

Meeting Minutes

Grasping and Manipulation Performance Measures and Benchmarking

Held May 8, 2018

Joe Falco provided a brief overview of this meeting series and introduced Jeff Mahler of UC Berkeley.

Jeff Mahler provided a presentation of robotic grasping and manipulation benchmarking work at Berkeley. Jeff's Power Point slides can be found [here](#). A WebEx video recording of his presentation can be found [here](#).

Joe Falco concluded with the following information.

- NIST will soon release two draft documents for public review:
 - Performance Metrics and Test Methods for Robotic Hands
 - Proposed Standard Terminology for Robotic Hands and Associated Performance Metrics
- The next Grasping and Manipulation Performance Benchmarks meeting will be held in the September timeframe.