5 minutes each.



- This scenario mechanization enables embedded bucket scoring tasks to be performed similarly by all participating Pilots. So the results are comparable within the same scenario layout. Additional tactics can be overlayed onto these scenarios at your facility.
- Up to 3 teams concurrently fly different scenario objectives from safe distances and altitudes apart.
- Teams move as necessary to maintain sight lines with their aircraft and communications with other teams.
   The overwatch team leads communications.
- Scenarios restart every 20 minutes with a different rotation of Pilot, Proctor, and VO.

