

Characterization of Magnetic Nanostructures for STT-RAM Applications by use of Macro- and Micro-scale Ferromagnetic Resonance

Tom Silva¹, Hans Nembach¹, Justin Shaw¹, Brian Doyle², Kaan Oguz², Kevin O'brien², and Mark Doczy²

¹·National Institute of Standards and Technology, Boulder

²·Intel, Hillsboro



NIST team members

Justin Shaw
Nanomagnetics Project



Hans Nembach
Nanomagnetics Project



Bob McMichael
NIST, Gaithersburg



Martin Schoen
(Ph.D. Student, U. Regensburg)



Mike Schneider
Spintronics Project



The two faces of metrology

If you can't measure it, you
can't understand it...



Generalized
Understanding:
Reductio ad mathematicum



Specialized Understanding:
Reductio ad profitus



Overview

- STT-MRAM: Background and motivation
- VNA-FMR: Measuring damping and anisotropy in blanket films.
- H-MOMM: Measuring damping and anisotropy in e-beam patterned structures.

STT-MRAM: a promising emerging memories

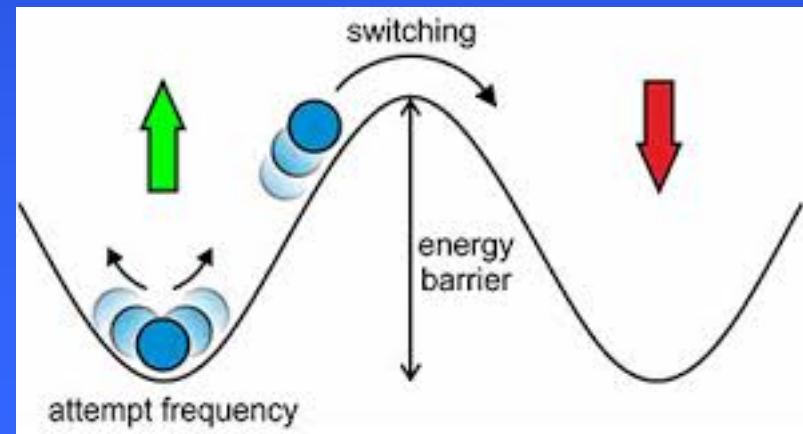
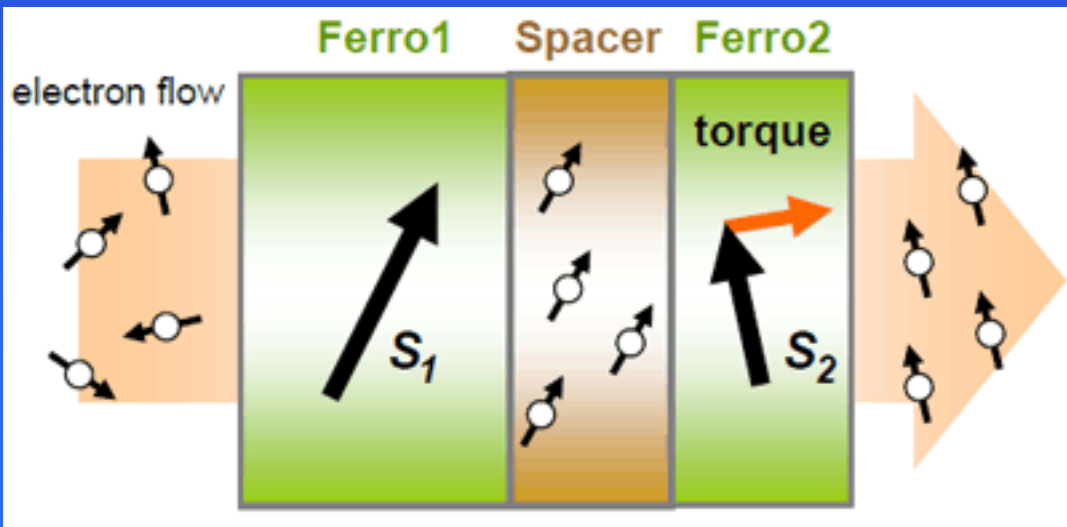
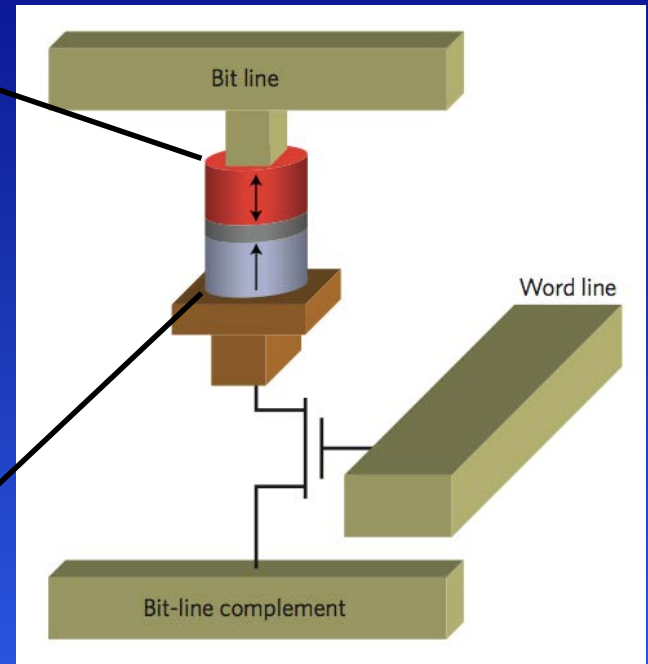
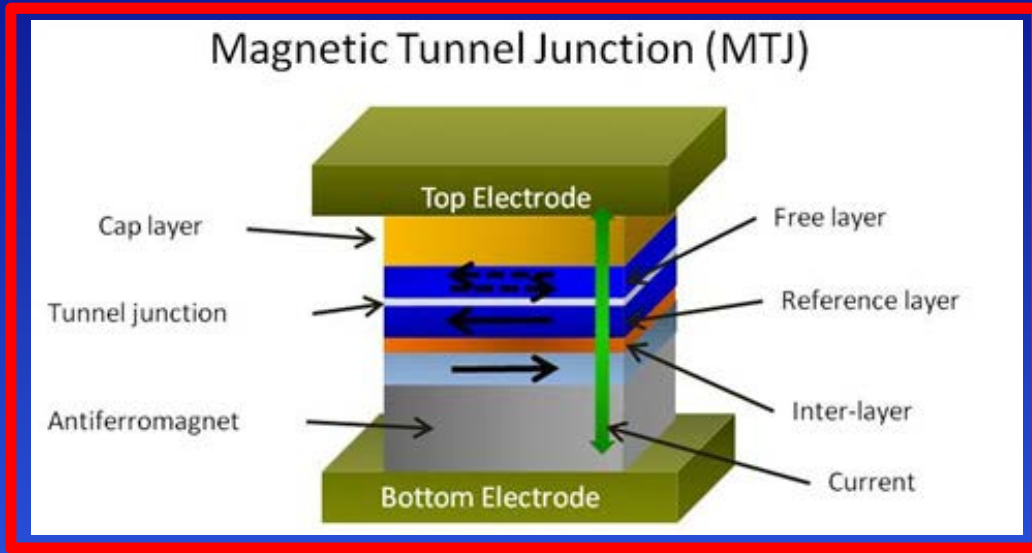
Table 1 | Comparison of key features of existing and emerging memories.

	SRAM	eDRAM	DRAM	eFlash (NOR)	Flash (NAND)	FeRAM	PCM	STT-MRAM	RRAM
Endurance (cycles)	Unlimited	Unlimited	Unlimited	10 ⁵	10 ⁵	10 ¹⁴	10 ⁹	Unlimited	10 ⁹
Read/write access time (ns)	<1	1-2	30	10/10 ³	100/10 ⁶	30	10/100	2-30	1/100
Density	Low (six transistors)	Medium	Medium	Medium	High (multiple bits per cell)	Low (limited scalability)	High (multiple bits per cell)	Medium	High (multiple bits per cell)
Write power	Medium	Medium	Medium	High	High	Medium	Medium	Medium	Medium
Standby power	High	Medium	Medium	Low	Low	Low	Low	Low	Low
Other	Volatile	Volatile. Refresh power and time needed	Volatile. Refresh power and time needed	High voltage required	High voltage required	Destructive readout	Operating T < 125°C	Low read signal	Complex mechanism

Significant disadvantages are marked in bold. Estimates for emerging memories are based on expectations for functioning chips, not demonstrations of individual bits. See text for abbreviation.

STT-MRAM: Unlimited endurance like DRAM, *but with much lower power consumption in standby.*

(STT-MRAM) Spin torque transfer magnetic RAM



What do we want for STT-RAM?

“switching current” $J_{c0} = \frac{e\alpha M_s t_{FM}}{\mu_B g(\theta) p} \left(\gamma \mu_0 (H_k - M_s) \right)$

“damping” α t_{FM} thickness of memory layer

Low switching currents \rightarrow small alpha, small volume area of memory layer

thermal “attempt” time (~ 1 ns) $\tau = \tau_0 \exp \left(\frac{\mu_0 M_s (H_k - M_s) t_{FM} A_{FM}}{k_B T} \right)$

“decay” time of memory state τ_0 A_{FM}

High stability \rightarrow large anisotropy (H_k)

For >10 year stability, need $\frac{\mu_0 M_s (H_k - M_s) V}{k_B T} > 40$

$$\Rightarrow \mu_0 (H_k - M_s) \cong 0.8 \text{ T} \left[\begin{array}{l} d_{FM} = 30 \text{ nm} \\ t_{FM} = 0.5 \text{ nm} \end{array} \right]$$

For scalability:

$$\frac{\alpha}{A_{FM}} = \text{constant}$$

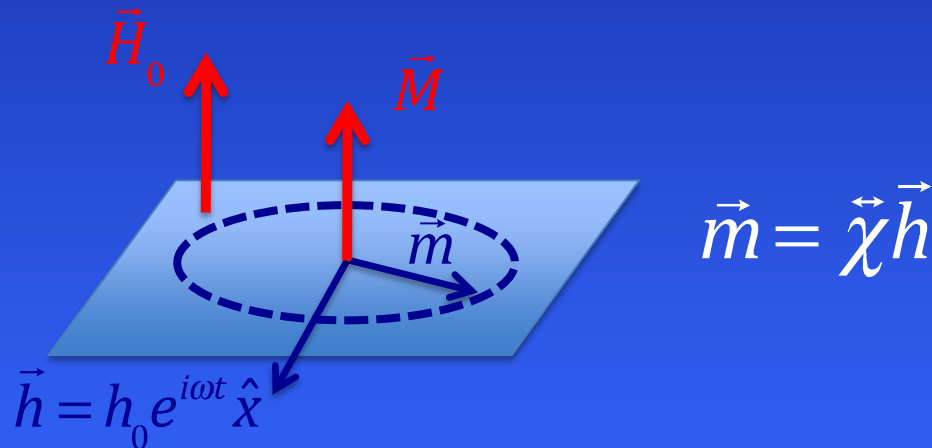
Ferromagnetic resonance in a nutshell

The Gilbert equation: *The magnetic analog to Ohm's law*

$$\frac{d\vec{M}}{dt} = -|\gamma|\mu_0(\vec{M} \times \vec{H}) - \frac{\alpha}{M_s} \left[\vec{M} \times \frac{d\vec{M}}{dt} \right]$$

Reactive: "Larmor"

Lossy: "damping"



$$\chi_{xx}(H_0, \omega) = \frac{M_{eff}(H_0 - M_{eff})}{\underbrace{\left((H_0 - M_{eff})^2 - (\omega/\gamma\mu_0)^2 \right)}_{\text{Resonance}} - \underbrace{i(2\alpha\omega/\gamma\mu_0)(H_0 - M_{eff})}_{\text{Linewidth}}}$$

Resonance

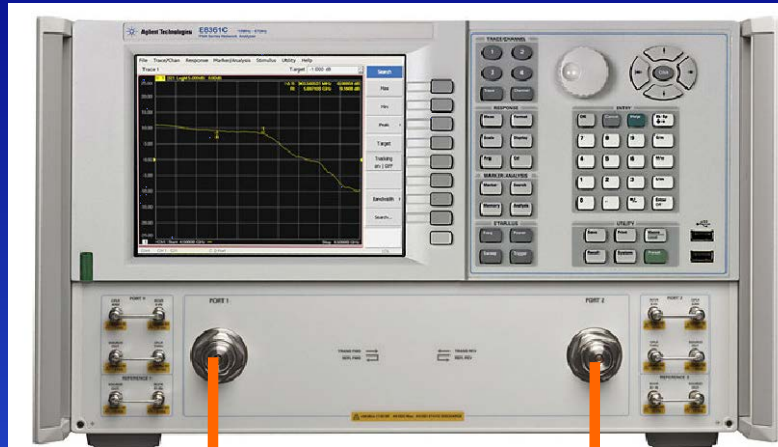
Linewidth

Overview

- STT-MRAM: Background and motivation
- VNA-FMR: Measuring damping and anisotropy in blanket films.
- H-MOMM: Measuring damping and anisotropy in e-beam patterned structures.

Instrumentation: VNA-FMR

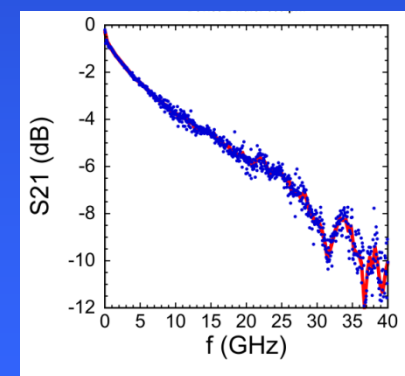
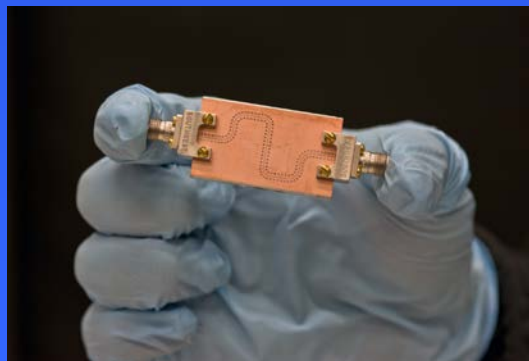
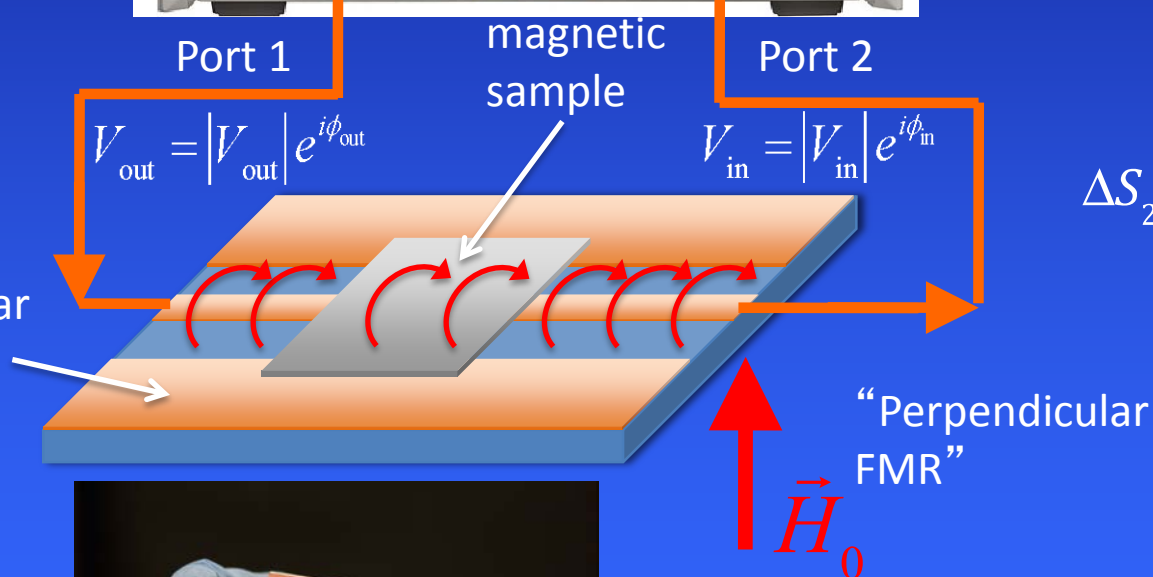
Vector network analyzer



- $10 \text{ MHz} < f < 67 \text{ GHz}$
- Maximum field: 3 T
- Coplanar waveguides with $50 \mu\text{m}$ wide center conductor
- 1 Watt max microwave power

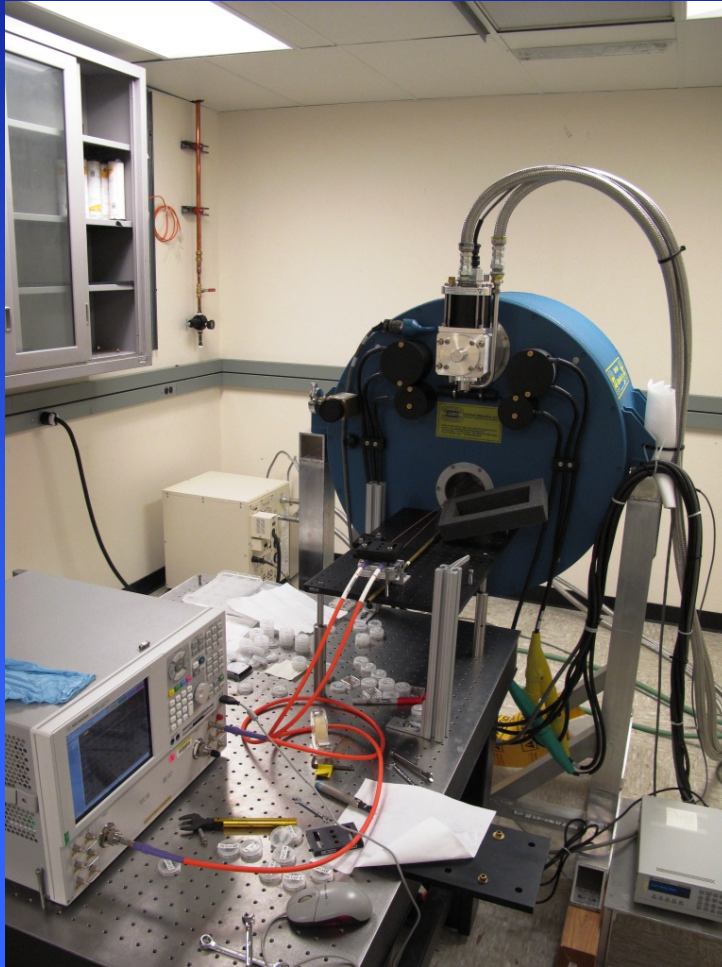
$$S_{21} = \frac{|V_{\text{in}}| e^{i\phi_{\text{in}}}}{|V_{\text{out}}| e^{i\phi_{\text{out}}}}$$

$$\Delta S_{21} \cong -\frac{i\omega L}{Z_0} = -\chi_{xx} \frac{i\omega \tilde{L}}{Z_0}$$

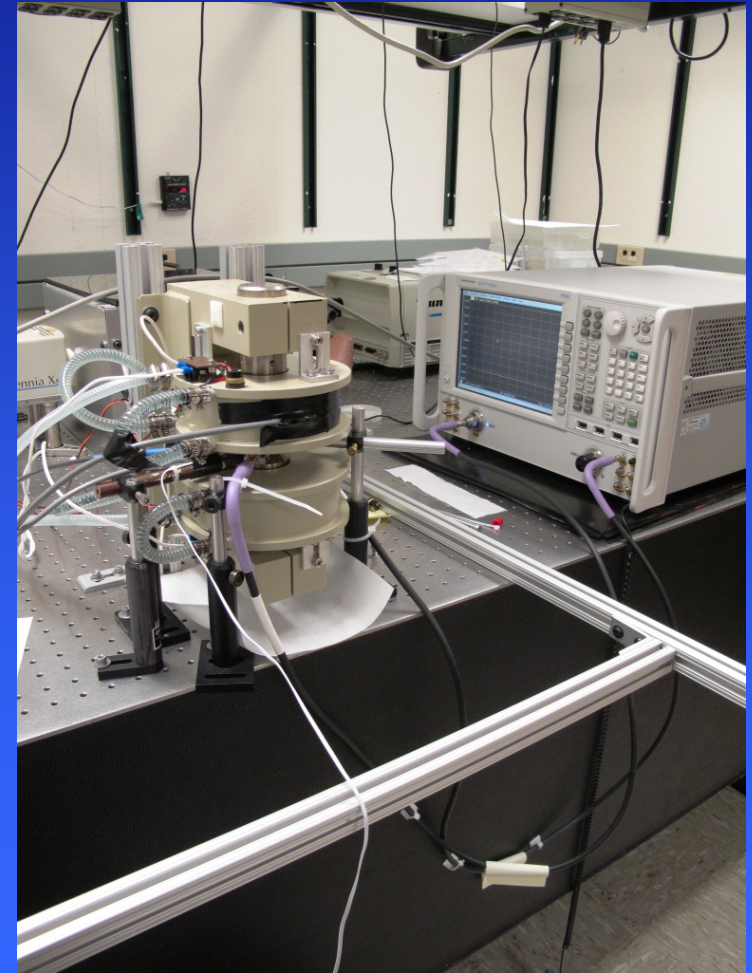


Ferromagnetic Resonance (FMR) @ NIST Boulder

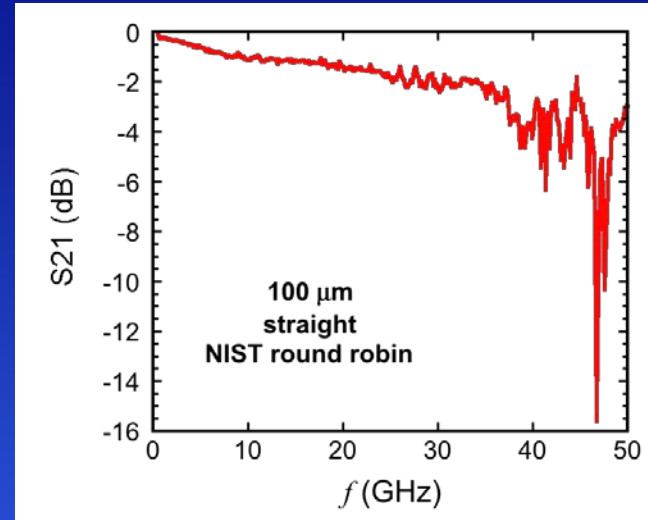
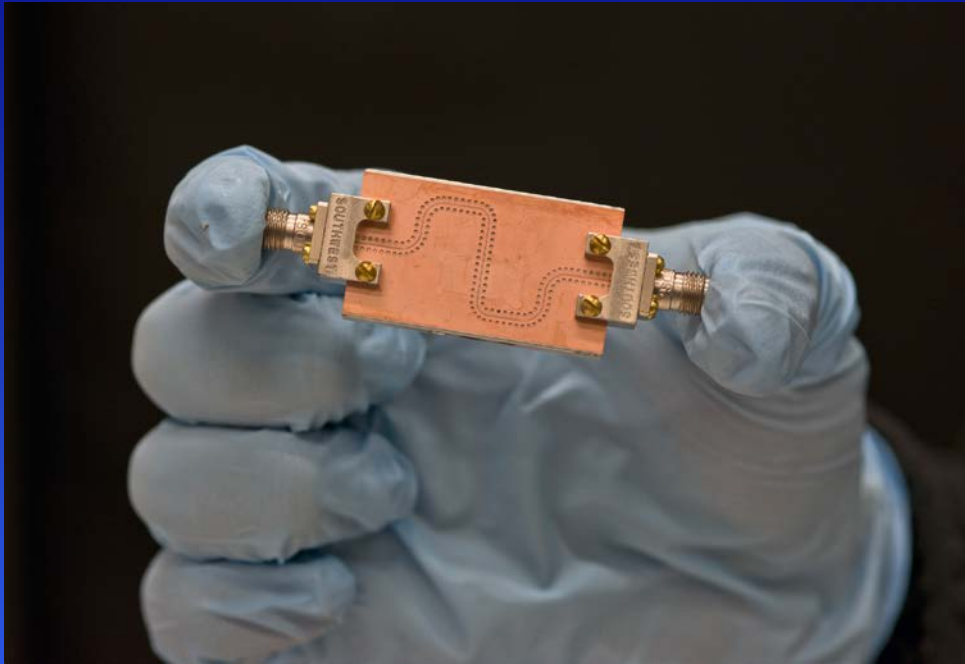
3-Axis Superconducting Magnet (3 Tesla)



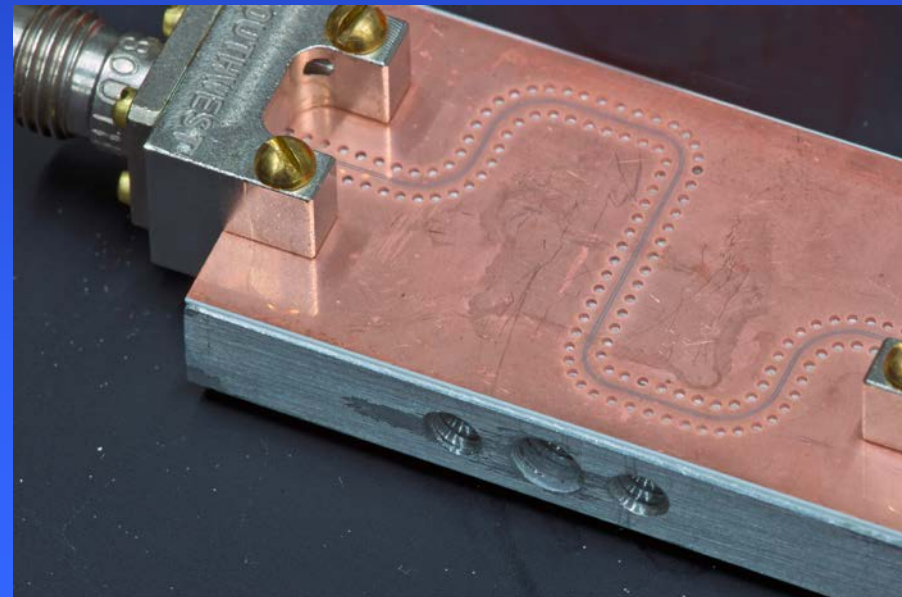
Perpendicular Geometry (2.4 Tesla)



NIST coplanar waveguides



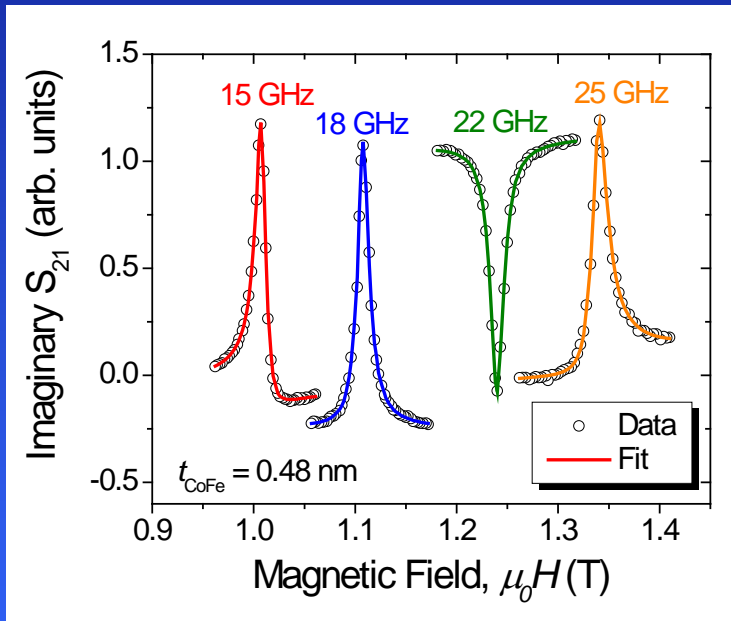
- “Stitching” to electrically connect all three ground planes.
- Prevents mode hybridization for $f < 40$ GHz.



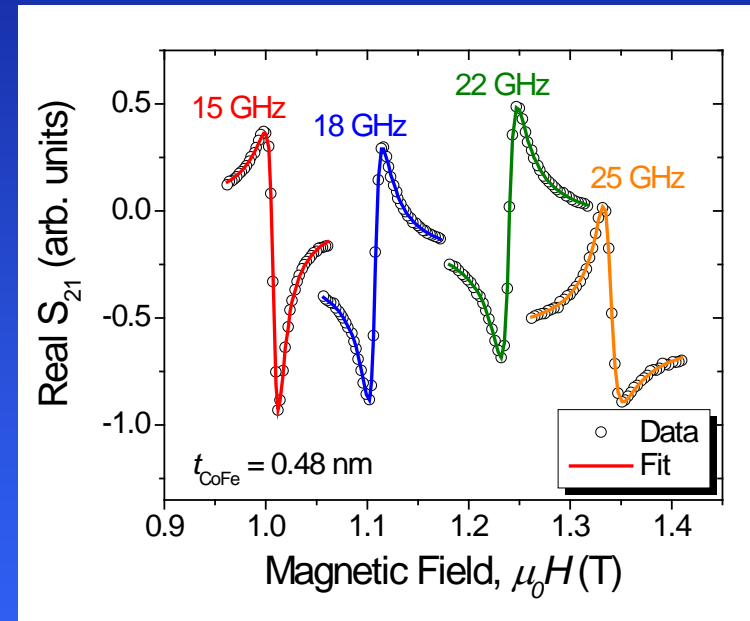
Ferromagnetic Resonance (FMR)

Perpendicular geometry Vector Network Analyzer FMR (VNA-FMR)

- 67 GHz bandwidth, 3 T perpendicular fields



Ex: NIST-grown
CoFe/Ni
multilayers



Extracting anisotropy and damping from FMR

$$H_{res}(f) = \frac{2\pi}{|\gamma|\mu_0} f + M_{eff}$$

$$M_{eff} \doteq M_s - H_k$$

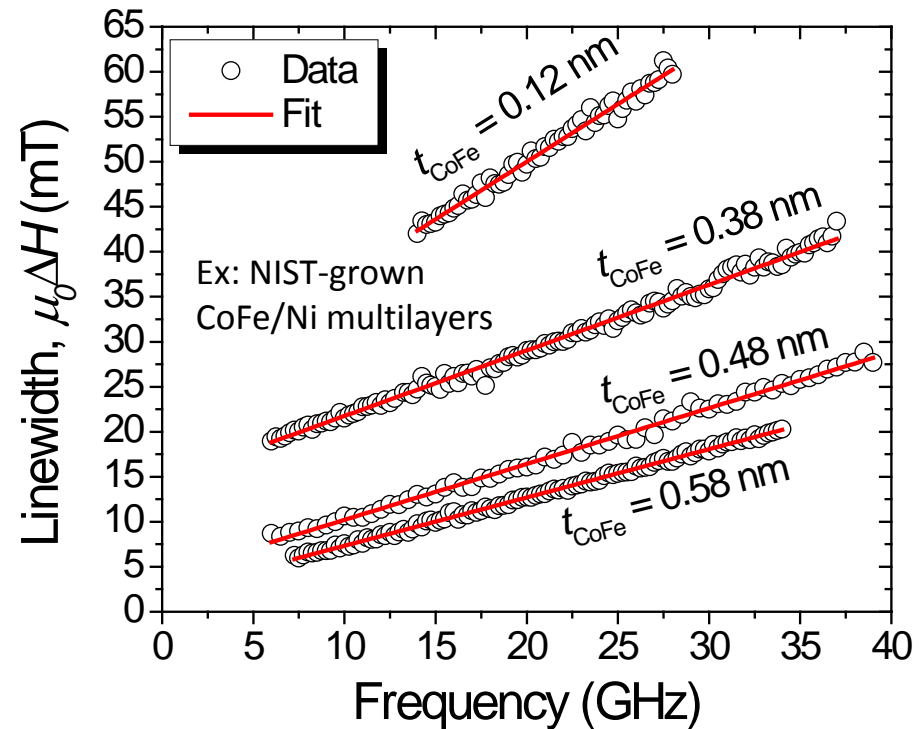
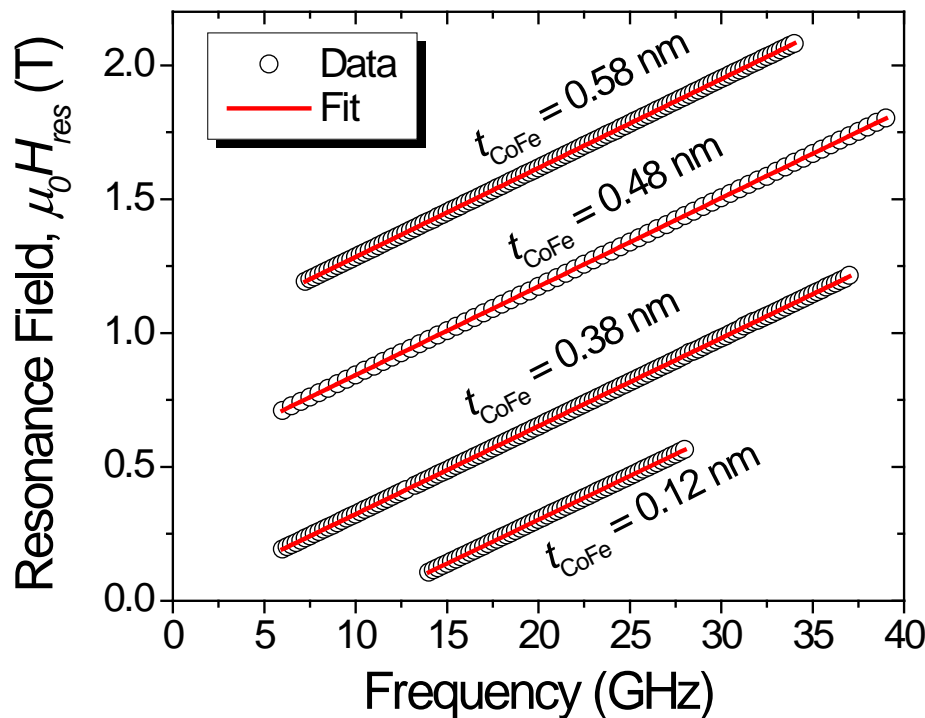
Slope \rightarrow g -factor

y-intercept \rightarrow Effective magnetization, M_{eff}

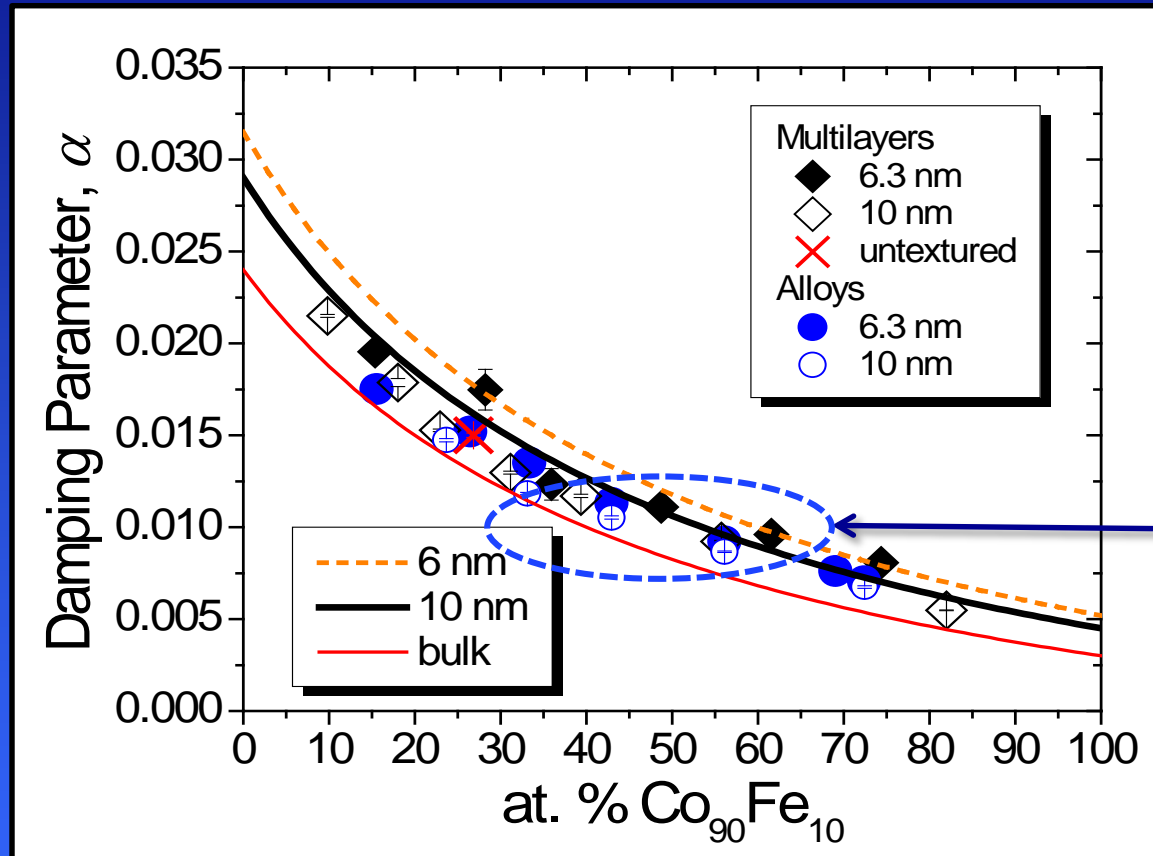
$$\Delta H(f) = \frac{4\pi\alpha}{|\gamma|\mu_0} f + \Delta H_0$$

Slope \rightarrow Damping, α

y-intercept \rightarrow Inhomogeneous linewidth broadening ΔH_0



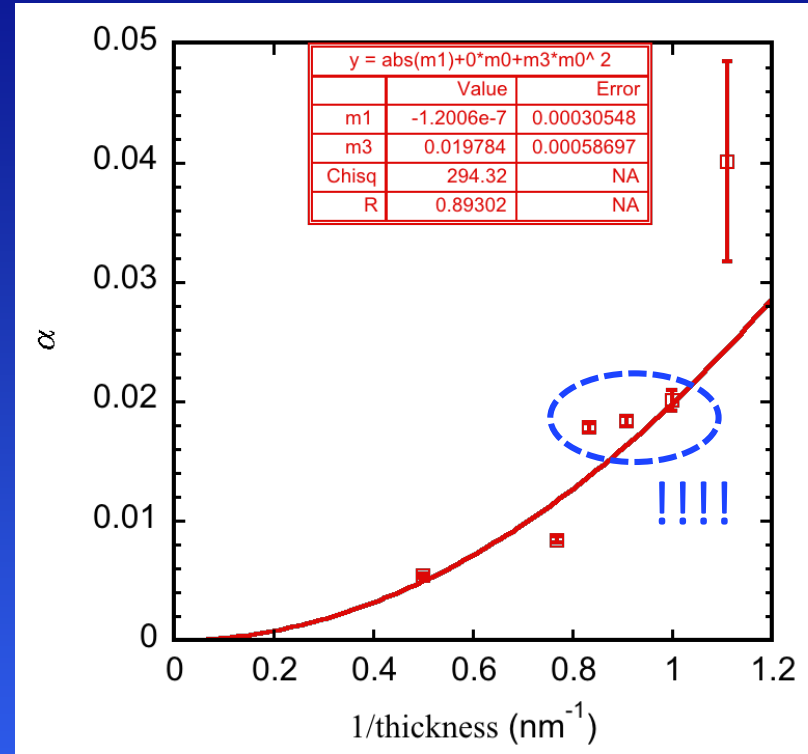
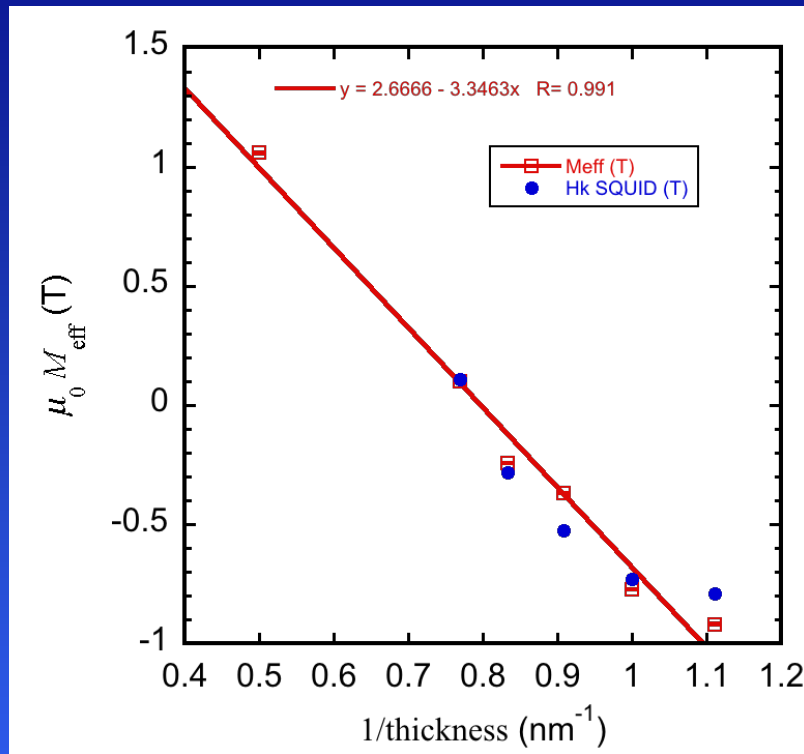
Damping parameter in $\text{Co}_{90}\text{Fe}_{10}/\text{Ni}$ multilayers



$\alpha \cong 0.01$
(A typical value...)

J.M. Shaw, APL, 99, 012503 (2011)

Damping for “conventional” Ta/CoFeB/MgO



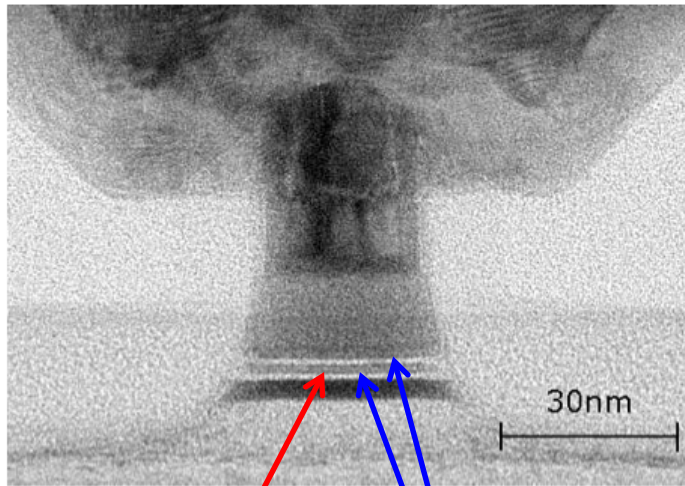
- Small thickness required for high anisotropy (“interfacial anisotropy”).
- Small thickness results in higher damping, but with quadratic dependence on reciprocal thickness. Interfacial?!?

MgO “sandwiches”

Impact of ultra low power and fast write operation of advanced perpendicular MTJ on power reduction for high-performance mobile CPU

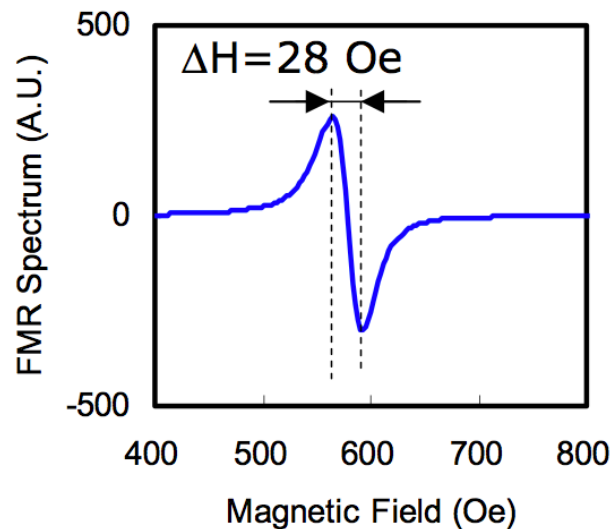
E. Kitagawa, S. Fujita, K. Nomura, H. Noguchi, K. Abe, K. Ikegami, T. Daibou, Y. Kato, C. Kamata, S. Kashiwada, N. Shimomura, J. Ito, and H. Yoda
Corporate R&D Center, Toshiba Corporation, Kawasaki 212-8582, Japan

IEEE, International Electron Devices Meeting, 677 – 680 (2012)



“Storage layer”

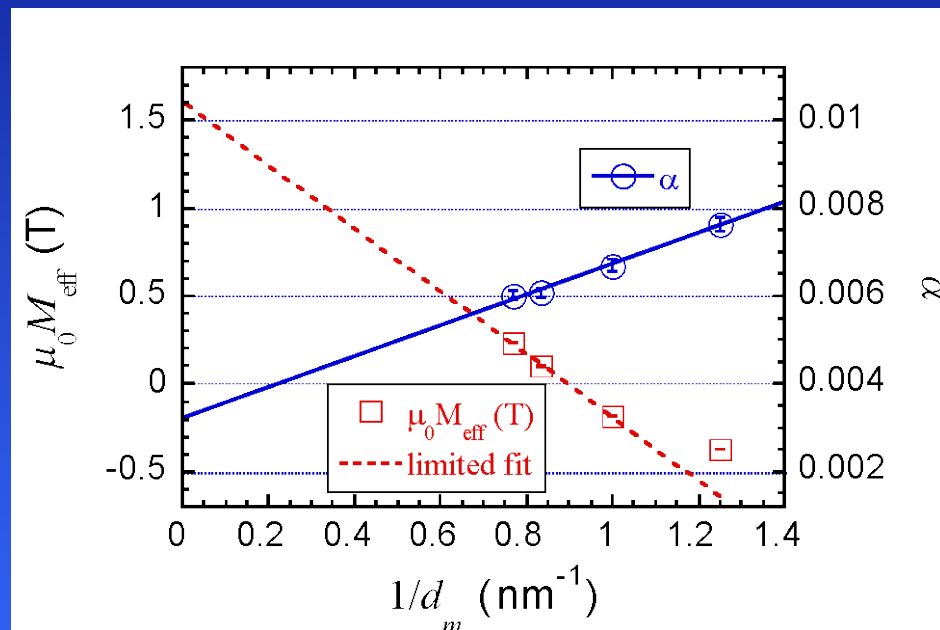
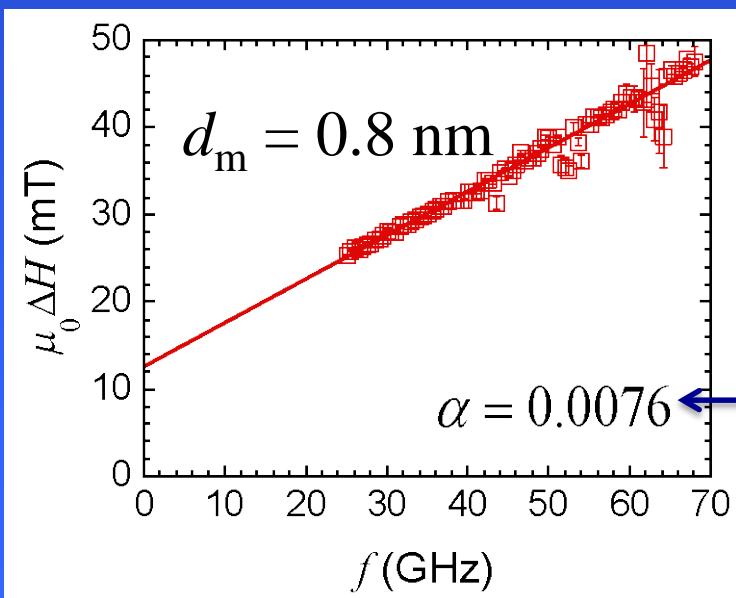
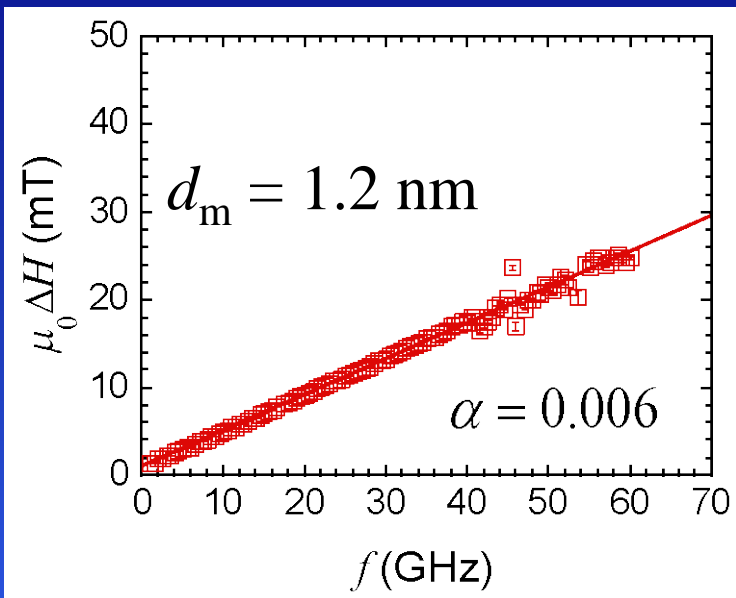
MgO “spacers”



$$\mu_0 M_{\text{eff}} = -0.35 \text{ T}$$
$$\alpha = 0.004$$

Intel CoFeB sandwich material

MgO(2 nm) / Co_{0.6}Fe_{0.2}B_{0.2}(d_m) / Ta(0.4 nm) / Co_{0.6}Fe_{0.2}B_{0.2}(d_m) / MgO(2 nm)

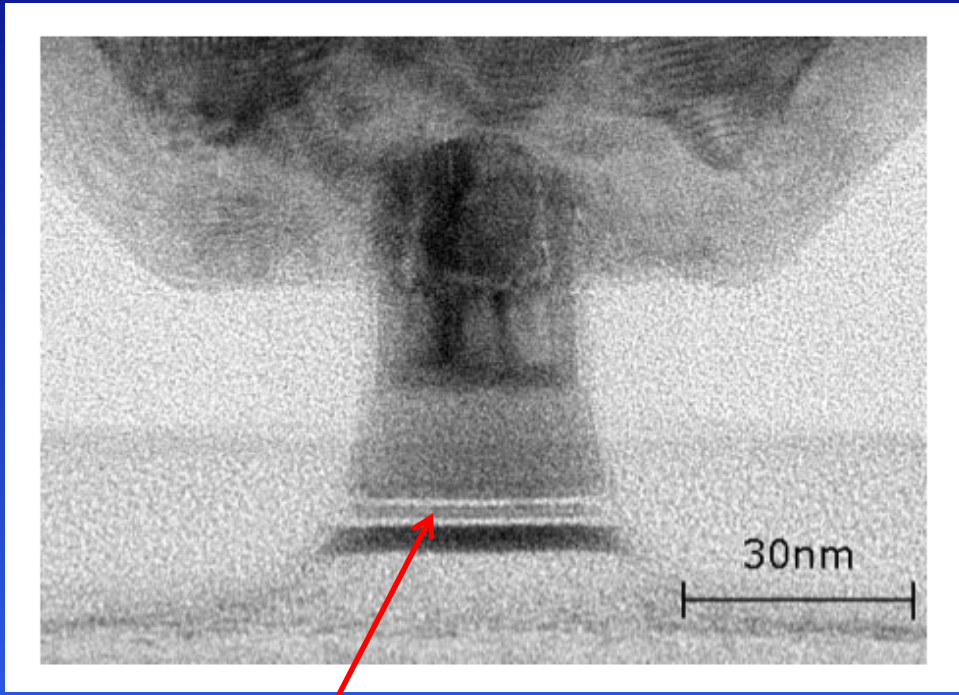


2.6x smaller than for single-layer CoFeB with the same anisotropy!

Overview

- STT-MRAM: Background and motivation
- VNA-FMR: Measuring damping and anisotropy in blanket films.
- H-MOMM: Measuring damping and anisotropy in e-beam patterned structures.

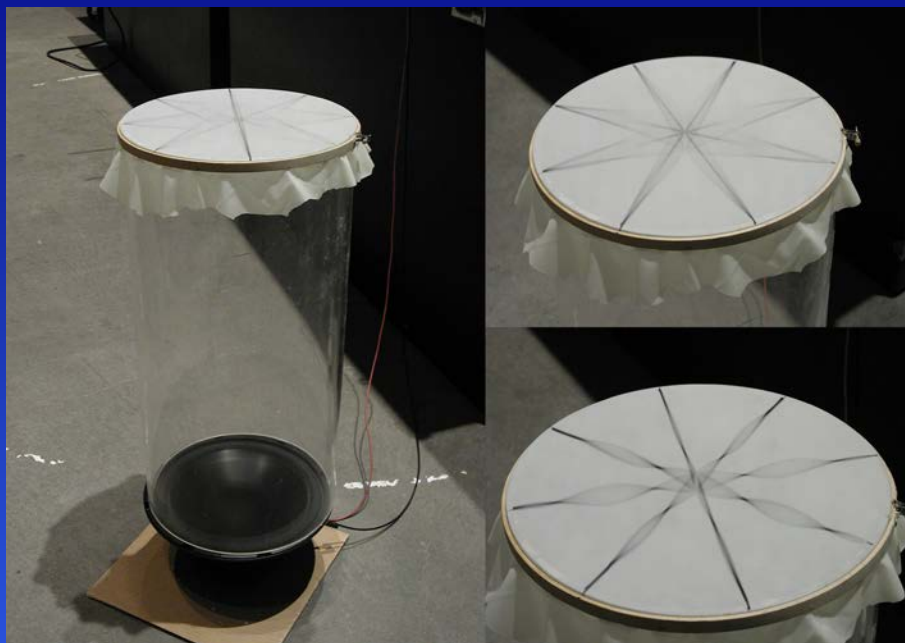
Damping and finite size effects



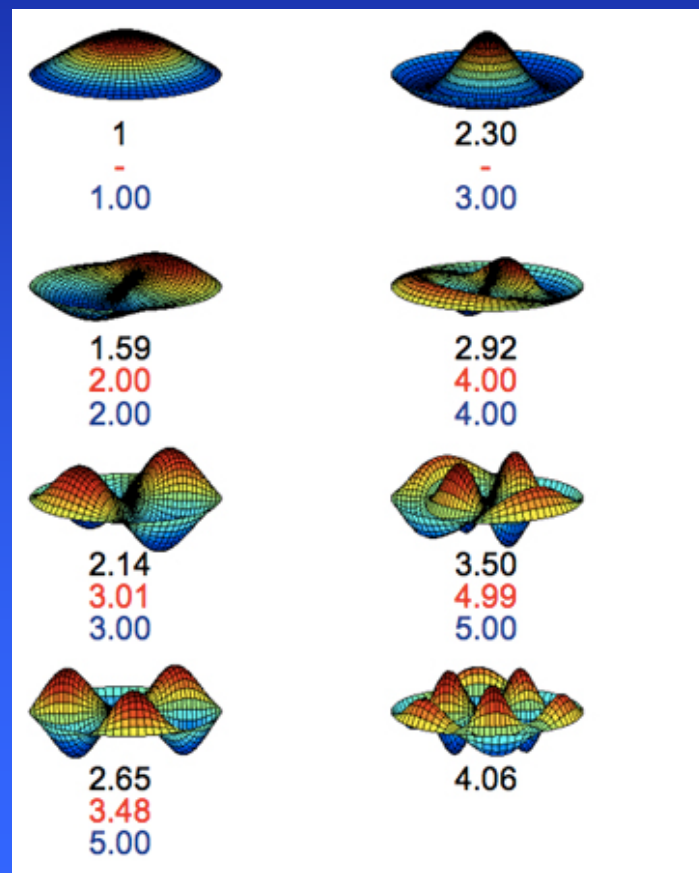
“Storage layer”

Question: Is the damping measured with an unpatterned film representative of damping in structures smaller than 30 nm?

Finite size effects: “Drum-head” eigenmodes

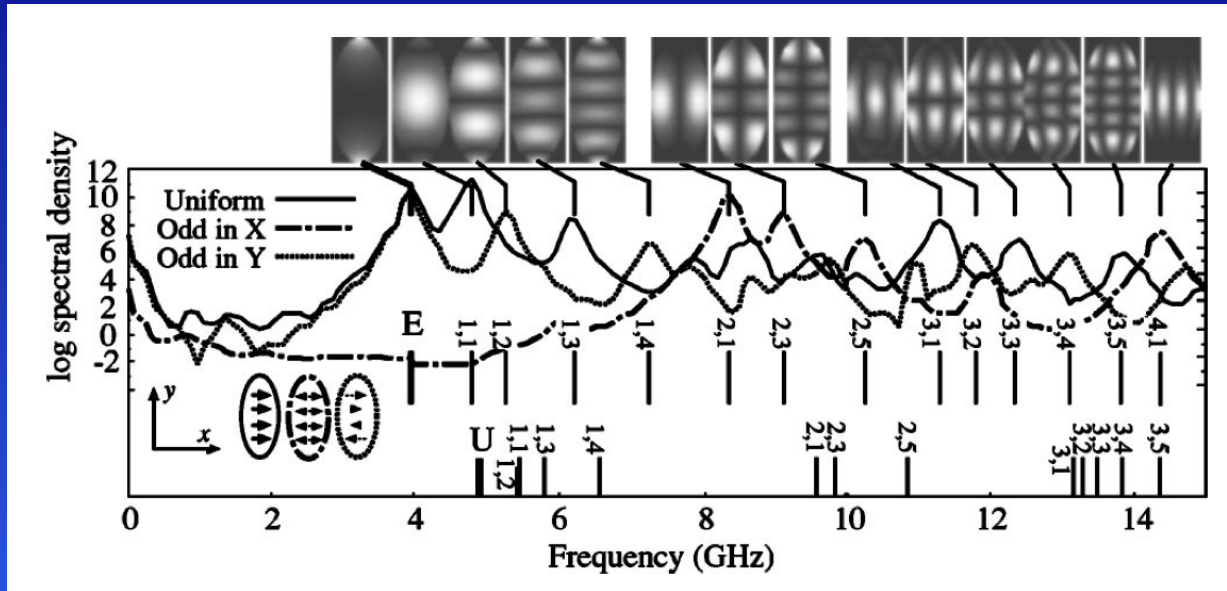


<http://www.fas.harvard.edu/~scidemos/OscillationsWaves/VibratingDrumhead/VibratingDrumhead.html>



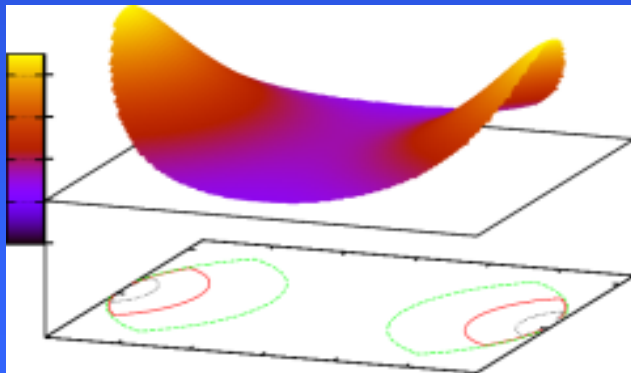
Nanomagnet eigenmodes: Micromagnetics

160 nm x 350 nm x 5 nm Permalloy in zero field:



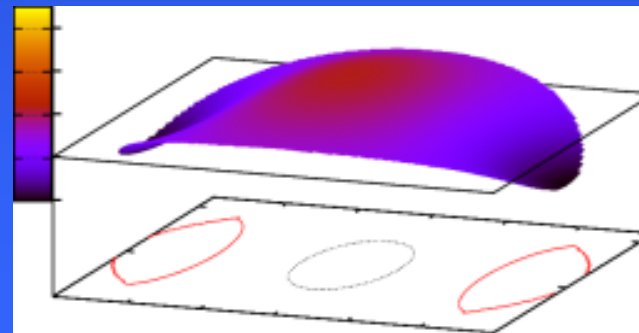
100 nm x 120 nm x 10 nm Permalloy in zero field:

McMichael and Stiles, JAP 2005



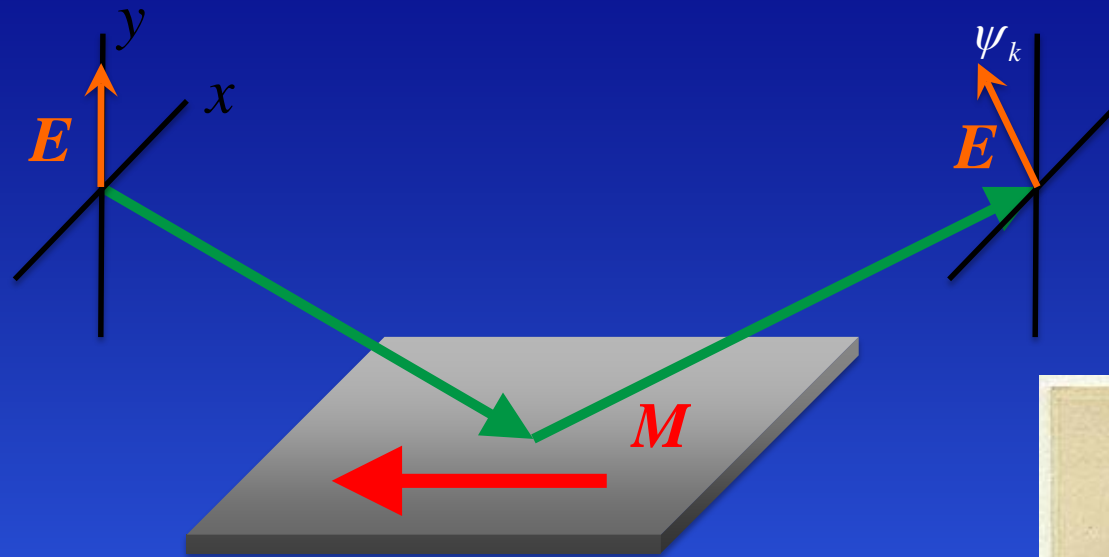
“End modes”

“Center modes”



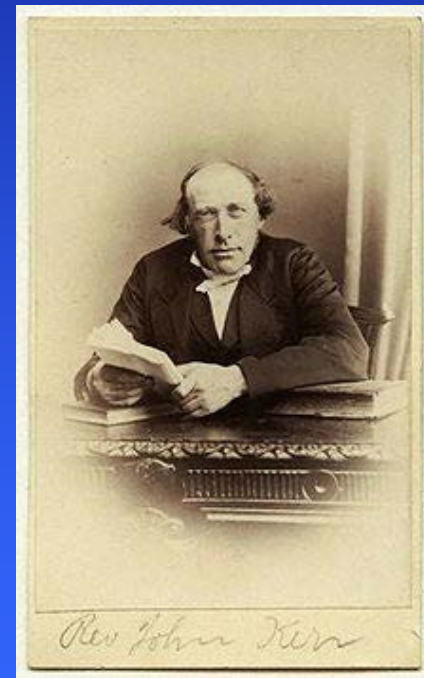
J. Shaw, et al. PRB 2009

Advantage: MOKE



“Magneto-optic Kerr effect” (MOKE)

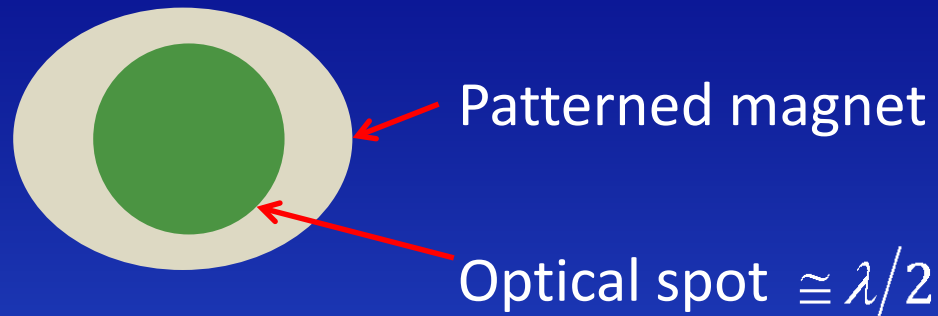
- Non-invasive.
- Local probe. (Diffraction limited ~ 500 nm).
- Vector sensitive.
- **Broadband/high speed compatible.**



John Kerr (1824-1907)

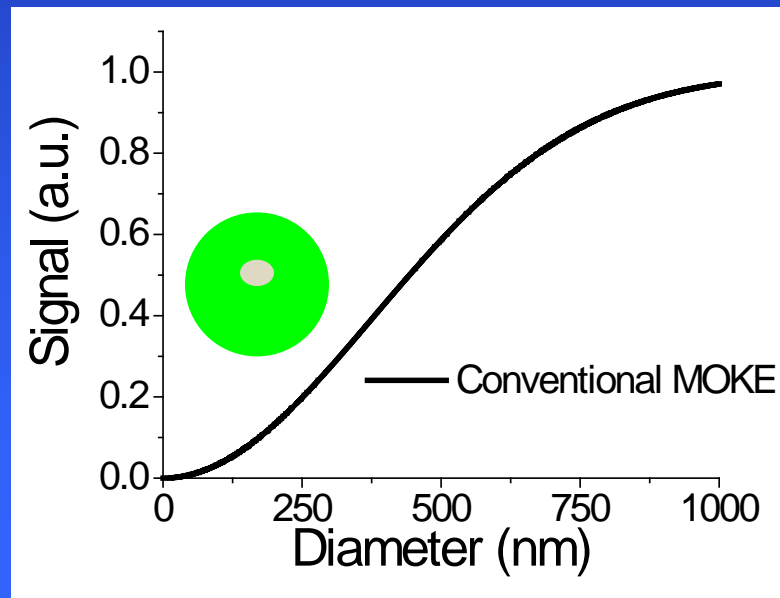
Michael Faraday (1791 –1867)

Challenge of measuring small magnets



Increased “resolution”, but at the expense of sensitivity...

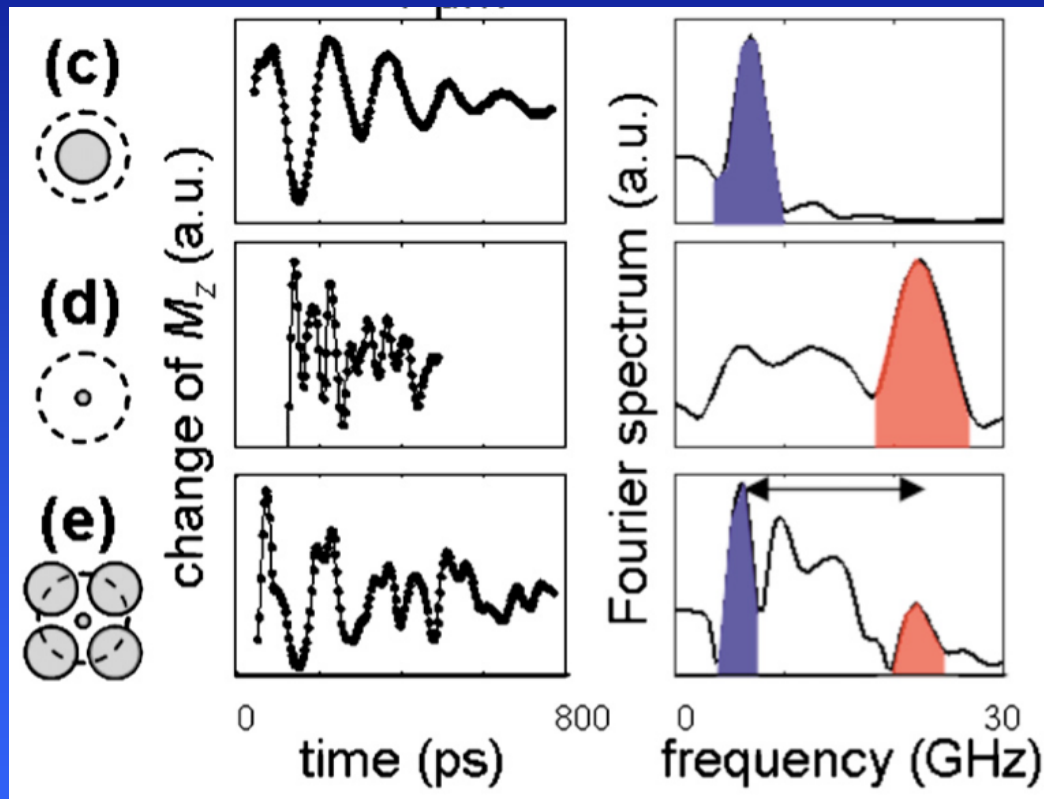
If sensitivity gap can be overcome, an example of “device-defined resolution”



Prior art: fs pump-probe

Holger Schmidt, UC Santa Cruz

(Time-resolved MOKE)



Ni nanomagnet
500 nm diameter

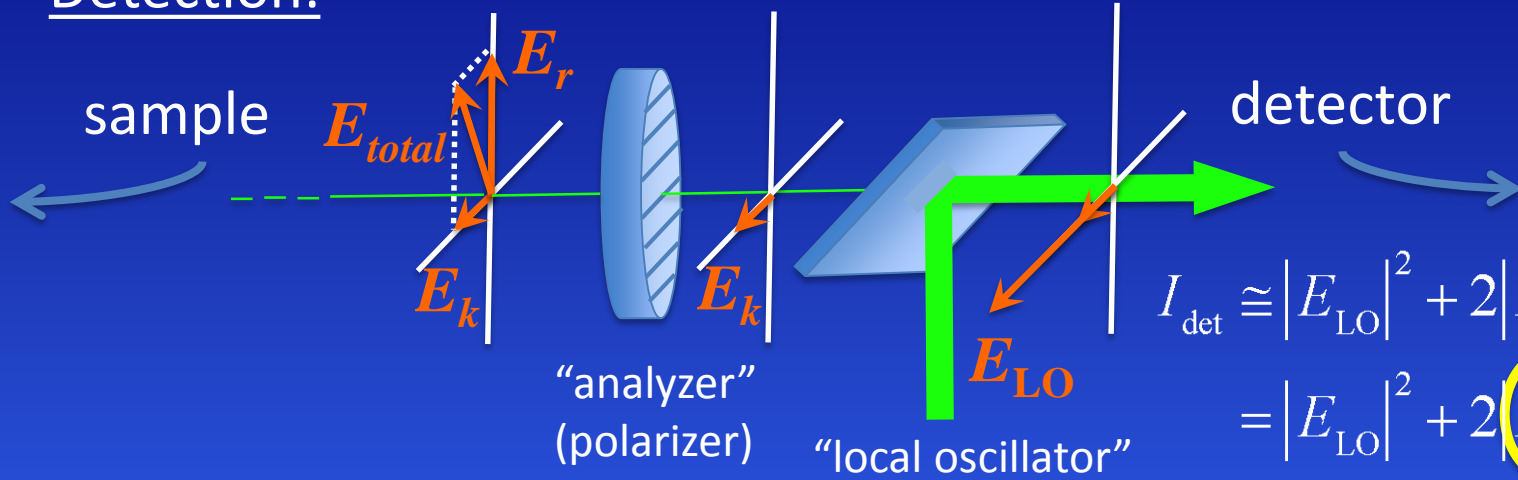
Ni nanomagnet
150 nm diameter

Z. Liu, et al., APL 98, 052502 (2011)

H-MOMM technique summary

$$\theta_k \cong E_k / E_r = \text{“MOKE angle”} \propto M$$

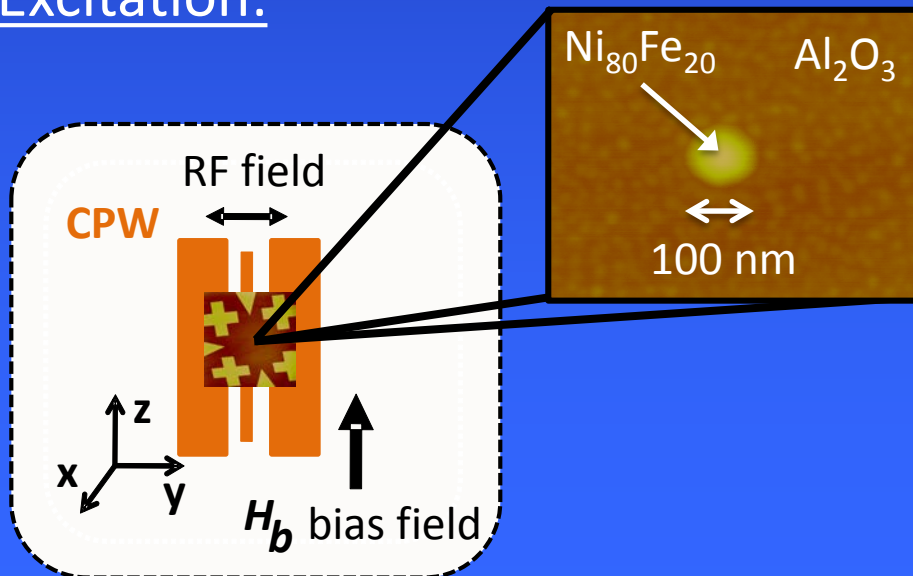
Detection:



$$I_{det} \cong |E_{LO}|^2 + 2|E_{LO}||E_k|\cos\phi$$

$$= |E_{LO}|^2 + 2|E_{LO}||E_r|\cos\phi \cdot \theta_k$$

Excitation:



H-MOMM Advantage: SNR

Signal-to-noise estimate (ONLY shot noise and detector noise.)

$$\text{SNR}_{\text{MOKE}} = \frac{\theta_k \sqrt{P_{\text{scat}}} \sin(\theta_m)}{\sqrt{1 + \left(\frac{P_{\text{det}}}{P_{\text{scat}}}\right) \frac{1}{\cos^2(\theta_m)}}} \sqrt{\frac{\Delta t \text{QE}}{\hbar \omega}}$$

θ_k = MOKE angle

P_{scat} = optical power of backscattered light

$P_{\text{det}} \doteq (\text{NEP})^2 / (\hbar \omega)$ = equivalent optical power for (shot noise) = (detector noise)

Δt = integration time

QE = quantum efficiency of detector

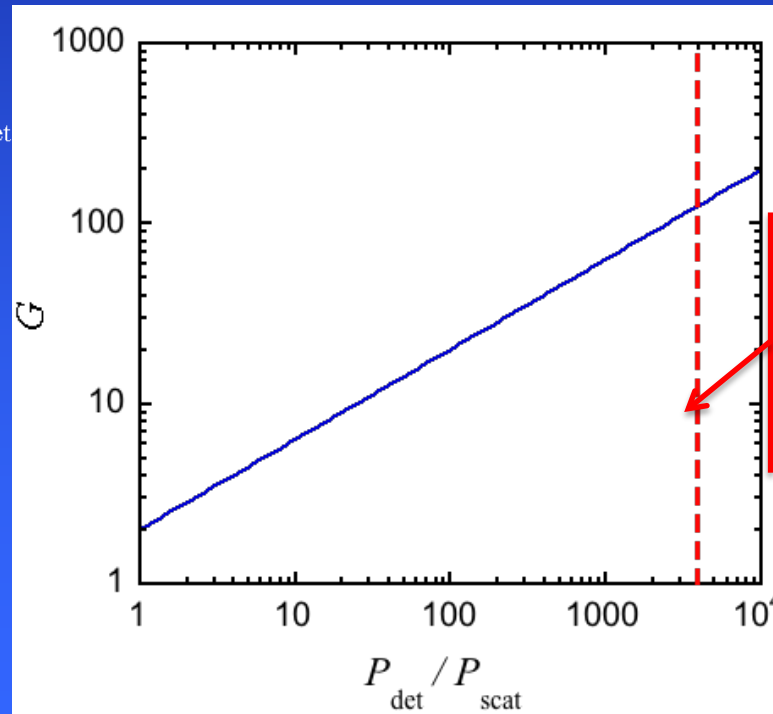
θ_m = optimum analyzer angle for max. SNR

$$\text{SNR}_{\text{H-MOMM}} \cong \theta_k \sqrt{P_{\text{scat}}} \sqrt{\frac{\Delta t \text{QE}}{hf}}; P_{\text{LO}} \square P_{\text{det}}$$

$$G \doteq \frac{\text{SNR}_{\text{H-MOMM}}}{\text{SNR}_{\text{MOKE}}}$$

$$= \frac{\sqrt{1 + \left(\frac{P_{\text{det}}}{P_{\text{scat}}}\right) \frac{1}{\cos^2(\theta_m)}}}{\sin(\theta_m)}$$

$$\cong 2 \sqrt{\frac{P_{\text{det}}}{P_{\text{scat}}}} \quad \text{if} \quad \left(\frac{P_{\text{det}}}{P_{\text{scat}}}\right) \gg 1$$



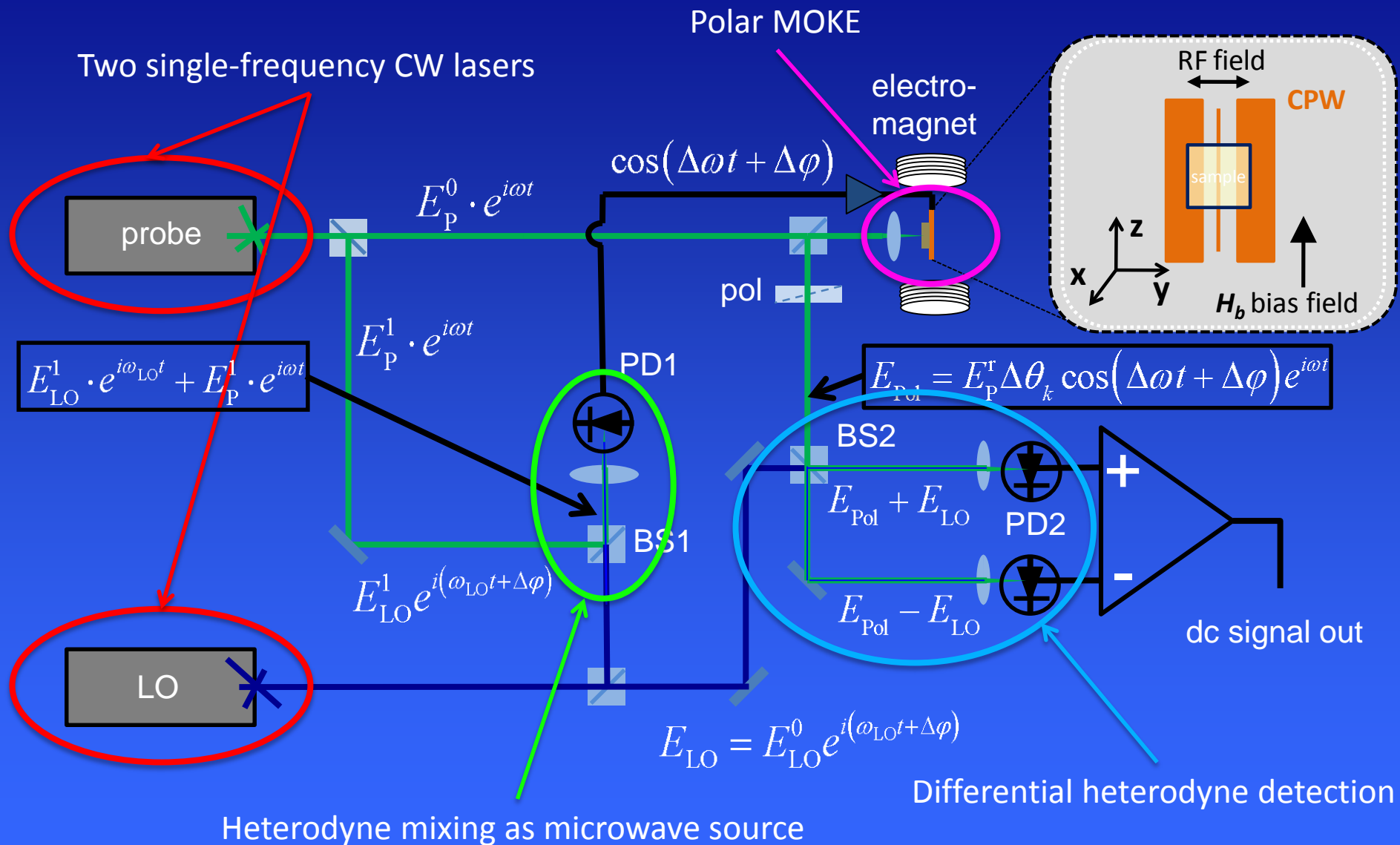
$P_{\text{scat}} \cong 4.5 \mu\text{W}$

$\lambda = 532 \text{ nm}$

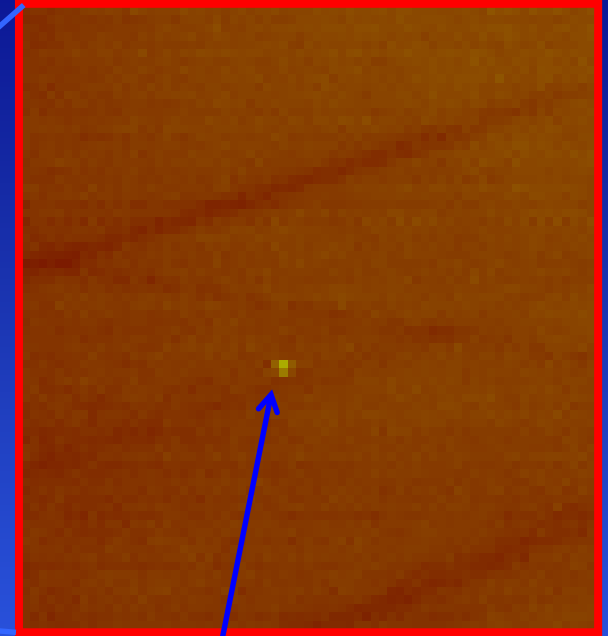
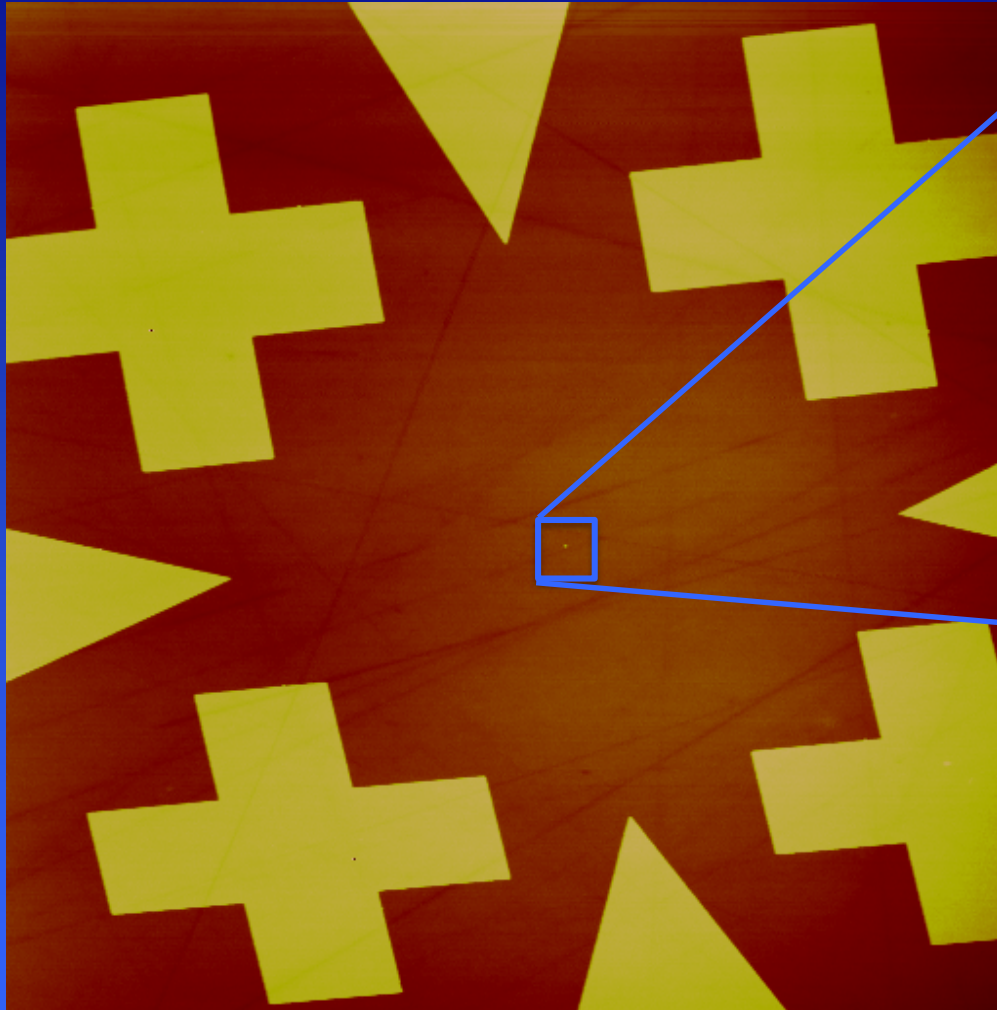
$\text{NEP} = 80 \text{ pW}/\sqrt{\text{Hz}}$

$P_{\text{det}} \cong 17 \text{ mW}$

H-MOMM diagram



original Experiment background



Single nanomagnets

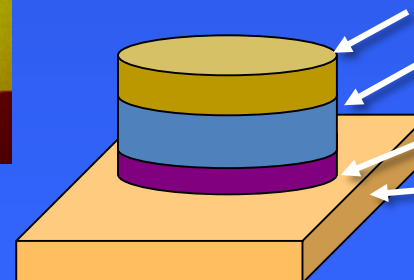
Nominal sizes: 50, 100, 200, 400 nm

4 nm Si_3N_4

10 nm $\text{Ni}_{80}\text{Fe}_{20}$

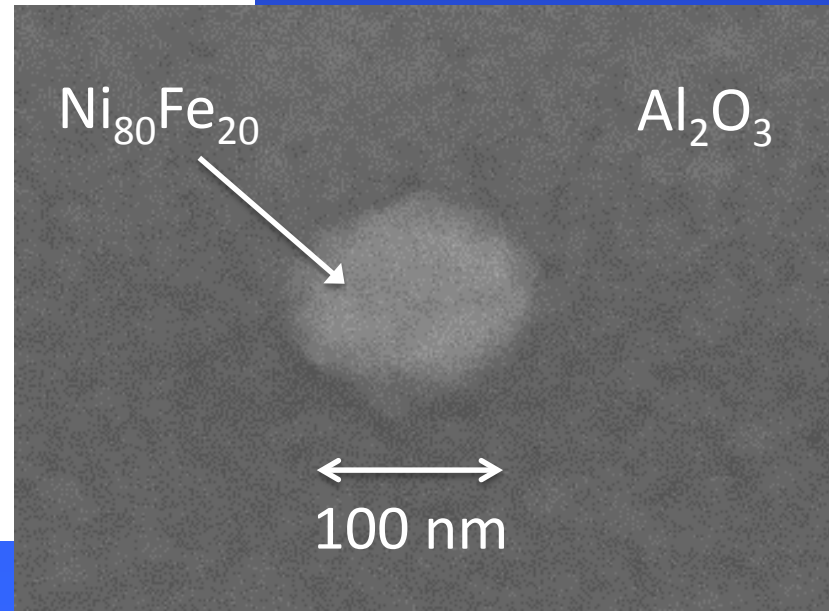
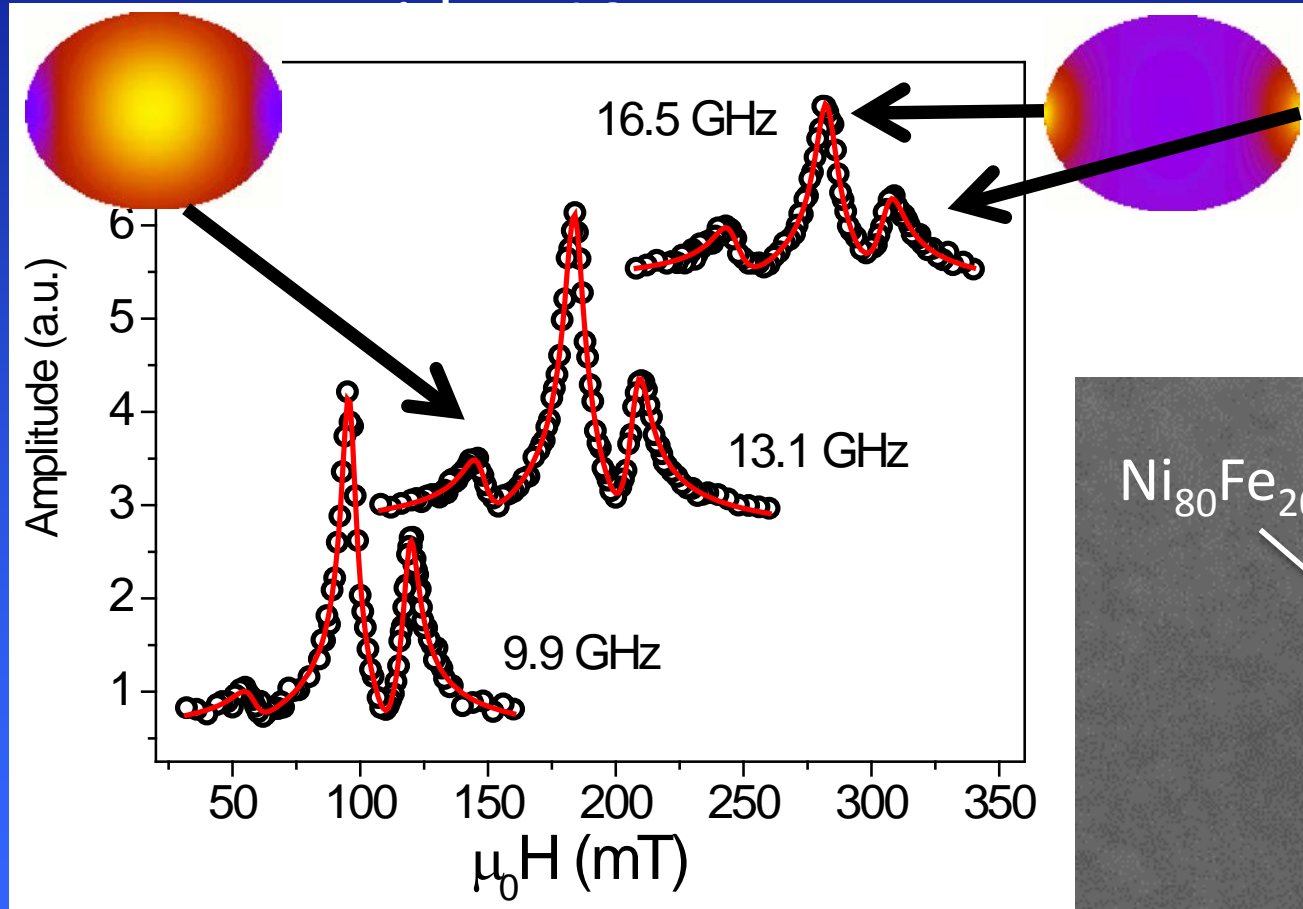
3 nm Ta

Sapphire



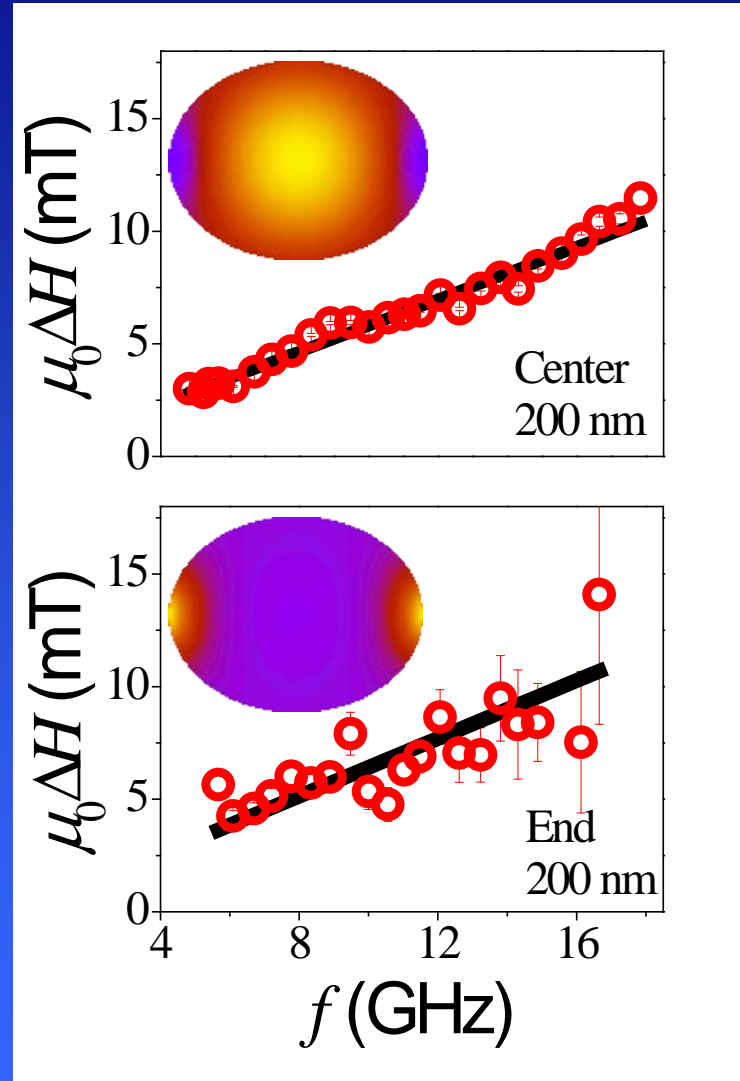
H-MOMM measured spectra

Spectra of a 100 nm Permalloy ($\text{Ni}_{80}\text{Fe}_{20}$)
nanomagnet



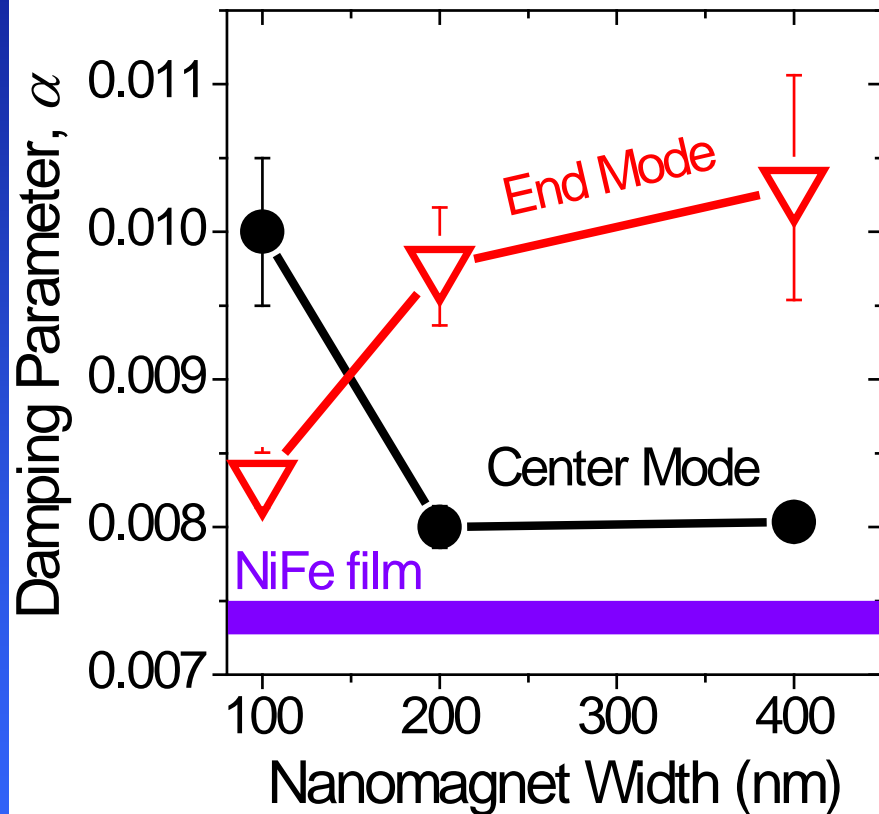
Damping examples

$$\Delta H \equiv \frac{4\pi\alpha f}{\gamma\mu_0}$$



Damping vs. size/mode

H-MOMM Data



Damping has nontrivial dependence on both nanomagnet size AND eigenmode profile.

Nonlocal damping theory

Phenomenological damping in metals (Bar'yakhtar JETP 1984)

$$\frac{d\vec{M}}{dt} = -|\gamma|\mu_0(\vec{M} \times \vec{H}) - \frac{\alpha}{M_s} \left[\vec{M} \times \frac{d\vec{M}}{dt} \right] - \frac{\eta}{M_s} \left[\vec{M} \times \frac{d}{dt} \nabla^2 \vec{M} \right]$$

↑ Exchange-mediated damping

Mode curvature affects damping! Larger curvature = larger damping

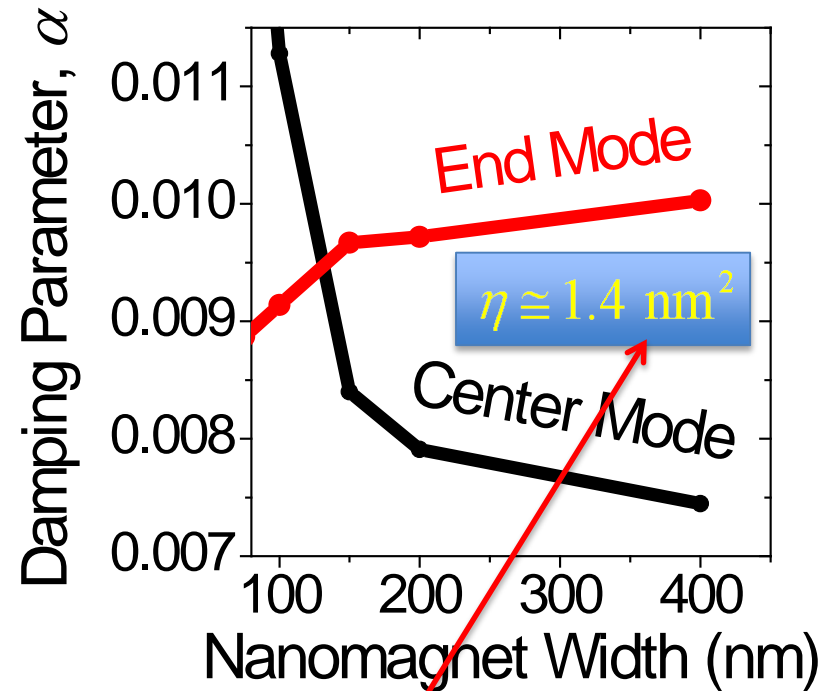
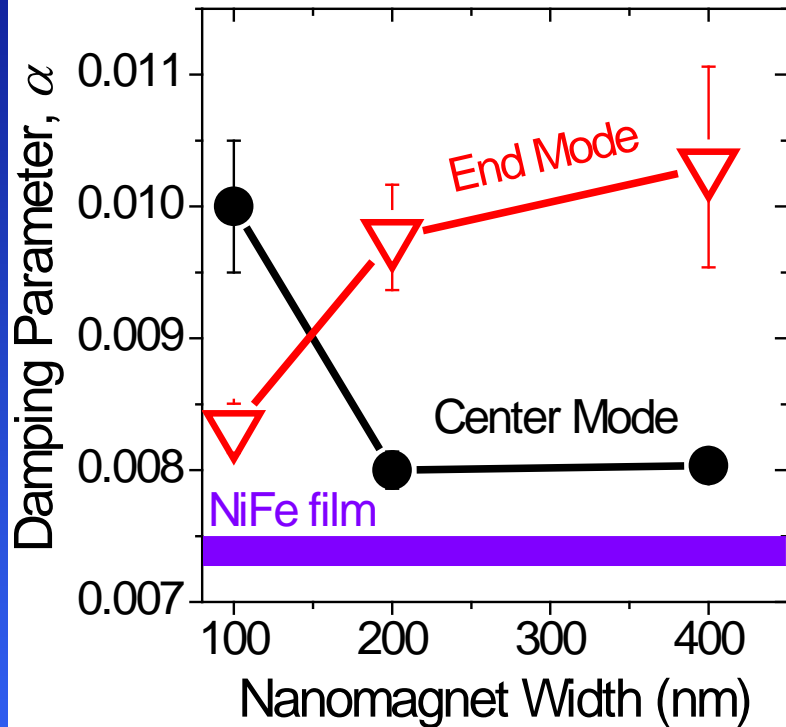
Transverse intralayer spin diffusion theory (Tserkovnyak, Hankiewicz, Vignale PRB 2009):

$$\eta = \left(\frac{\gamma}{M_s} \right) \left(\frac{\hbar}{2e} \right)^2 \sigma_{\perp} \quad \sigma_{\perp} = \text{transverse spin conductivity} = \frac{ne^2 \tau_{\perp}}{m^*} \left[\frac{1}{1 + (\tau_{\perp} \omega_{\text{ex}})^2} \right]$$

$$\cong 10^{-3} \text{ nm}^2$$

Damping vs. size/mode

Simulation w/ nonlocal damping



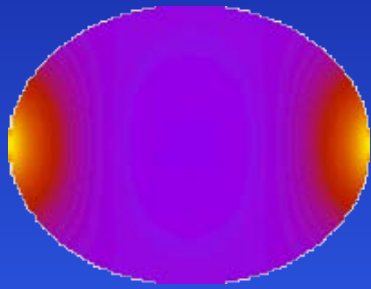
Tserkovnyak, et al.: $\eta \approx 10 \times 10^{-3} \text{ nm}^2$

~ 100x too small to explain our data!

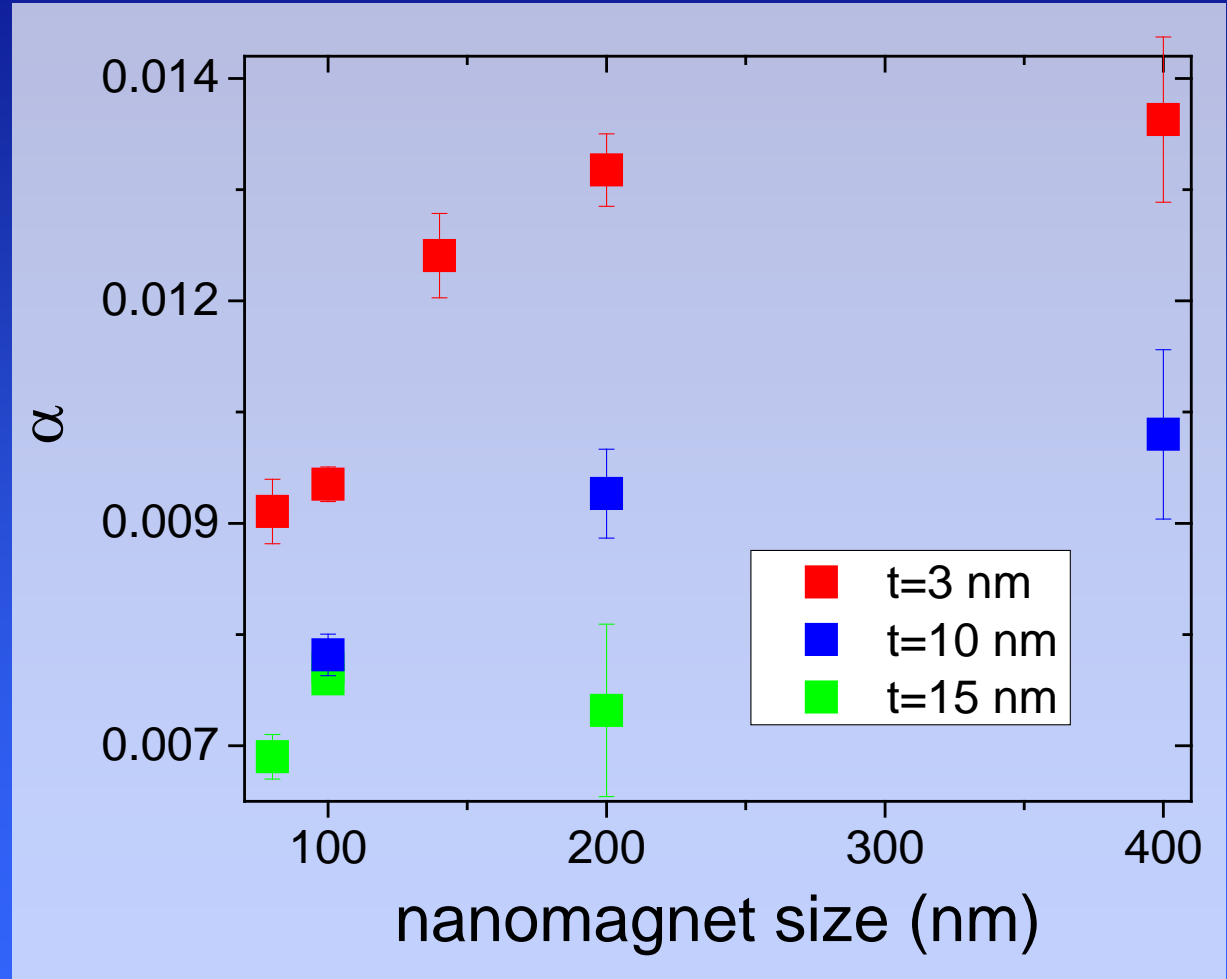
Nembach, Shaw, Boone, & Silva PRL 2013

New H-MOMM data

Damping for end-modes vs. size *and* film thickness



End-Mode



(H. Nembach, et al., in preparation)

Summary

- STT-MRAM: An promising memory for low-power applications.
- Need to characterize damping and stability in advanced materials.
- Blanket thin films: VNA-FMR.
 - Ex: Low damping in engineered sandwich memory layers.
- Patterned structures: H-MOMM.
 - Ex: Curvature-dependent “non-local” damping with eigenmodes.

T. J. Silva, et al., “Characterization of Magnetic Nanostructures for Spin-Torque Memory Applications with Macro- and Micro-Scale Ferromagnetic Resonance,” in Characterization and Metrology for Nanoelectronics, eds. Zhiyong Ma and David Seiler, (to be published by the end of this year by Pan Stanford Publishing.)